

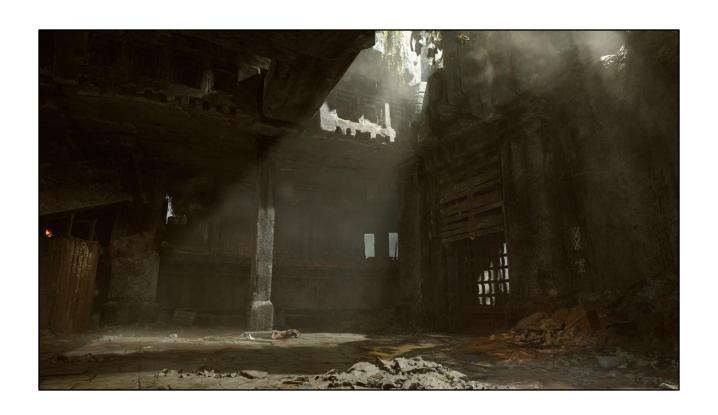
The Indirect Lighting Pipeline of God of War

Josh Hobson

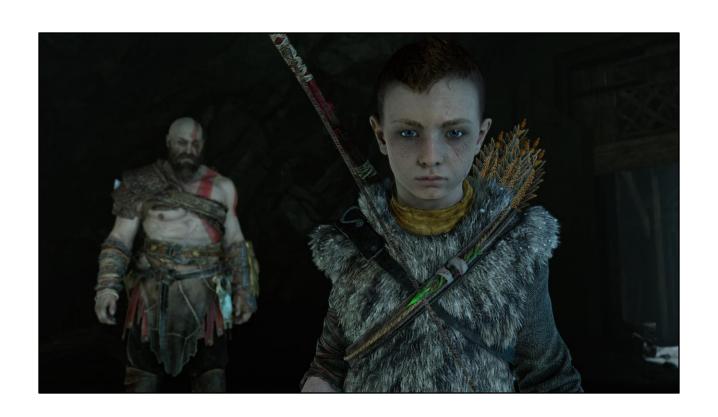
1st Party studio, part of Sony Playstation Responsible for the God of War series







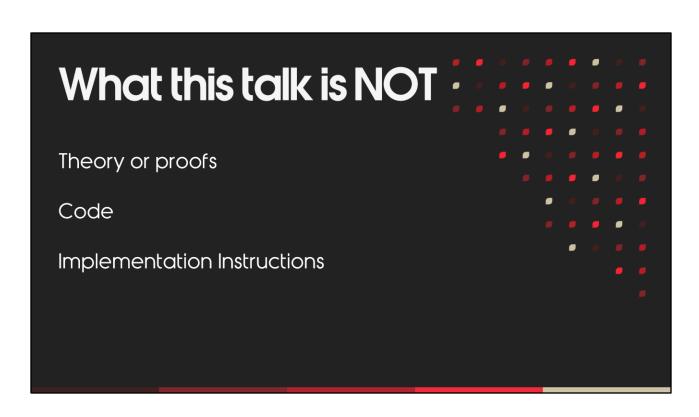








This talk will cover high-level end-to-end pipeline with a focus on concepts, motivations, situations, and some technical depth Where possible I will integrate dates and behind the scenes info



It's not intended to be implementation instructions or proofs. While we do bring some new ideas to the table, this is largely built on existing work

Pipeline Overview

Wads

Streamable unit, lifetime of objects, heap

Defined by reference hierarchy of Maya files

Refnodes

Level assembly workflow

Prefabs

Maya file pointer or #include

First let's go over some terminology.

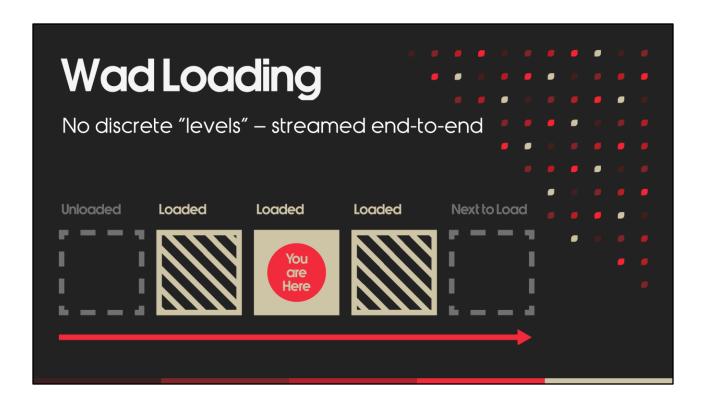
All level editing is done in maya there is no level editor

Wad - Streamable unit

- scene heirarchy
- Composed of a series of overlaid maya files
- heap/object lifetime (this is important for reliability/repeatability since there's never a full teardown)

Wads contain "Refnodes" serve as general purpose links for

- Prefab workflow object instances
- Level editing workflow layering (art/design, subdivision, vis, lights, entities)
- These can be recursive



Hallmark of the series - no loading screens

- Playable end to end, no discrete "levels"
- Conveyor belt loading
- What we load and when is data driven by level design and art
- Design/art responsible for breakdown of wads
- S-hallways, traversal pacing to hide/anticipate loading ahead and unloading behind

Wads can be stacked

- Kratos' house is a wad that's contained in the surrounding forest wad

Background

Indirect lightmaps and probes (until mid 2015)

- Disconnect between environments and characters
- Lightmaps per instance, bookkeeping complicated by refnodes
- Maintaining UV sets is laborious
- · Probe placement is laborious
- Layout/geo changes iteration is slow

In mid-2015, at our first playable, we had an indirect lighting pipeline that used lightmaps and loosely placed diffuse probes. It's not an uncommon solution but it comes with tradeoffs.

There's a visual disparity between dynamic and static objects that's reminiscent of old cartoons where you can tell something is about to move because it's cell-painted in the animated layer instead of the matte painted background.

Additionally there's a complex pairing of lightmaps to instances. This is further complicated due to the generic and recursive nature of our refnodes. For example you might have an object on a table, the table could be instanced several times in a house and then the house might be instanced several times. The number of instances can explode quickly. Keeping track of what is and isn't up to date is complex. UVs and probe placement is laborious. Changing mesh topology requires new UVs and rebaking. Moving lights and objects can require re-placing probes. All of this can be helped by tools but it's still time consuming and painful.

GI Volumes Motivation

Less manual overhead

Needs to work well with loading scheme

- Wads overlapping, loading, unloading
- Support lighting swaps

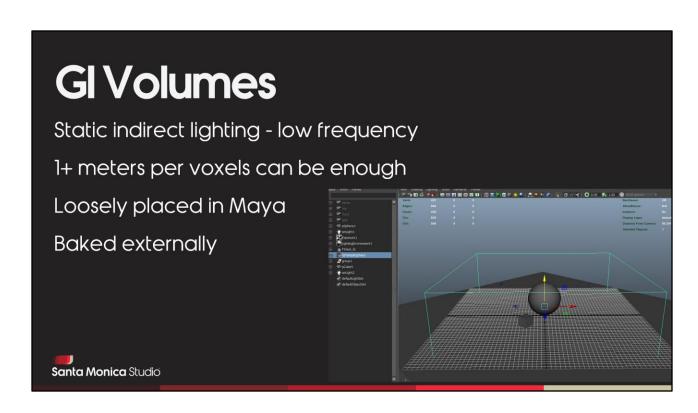
Needs consistency between characters and environment

Needs to be cheap to apply

We wanted to try something different. I'd used 3D textures for lighting in the previous console generation and it was affordable.

Consistent look for static and dynamic objects.

We have a relatively small lighting team, we want them focused on lighting not data management.



Keeping it simple, GI volumes are loosely placed boxes in Maya. Inside there's a series of 3D textures that contain lighting baked data.

Since we're only storing indirect lighting resolution does not need to be high. Even larger than meter per voxel can be enough.

