

Physics Meets Animation Character Stunts in Just Cause 2

John Fuller – System Architect, Physics Andreas Nilsson – Lead Gameplay Programmer

Talk Overview



Motion Control

Animation + Physics +IK

Parametric Animation

Effectors / Manipulators

Just Cause 2 : Requirements



- Huge open world
- Fast-paced, over-the-top action
- Reactive environment
- High level of responsiveness
- Large number of game mechanics
- Large number of vehicles



Freedom!

Concept Video



videomatic_060918_01_xvid.av

Approach



- Small animation budget
- Large feature set
- Small animation staff budget

_____ = Tiny

Large

Procedural animation?



Motion Control



- Started with badly structured character control system
- Slow and cumbersome to create behaviors
- First : decoupled root motion from posture update
- Refactored functional elements into 'Motion States'

Fast-paced

Motion Transitions

Motion States - Root Node Update



- Desired motion:
 - Procedurally driven motion
 - Animation driven motion
 - Attached motion
- External influences:
 - Collision response
 - Gravity



Attached Motion



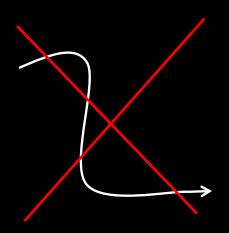
- Attached characters live in parent's local space
- Character movement changes relation between parent and child
- Animated root node translation and rotation affects offset

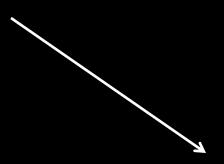


Scaling for fixup / alignment



- Scale motion to realign for specific targets
- Introduces two constraints on the assets
 - Low curvature within the translation
 - No translation during contact with parent
- Animator has control over timing and acceleration

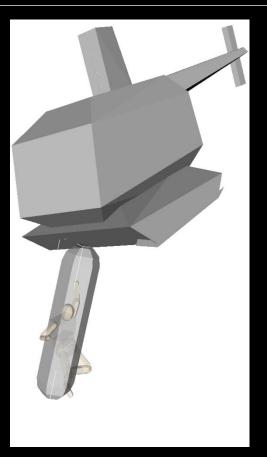




Rigid Body Proxy



- Physical effects applied in a controllable way
- Applying impulses to a ragdoll : less controllable
- Single rigid body represents entire character
- Can be constrained to other objects

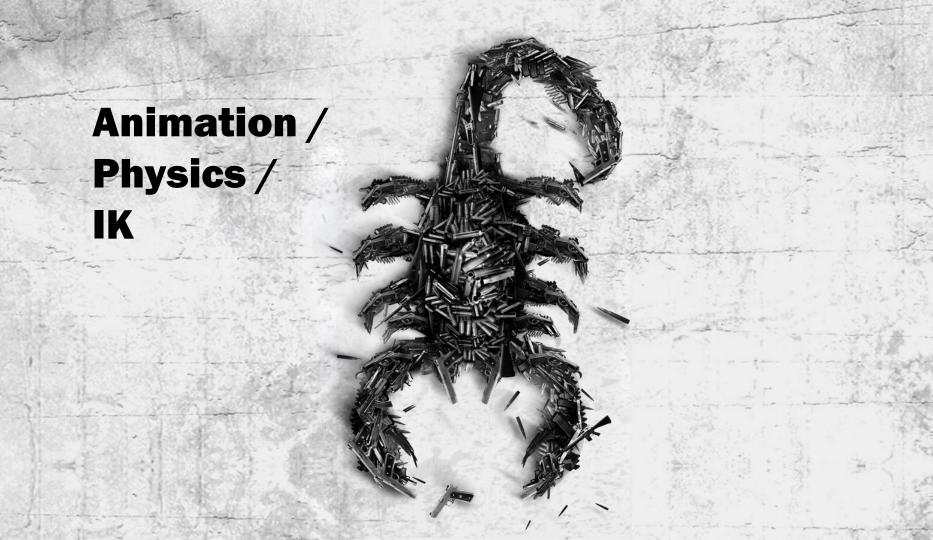


Recoil

Custom Transition States



- Some transitions needed special care
- Transition states bridge between motion states with different velocities
- Applies custom velocities and impulses
- Crucial to fluid gameplay
- These are context dependent



Pre-visualization





Ragdoll / Animation / IK Blending



Systems influencing pose:

- Ragdoll
- Cling animations
- Hand and foot IK
- Aim Constraints



Control Flow



Sample Animation Pose

Foot / Hand IK attachment

Update ragdoll

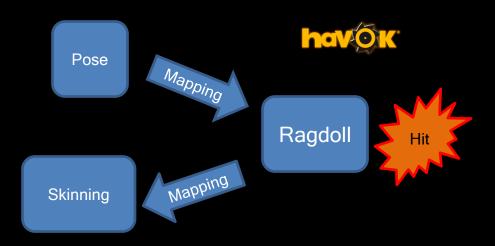
Physics Update

Aim constraints

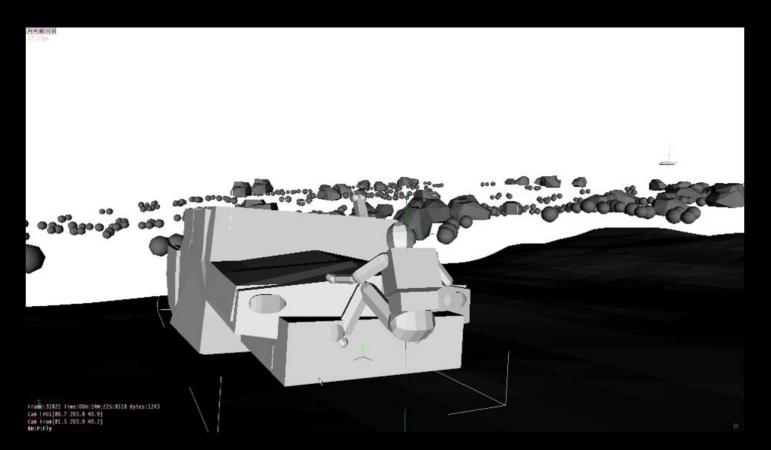
Skinning

Pose Driving





- Drive ragdoll towards animation pose (using impulses / joint motors)
- •Not a keyframed ragdoll can still respond to collisions



Transition from Ragdoll to Animated



 Below a certain velocity, transition to Pose Matching state

2. Compare orientation with a number of Get-Up start frames

3. Drive ragdoll towards the closest start frame

4. When close to target pose, start the animation and blend to it



Spinning Ragdolls



Needed Over-the-top, extreme reactions to explosions

- 1. Applied impulses to torso and hips
 - -> Very ragdolly ©
 - -> Occasional instability (stretching)

- 2. Evenly spread impulses on all bones
 - -> Lots of translation, not much spin
 - -> Synchronized swimmers (in-sync flailing animation)
 - -> Reminiscent of sprites!

Spinning Ragdolls



3. Vector field

- -> Get an axis perpendicular to explosion
- -> Evenly spread impulses to achieve rotation
- -> Still have synchronized swimmers

4. Randomness

-> Vary the axis within a 45 degree cone

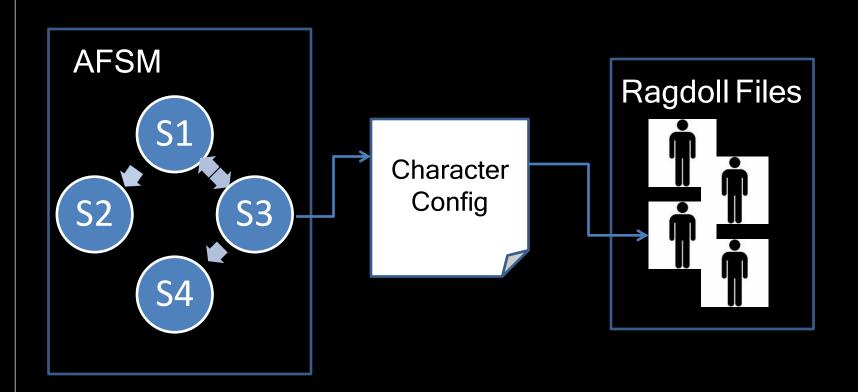
Note: Also drive towards flail animation