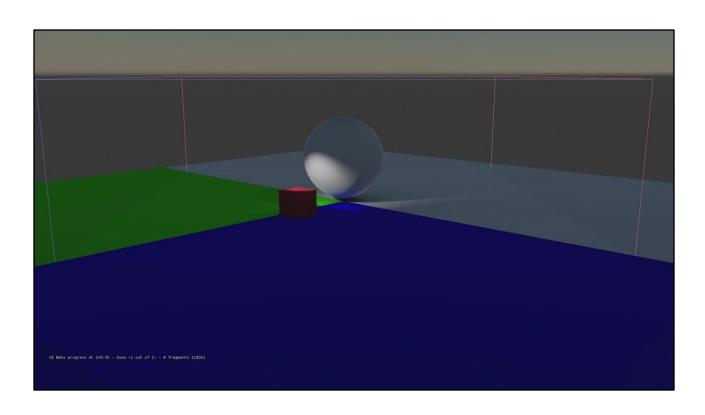
Encoding

Four 3D textures

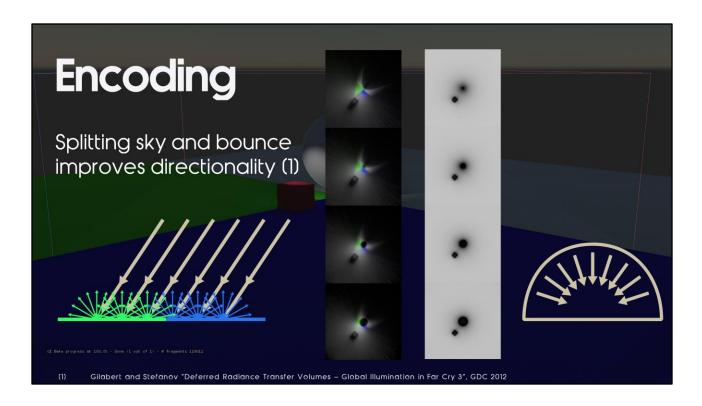
- 2 band spherical harmonics
- RGB bounce and sky visibility + monochrome bounce (1)
- Float16 (more later)

Gilabert and Stefanov "Deferred Radiance Transfer Volumes – Global Illumination in Far Cry 3", GDC 2012

4 3D SH textures RGB – bounce lighting from analytic light sources Alpha – sky vis + monochrome bounce



Test scene

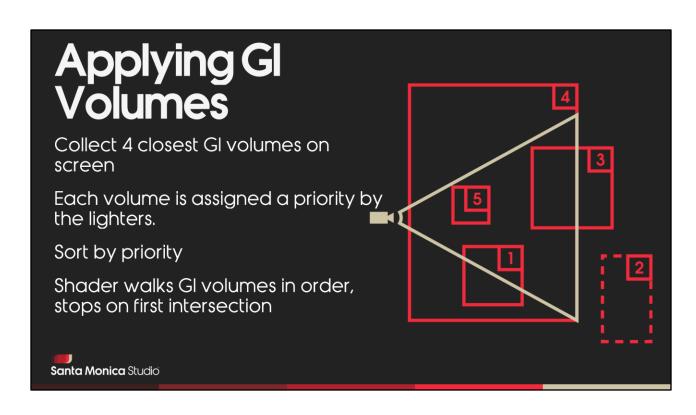


Here's an example of a few slices from the GI volume.

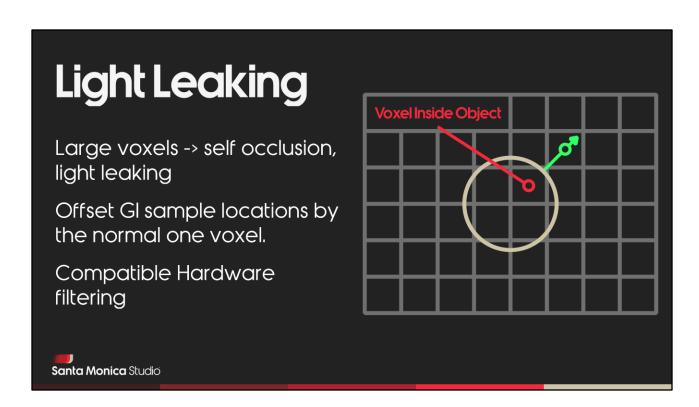
Splitting sky and bounce helps SH encoding maintain directionality. With 2-band SH opposing directions cancel each other out, leaving only the constant 0-band to represent the data. Sky comes largely from above and bounce from below.



You can think of the sky visibility term like a directional ao. The sky lighting is joined at runtime, this means we can change the sky without rebaking. We express sky lighting as a SH encoding of cubemap, generated during build. We do change sky lighting/rotate at runtime, mostly during transitions.

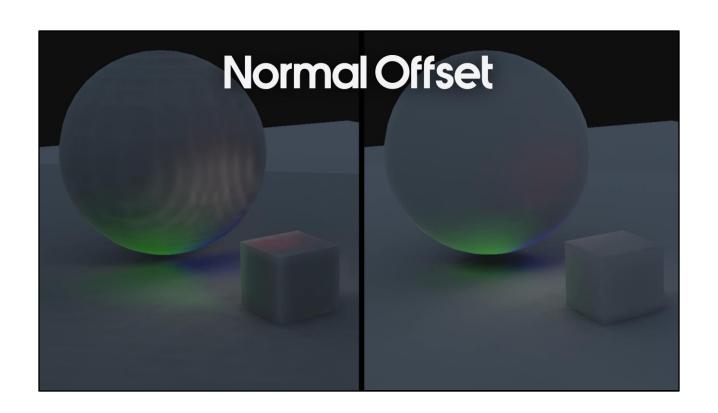


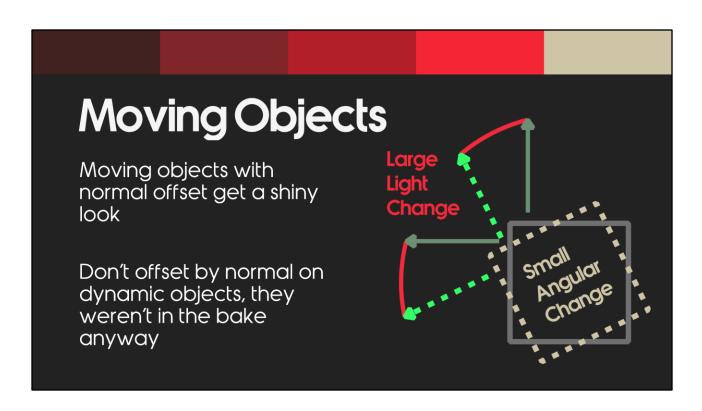
4 closest on screen
Sort by authored priority
We want this simple on the GPU. Shader walks in order, stops on first intersection
We'll talk a little about optimizations shorly.



Because the voxel density is low we get self occlusion and light leaking artifacts. This is a similar effect as shadow acne.

We're motivated to use hw filtering and avoid unrolling the 8 taps for manual filtering. To solve this we simply offset the GI sample away from the receiving surface along the normal. This effectively inflates objects when sampling the GI so they're sampling outside of themselves.



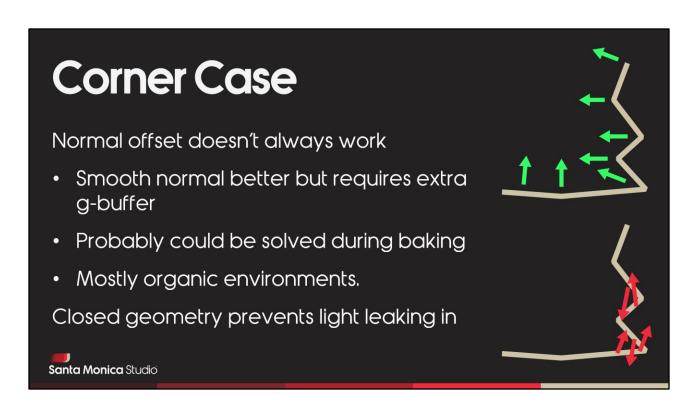


Sample offset on moving object reads like specular, looks shiny. We already had a bit in our gbuffer for characters.

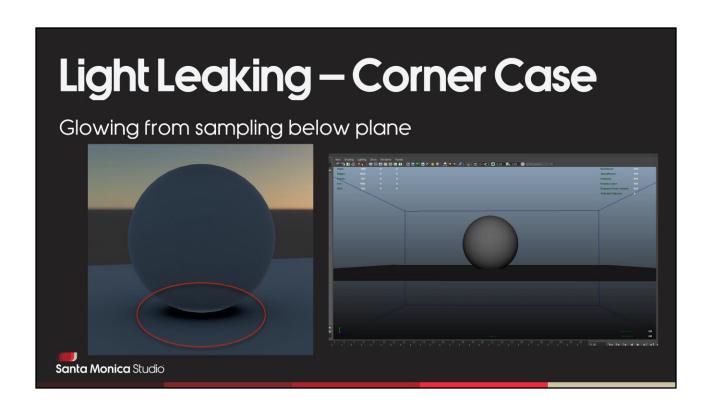
Don't apply offset for characters (they didn't participate in the bake anyway).

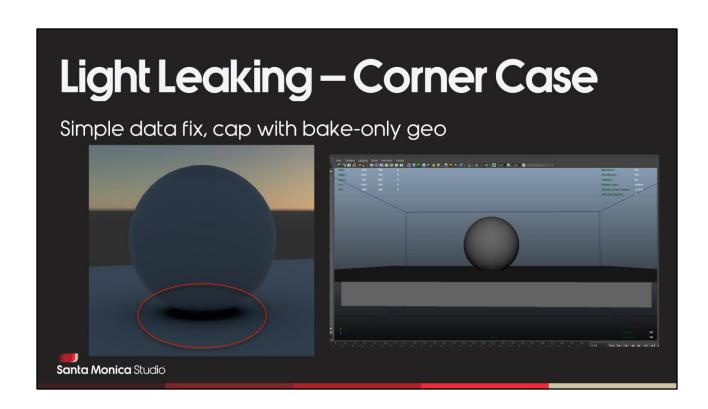


Video showing character GI looking like spec when moving because of normal offset. Real-time shader update shows problem go away on Kratos.



There's a literal corner case where close-by normals cause the normal offset to poke through walls or the floor revealing un-occluded sky.





Over occlusion more acceptable than under

Indirect Specular

Optional Screen Space Reflections

Cubemaps (gloss convolution in mip chain)

- Box parallax correction (2)
- Placed manually (including box collision)
- Utilities to find the best-fit box collision from cubemap depth buffers
- Box is not a very good for organic environments

Lagarde and Zanuttini, "Local Image-based Lighting With Parallax-corrected <u>Cubemaps", Siggraph 2012</u>

Box is not great for organic environments -we intend to investigate alternatives going forward



Glowing Reflections

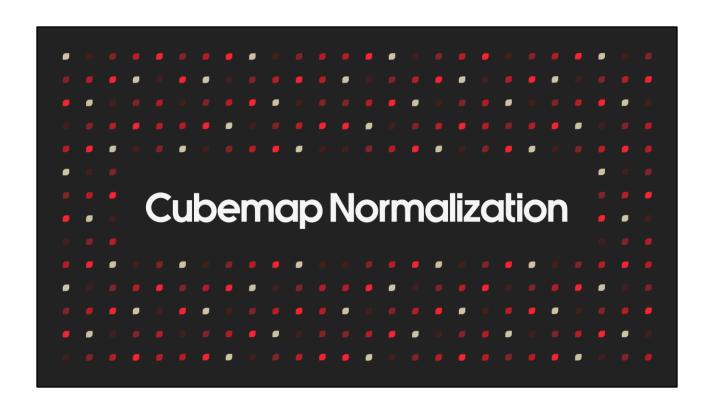
The problem:

Cubemaps are sparse

GI has local occlusion, cubemap does not

Metals see only cubemaps

Cubemaps are sparse compared to the GI, which means spec lighting can leak into occluded areas.



Cubemap Normalization

Objectives

- Keep a natural balance between diffuse and specular ambient lighting
- Use cubemaps for angular detail and GI for spatial detail.

A natural balance between diffuse and spec is more important than pixel correct reflections.

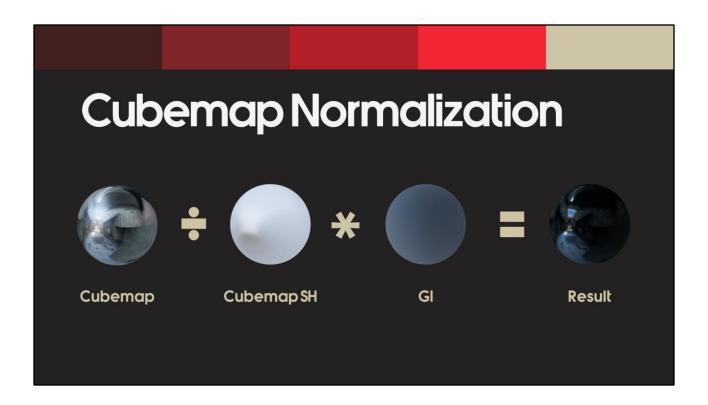
Metals need to benefit from GI bake Ideally should leverage cubemap angular detail + GI spatial detail.

Cubemap Normalization

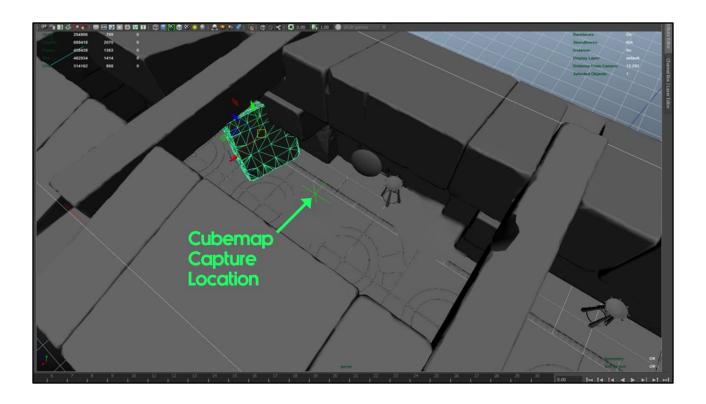
Generate spherical harmonics from cubemap during build

Use spherical harmonics to remove low frequency detail

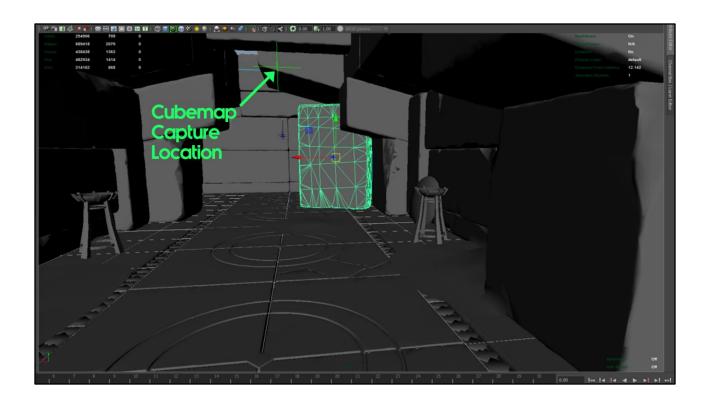
Replace with low frequency detail from GI



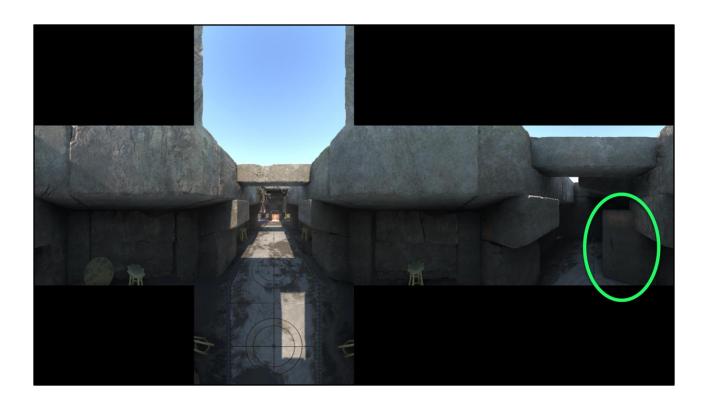
Again, the composition of reflections may be incorrect but the intensity/balance should be correct. This lets us get away with fewer cubemaps overall.