Authoring Ragdoll / Character setup





Authoring Ragdoll / Character setup



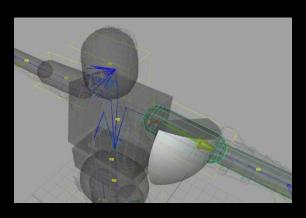
```
<object name="Setting HangOnVehicle">
   <value name="name" type="string">HangOnVehicle</value>
   <value name="ragdoll file id" type="string">ragdoll file 1</value>
   <object name="parameters">
       <value name="controller_type" type="string">RIGID BODY</value>
       <value name="map anim to physics" type="int">1</value>
        <value name="map physics to anim" type="int">1</value>
        <value name="blend speed" type="float">2</value>
       <value name="blend weight" type="float">0</value>
       <value name="tau" type="float">0.95</value>
       <value name="damping" type="float">0.45</value>
        <value name="proportional recovery velocity" type="float">10.0</value>
        <value name="constant recovery velocity" type="float">4.0</value>
        <value name="max force" type="float">10000.0</value>
        <value name="hierarchy gain" type="float">0.01</value>
       <value name="velocity damping" type="float">0.0</value>
        <value name="acceleration gain" type="float">0.35</value>
        <value name="velocity gain" type="float">0.35</value>
        <value name="position gain" type="float">0.35</value>
        <value name="position max linear velocity" type="float">1000.0</value>
        <value name="position max angular velocity" type="float">1000.0</value>
        <value name="snap gain" type="float">0.25</value>
       <value name="snap max linear velocity" type="float">0.1
        <value name="snap max angular velocity" type="float">0.1</value>
       <value name="snap max linear distance" type="float">0.01
       <value name="snap max angular distance" type="float">0.01</value>
   </object>
    <object name="keyframed parts">
        <value name="part 1" type="string">ragdoll LeftHand</value>
       <value name="part 3" type="string">ragdoll LeftFoot</value>
       <value name="part 4" type="string">ragdoll RightFoot</value>
   </object>
</object>
```

Authoring Ragdoll / Character setup

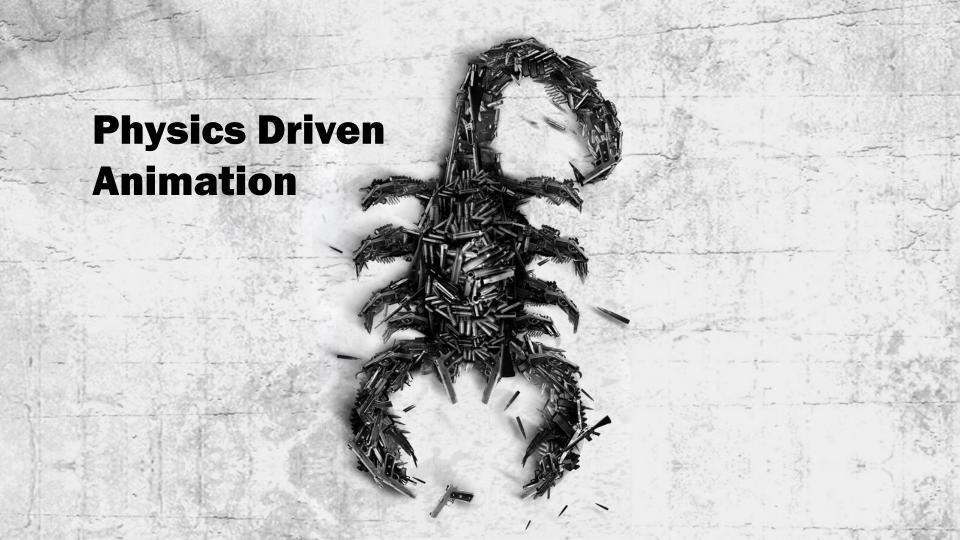


Anecdote:

- Rico freefall colliding state had artifacts
- Technical Animator diagnosed problem:
 - conflicting animation and constraints
- Tweaked ragdoll constraint limits
- Created a new Character Configuration
- Changed 'Falling' state to point to this character configuration
- Rico's death sequence reworked in one morning, no coders involved







Ragdolls and parent motion



Ragdoll pros

- Feeling of presence
- Collision handling

Ragdoll cons

- Feeling of intention and awareness
- Poor momentum transfer



Traditional Link Between Animation and Physics



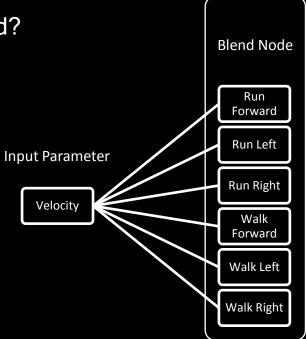
- Physics Event -> Animation Transition
- Results in:
 - Series of discrete animation states and transitions
 - Recognizable state machine style
 - Repetitive timing and movement patterns
- Artifacts typically combated with:
 - Shorter animations, more transitions, more complex trees?

But ... neither physics nor character behavior is discrete!!!

Parametric Animations



- Commonly used for navigation on ground?
- Smooth dynamic motion



Physics Driven Animation



- Parameterize blend nodes with parent's motion
- Feed in continuous values to act as inputs to single states
- Result? Non-repetitive, smooth motion





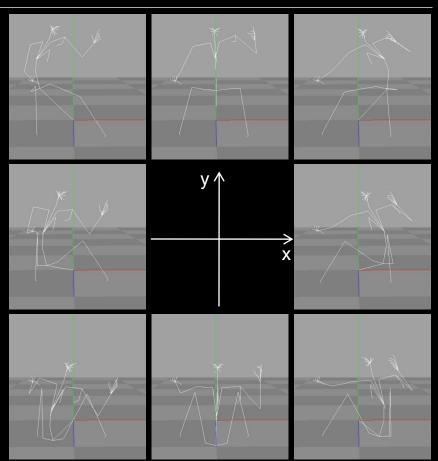
Ragdoll Only

How does it work?