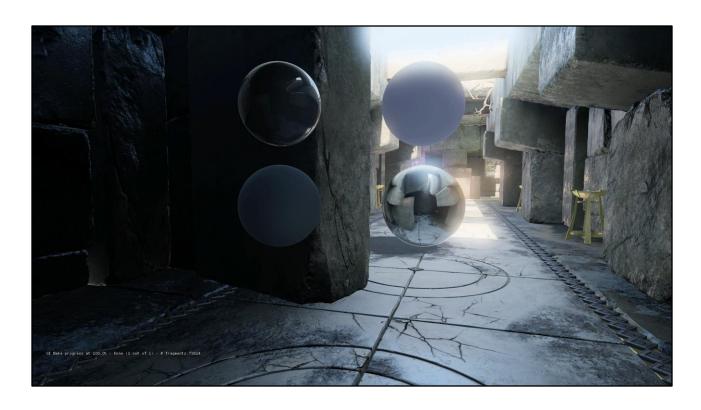
Example scene. Highlighted block and overhang occlude the corner of the hallway.



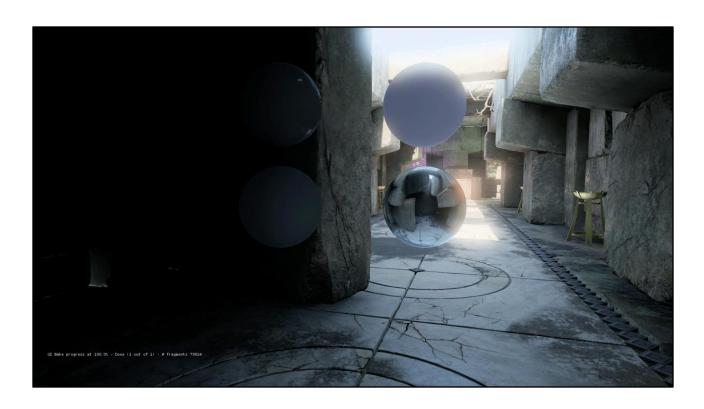
Example scene. Highlighted block and overhang occlude the corner of the hallway.



Cubemap sees the block, not the dark corner.



Original example.



Normalization on. Clearly contents of cubemap still incorrect (chrome ball) but the intensities are more correct.



Hard to tell they're behind the block Spec diffuse balance is way off (upper left sphere)



Notice the chrome ball is brighter where reflections point out of the corner like you'd expect.

Note: The corner on the left of the image isn't water-tight, there's an opening about the size of a tennis ball letting light in.



The back wall looks wet (remember there's an overhang above).



Normalization on.





To keep ourselves honest, you can see that when the objects get closer to the cubemap capture location the effects of normalization lessen. These aren't perfectly on the capture location, and the change is small. This is what you would expect because as the cubemap and the GI agree on what they see, they essentially cancel each other out.

Cubemap Normalization

Not an original concept (3)

Other studios were unhappy with results

Your mileage may vary

- Divide by 0 (or near)
- Channel separation causes discoloration

Lazarov, "Getting More Physical in Call of Duty: Black Ops II", Siggraph 2013

This wasn't really based on any particular paper however it ends up being pretty much identical to the call of duty technique (lazarov, 2013). I've spoken with other studios who've tried this (or similar) and some reported abandoning it because they didn't like the results.

"Fixing" Cubemap Normalization

Empirical tuning of denominator

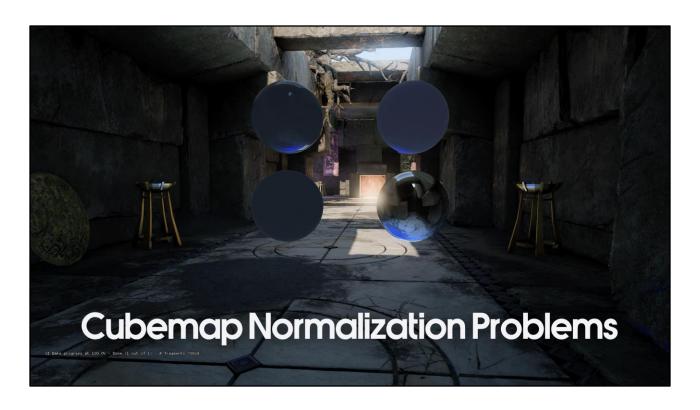
- Reduce directionality of cubemap SH encoding
- Reduce saturation of cubemap SH encoding

Ideally GI and cubemap have the same information

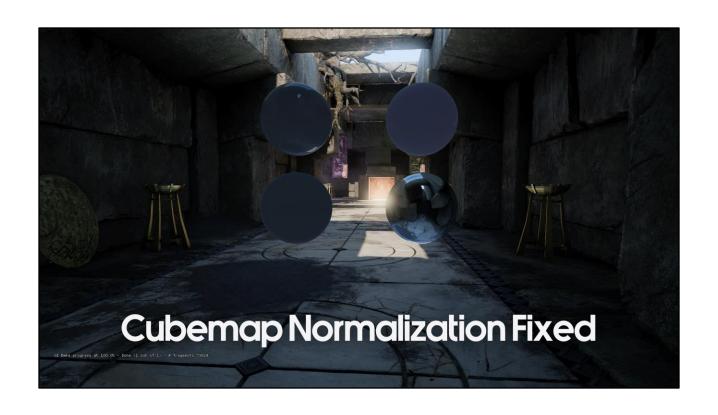
Use reconstructed GI at cubemap capture location for denominator instead of cubemap?

To fix the issues we reduce directionality and saturation in cubemap SH (denominator/div by 0).

If you have problems resulting from particles or transparents in your cubemap (that don't participate in the bake), you could probably use the GI at the cubemap capture location instead of SH from the cubemap as the denominator. We considered this but never ended up needing to try it.



Here's an example of the discoloration that results from clamping and channel separation.



Ambient Occlusion

SSAO

(4)

AO maps

Character AO capsules similar to the Last of Us constant + directional term (4)

For God of War we used the ragdoll capsules

- Almost ran over limit late in production
- · Will be custom going forward

lwanicki, "Lighting Technology of "The Last of Us"", Siggraph 2013

We used the ragdoll capsules for our character AO. It worked well but AO ended up having competing goals with ragdoll and we narrowly cleared the AO limit during finaling. Ragdoll can inflate capsules for various reasons, and potentially add extra to avoid falling through the world. We plan to make this a custom pipeline going forward.







Add capsules



Add ssao



Add ao maps

Volumetric Fog

Fog uses Bart Wronski's technique. (5)

GI volumes (0 band only) are sampled when constructing the lighting texture.

Particles use fog lighting texture for cheaper lighting. Get GI for free. Bart's idea.

) Wronsk

Wronski, "Volumetric Fog: Unified Compute Shader-Based Solution to Atmospheric Scattering", Siggraph 2014

Consistency is important so the fog also uses the GI.

The fog uses only band0 (single texture fetch) of the GI as an optimization we made for the e3 2016 reveal of the game. We used to store a texture per channel, had to reswizzle data to be a texture per band.

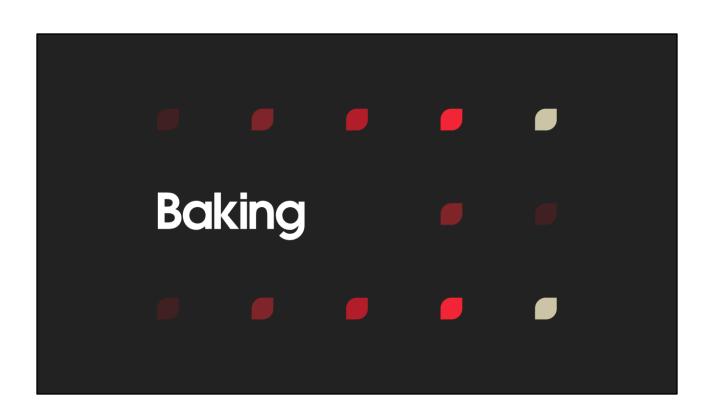
Optimization

Accelerated as part of our tiled lighting. Each 8x8 tile has a mask of potentially intersecting GI volumes, loaded as SGPR.

Runs in parallel with shadow rendering on async compute. Shader applies both ambient diffuse and spec.



GI and cubemaps are applied together in one pass.



Baking Background

Nova bakes (e3 2016)

- 1st party tool developed by Sony research ATG
- Carried over from lightmap and probe workflow
- Good staring point, known quantity

Nova was developed in the PS3 generation. It has shipped lots of great games and I believe is still used.

Baking Background

Nova bakes

- Complex material/mesh/scene conversion (20+ minutes, compute shader to bake materials into vertex colors)
- Bakes took a long time (30-60 minutes)
- Differences in lighting models as well as light primitives and parameters. Are results correct?
- Translucency was problematic
- Volumetric fog was not represented

...But it wasn't great for iteration.

- It has its own data format that is principally redundant to ours and is built only for Nova.
- The material conversion is complex for our materials. They were baked to vertex colors as an optimization.
- Are the results correct? Does Nova model their lights the same as we do? Spotlights were problematic for this reason. It was hard to verify that you've converted your parameters correctly. Left us to verify visually (which isn't trustworthy).

Additionally

- Scattering/translucent materials were possible with Nova but another tricky conversion.
- No volumetric fog.

Baking in-Engine Motivation

Leverage built data

- Lighters already build the levels to see results
- Custom building for light baking is wasteful
- Fewer pipelines -> fewer points of failure

Real-time results

- Lighting workflow is iterative
- We already support live-update changes from Maya

The Nova pipeline largely relied on automated testing to stay functioning. The (small) lighting team was the only group really using the tool and it was easy for even seemingly benign material changes to break the Nova pipeline.

Baking on PC or PS4

Why not use PC build?

PC doesn't use PS4 data

Would require lighters to move their workflow

PC only ran on automated tests

If it broke could we justify fixing late in dev?

PS4 issues?

Memory – debug heap is small

Ended up baking some levels on PS4 Pro

I get asked why we bake on the PS4 instead of the PC.

- PC does share some but not all data, so it would be an extra build
- We were trying to get the lighters off their own support island. Our PC build isn't really used in any workflow so it, like Nova relies on automated testing to stay functioning.
- Generally, we would rather have everyone looking at results on PS4 (it's what we're shipping after all)
- Most importantly, we could have abandoned PC build if the maintenance became more than we could afford. It wasn't critical to ship the game.

Caldera ("The Lake of Nine") ended up only baking on PS4Pro because it required extra debug memory to bake.

Baking in Engine

"Fast Global Illumination Baking via Ray-Bundles" (6)

- Early rays have fewer bounces, converges on multibounce.
- Rather than looping over rays for every point, loop over points for every ray.

Recommendation from Bart Wronski. Ideas borrowed from Stephen Hill.

Tokuyoshi, Sekine, and Ogaki, "Fast Global Illumination Baking via Ray-Bundles", Siggraph Asia 2011

Credit to Stephen Hill for adaptation for GI volumes

Gl Baking – Building Surfels

Rasterize geo on X,Y,Z shrink-wrap to cloud of surfels.

- Null render target/depth, no culling
- Hijack debug shader to append each shaded point to the global list of surfels using atomics

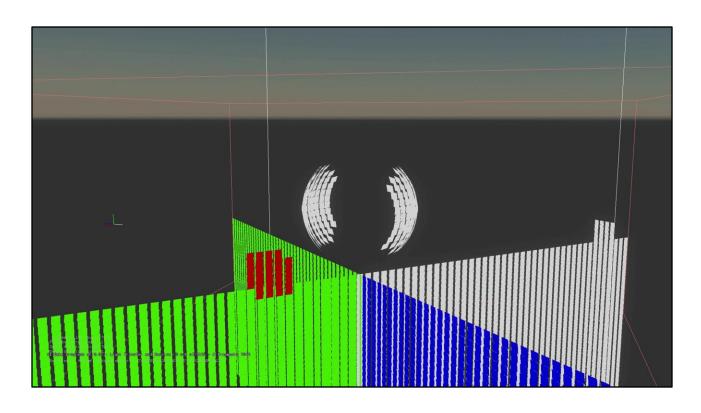
Every shader already has a debug permutation for various visualization modes.

Full material evaluated stored into surfel

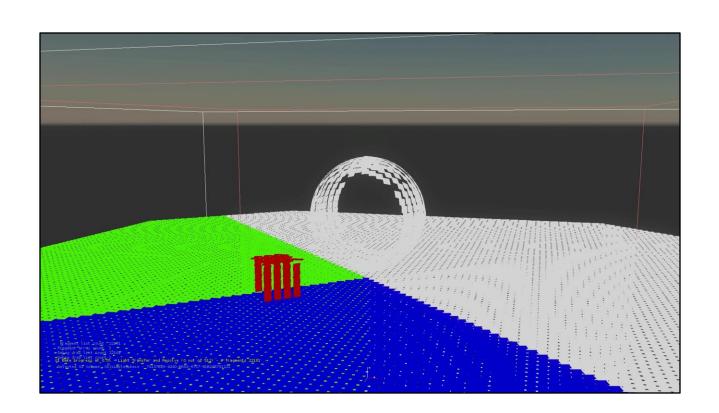
Position, normal, albedo, emissive, translucency

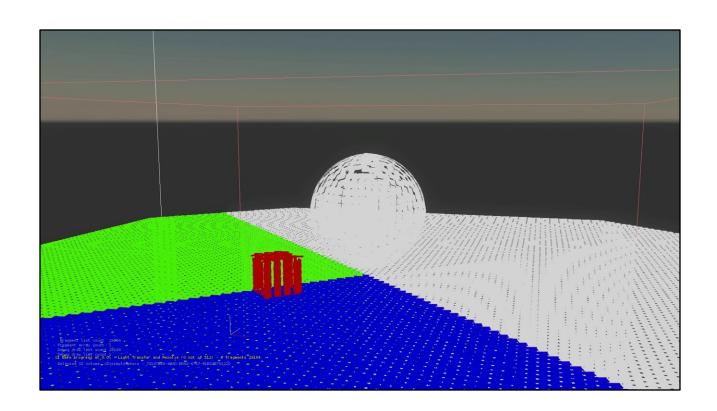
The first step is to shrink-wrap all the geometry into a cloud of surfels, each containing associated materials properties like normal, position, albedo, etc. To do this we hijack the rasterizer, rendering with no render or depth targets and no backface culling. It simply samples triangles on a regular grid for us. We use atomics to collect the surfels as we go into one list.