- All poses are baked into two animations
 - Upper row from left to right
 - Lower row from left to right

- Middle row is the result of blending
- Project parent's angular velocity onto...
 - X-axis to determine blend weight
 - Y-axis to determine sample time

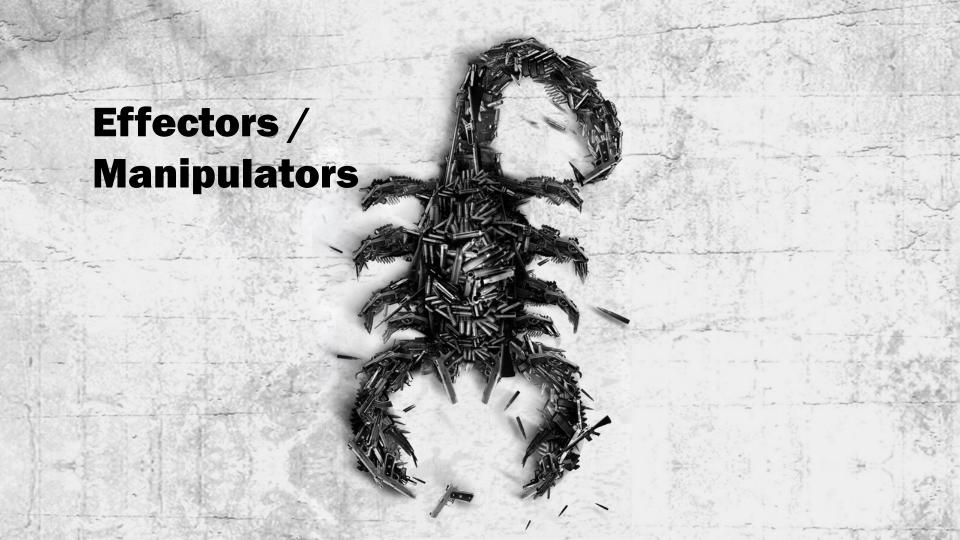


...One Step Further



- Multiple parameterizations create variation
- Parachuting has the following inputs:
 - Acceleration, velocity and gamepad input
- Riding motorcycle has the following inputs:
 - Suspension length rate of change
 - Speed
 - Orientation
 - Gamepad input

Physics Driven Animation



Animation Driven Impulses



Wanted data driven physical effectors

Animations contain annotations, e.g.

DOWNWARD-IMPULSE-LIGHT

DOWNWARD-IMPULSE-HEAVY

Impulses applied to parent or target body

• E.g. foot down event, enter vehicle, some cling positions

Motorbike Tilt



Let the player feel in control of the driver

Forward-back controls player lean ... C.O.M. shift

Re-align constraint limits on front and back

Makes it easier to tip backwards

• Also allows for leaning forwards / backwards in air

The Almighty Grapple



Physical constraint

Can 'tie' nearly any two physics objects together

• Custom impulses applied: e.g. yanking, wall tether, dual tether two enemies, etc.

Shorten the constraint to draw things together

Animation Driven Impulses

Findings

Problems we faced / Tips



Ragdoll Stability:

• Requires constant maintenance

- Animation poses must not violate constraint limits
 - Use different ragdolls to suit the context

QA unfamiliar with problem domain

• Monitor edge cases : have a fallback

Problems we faced / Tips



Ragdoll Driving:

- Varied quality at different speeds
- Tried varying driving params with speed, ran out of time

Motion:

Transitions between Motion States took a lot of work

Problems we faced / Tips



Blending:

- Noisy physics signal filter
- Blending away from a parametric blend node can be difficult

Dependencies:

Difficult to tweak without side effects

Important decisions we made



We separated motion state from pose generation

- Many states had different control flow for IK / Animation / Physics.
 - •We were able to vary this control flow for each state.
 - •Not quite a dynamic 'shader pipeline', but flexible

Exposed elements of the character configuration to content creators

Advantages of using Physics



• Cheap variation - few added animations

Rich context data to drive animation blending

Collision response enriches feeling of interaction and presence

• Fun emergent gameplay, e.g. grapple

Disadvantages of using Physics



Requires constant maintenance and tuning

Hard to preview final visual outcome

• Requires expertise across the organization, e.g. game designers, animators, QA

Thanks!



Just Cause 2 Team

Avalanche Studios

Eidos

Square Enix

Havok