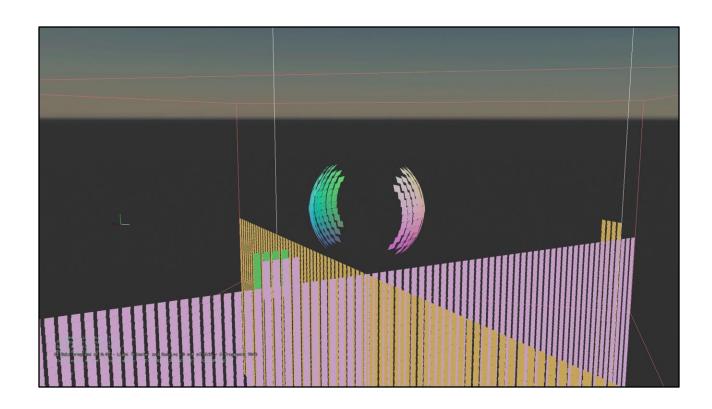
We have a lot of shaders so adding a GI bake permutation would slow the build down or create an ugly build-the-level-for-GI-baking workflow. Fortunately, we already had a debug shader permutation that we use for a variety of debug/instrumentation views. This shader obviously doesn't need to be performant so it was a convenient place to add a static branch for emitting the surfels.



Example: creating surfels on each axis

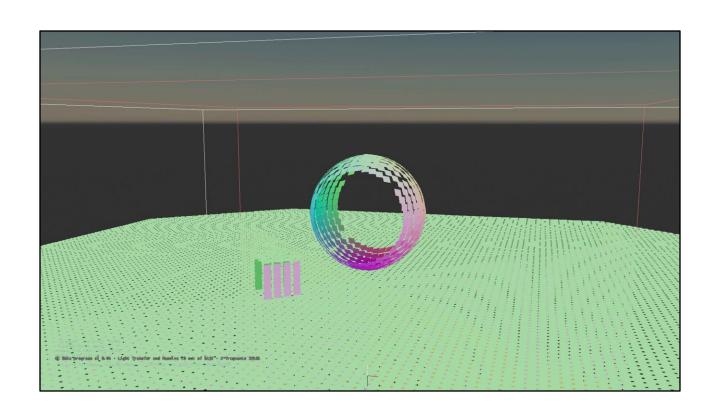


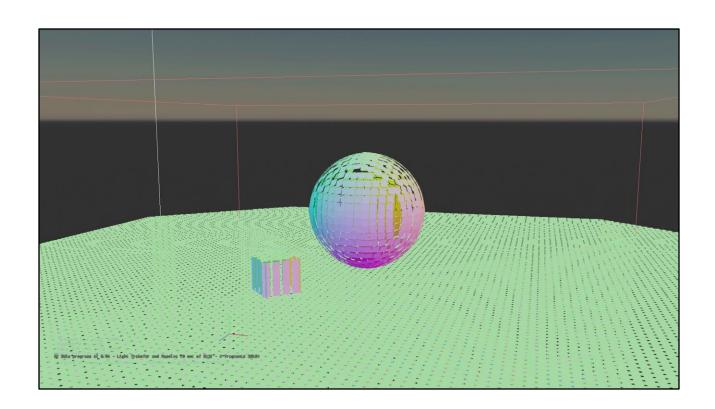




Again, but viewing normals.

This is the first of several times that I'm going to stress how important it is to build good debugging in _while_ developing a large feature like this.





Light Injection

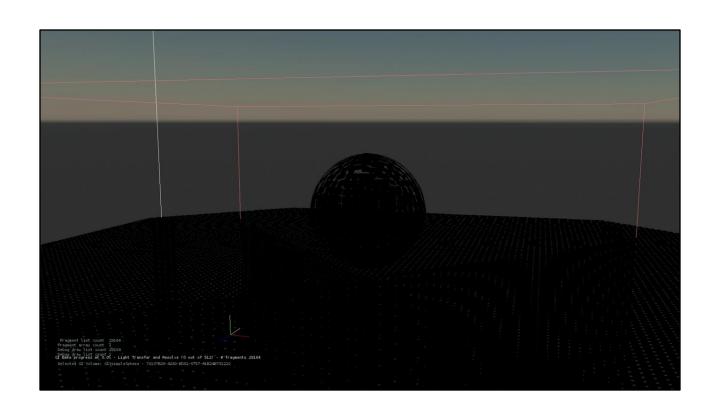
Original technique accumulated intermediate results in lightmaps

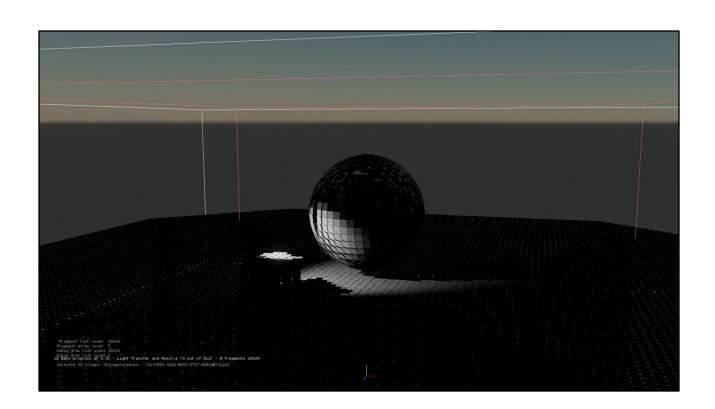
- This is done in the persistent set of surfels instead
- Lighting holds emissive when surfel is created

Direct light is evaluated for every surfel for every light (added to emissive)

Uses the same lighting calculations/models as the main render

Accumulate lighting in surfels rather than lightmaps, credit again to Stephen Hill.





Ray Processing

N rays

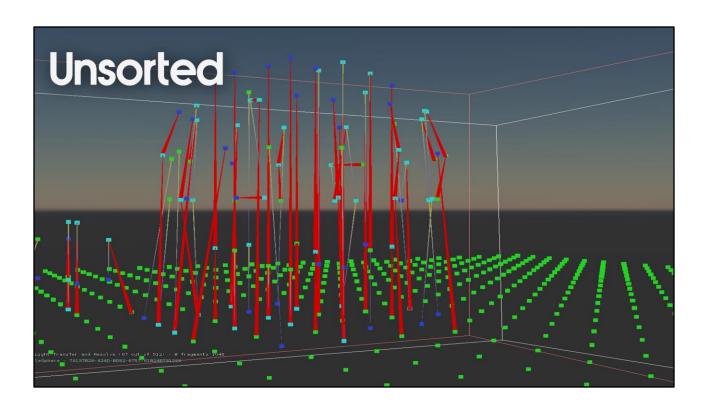
- Project surfels into linked lists
- Sort the lists
- Walk list, transfer light between surfels
- Resolve to GI volume

Build Lists For every ray direction Project surfels into texture of linked lists Each texel stores the current list head pointer Atomic swap to append new surfel as the new head Santa Monica Studio

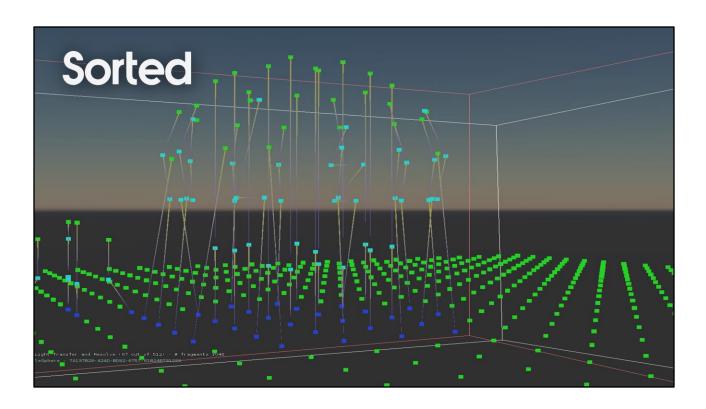
For each ray we build an orthographic projection around the area we care about. We project each surfel to a texture where each texel is the head pointer of a linked list. We use an atomic swap to replace the current head pointer with the new surfel.



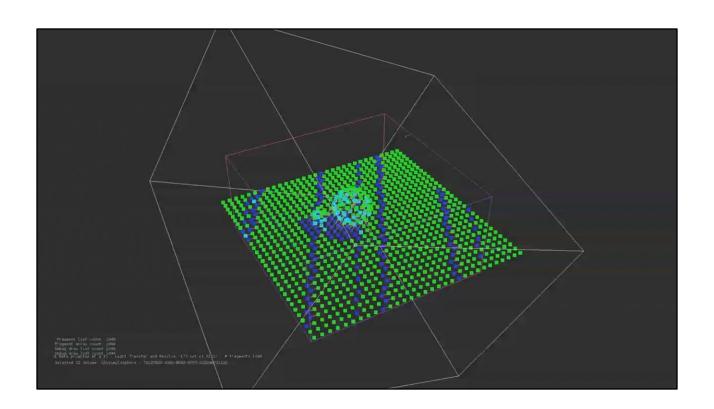
Next we sort the rays using a bubble sort. It was easy to implement and validate. It's surprisingly fast and never became the highest priority to optimize.

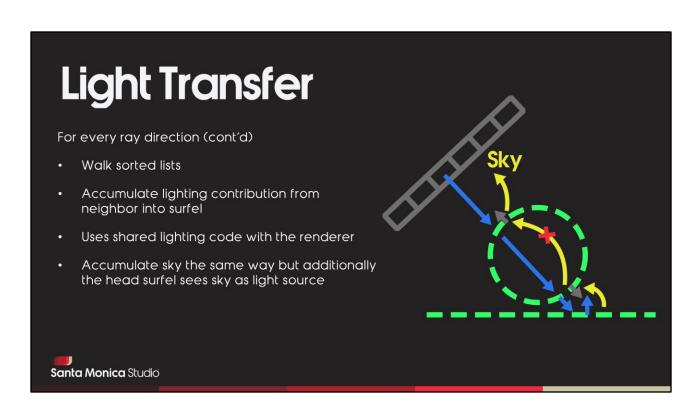


Again it's extremely important to build good debug rendering. Here's a view to help validate the sort order of lists. It renders directly from the surfel cloud with links between them. Improperly sorted links show up as red. Head surfels are green, tails are blue, otherwise cyan.

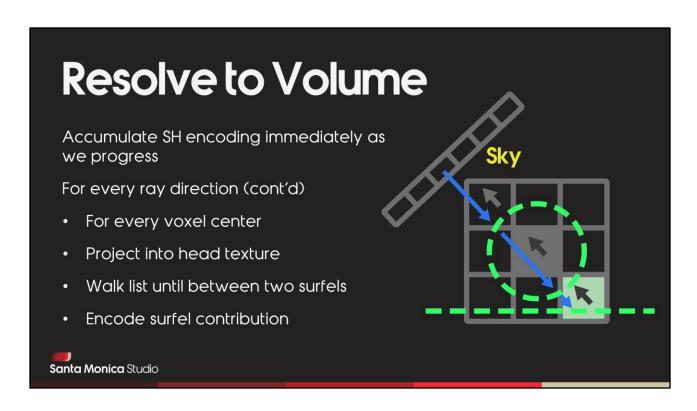


How could you validate 100k linked lists over 1000's of rays without it?





Now that the lists are sorted we need to exchange lighting. Simply walk the list and treat neighbors as light sources. Back-facing surfels are black. Head surfel sees unoccluded sky, sky is accumulated separately from lighting.



Lastly, we take the voxel center, project it into the list and walk until it's between two surfels. Then we simply encode the lit surfel as SH. Then we progress to the next ray.



Video showing the bake in GI view. Less than 14 seconds (realtime) to bake 512 rays, but the image stabilizes in far fewer rays. Artists can cancel, move objects/lights and restart. You can see how this would allow them to quickly iterate.

GI Baking Execution

State machine

Schedules GPU work by inserting passes into the renderer

Issues multiple state updates a frame (all necessary states are buffered)

Targets 80ms a frame. Assumes GPU time scales linearly with passes, adjusts accordingly.

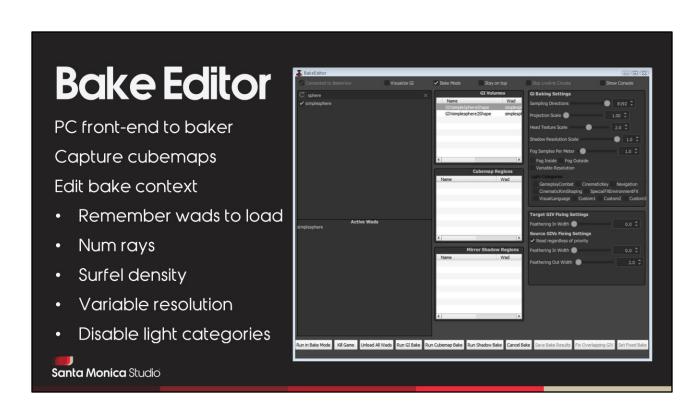
80ms target means most of the frame is spent on baking but maintains high enough framerate to be responsive.



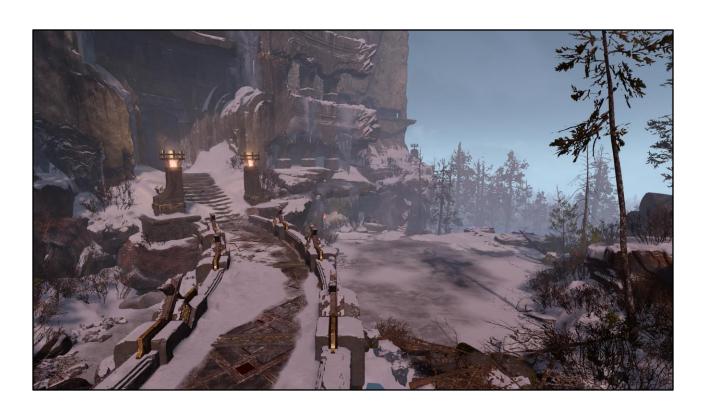
Objects like doors and breakables would be excluded from bake. Lights generally should participate except accent lights in cinematics and potentially special fx. For the e3 2016 demo there were several different suns with different angles and intensities to sell the progression of time. Transitions were strategically hidden.

To avoid seams in the bakes, all suns were marked as do-not-bake and a single bake-only sun was added from an average direction and intensity.

GI volume resolution will be based on ideal meters per voxel up until it reaches the memory budget, in which case it will reduce resolution to fit.



Entire categories of lights can be disabled during the bake for convenience. For example lights marked as special fx could be disabled during the bake.



Level from beginning of the game Original troll arena in e3 2016 Load additional wad Quick bake (realtime)



This video shows surfel debug mode, lighting, sky vis, albedo, normal. Baking progress while in surfel debug mode.

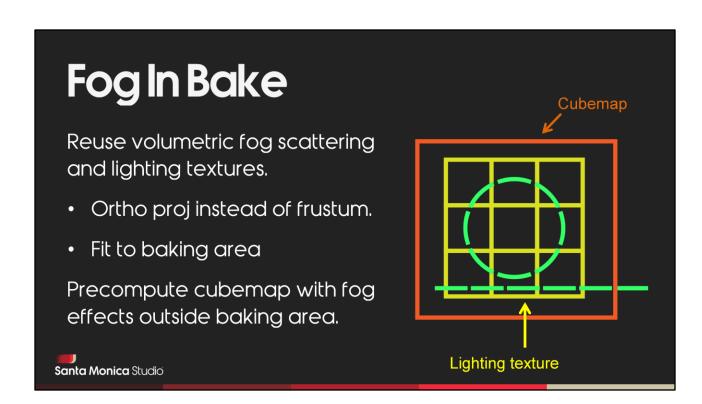
(realtime)



We support single step debugging through the bake. Here I single step while in linked list debug mode.



Here's an example of a more typical iterative workflow. Lights and objects being moved around several times re-baking along the way. You can see the surfels update after the sphere moves, there's no precomputation of the scene required. Bakes are easily cancelled and restarted. You can see that bright/small lighting causes fireflies initially but it smooths out with more rays. (realtime)



As I mentioned before, having fog participate in the bake is one of the motivators for moving away from Nova. Fog can be a significant light source in a scene. For this Bart modified his technique to use an orthographic projection for the lighting and scattering textures around the GI volume. We use a cubemap for anything outside.

Light Transfer - Fog

For every ray direction (cont'd)

- Apply extinction and inscattering between surfels
- Variable num taps, fixed step size.





We modify the light transfer to sample the fog textures, taking multiple taps to accumulate extinction and in-scattering.

Resolve - Fog For every ray direction (cont'd) Apply extinction and inscattering between voxel center and surfel Variable num taps, fixed step size.

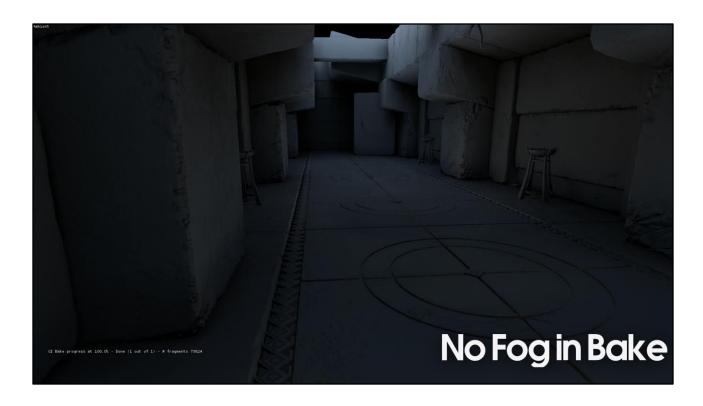
For resolve we do the same thing but from voxel center to surfel



Scene, no fog



Add fog



No fog in bake



Fog in bake

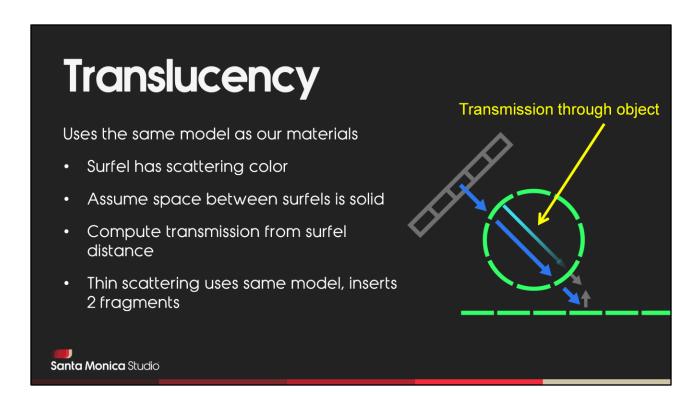


No fog in bake



With fog in bake

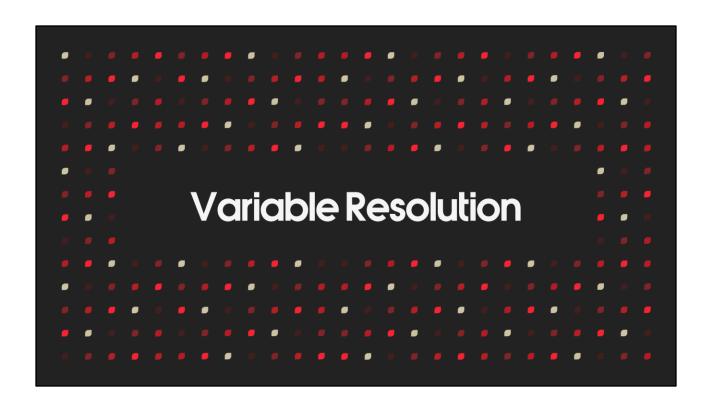
-Directionality on block at the left comes from the column of light, quite a drastic change.



Thin (2-sided) we add 2 surfels at the same location. We use some bit hacking to guarantee proper sort ordering for each ray.



Block of ice + spot light



Variable Resolution Motivation

Lighting is relatively constant in open spaces

Lighting varies most near surfaces

It would be nice to redistribute resolution near surfaces

Can't explode bake times, ideally bakes still scale with sampling density

Indirect lighting changes are low frequency in open air, away from objects.

Encoding

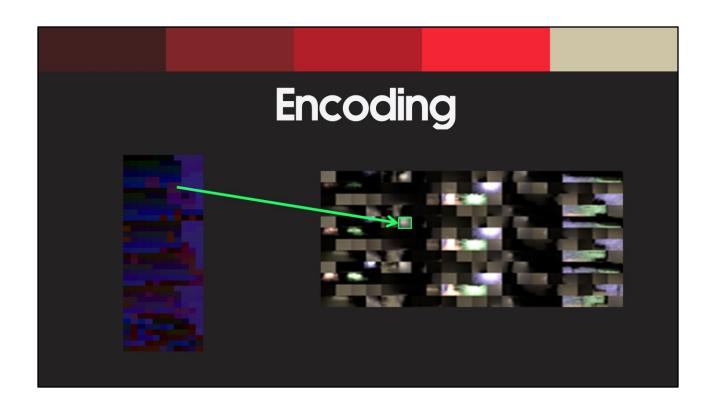
Atlas discontiguous blocks in the GI textures

Indirection texture to reassemble

- Indirection texture roughly 4m³ voxels (uniform) (7)
- Stores effective resolution (1x1x1 8x8x8 in GoW) + atlas location

J.M.P. van Waveren, "Software Virtual Textures", 2012

Variable resolution uses essentially a 3D virtual texture. This is a technique I'd developed in the previous generation. Indirection texture is usually 4 meters per voxel, sometimes larger. Each indirection voxel can be backed by a different sized block in the atlas texture.



On the right you see an example section of an atlas texture, scrambled blocks of different resolutions packed together. On the left you see a piece of the indirection texture, containing location and size information for the blocks in the atlas texture. The indirection texture's job essentially is to unscramble the atlas.

Determining Resolution

After surfels are collected, before lighting

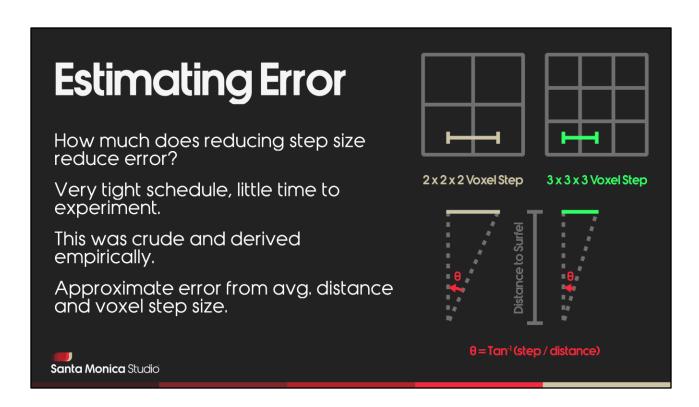
Small number of rays to calc average distance from indirection voxels. (< 10 sec)

Read back on the cpu.

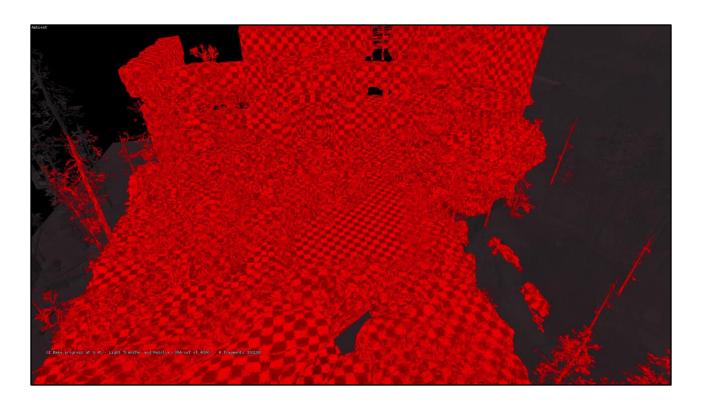
Start with indirection voxels as 1x1x1.

Promote the voxel that reduces error the most. Repeat until memory budget has been met.

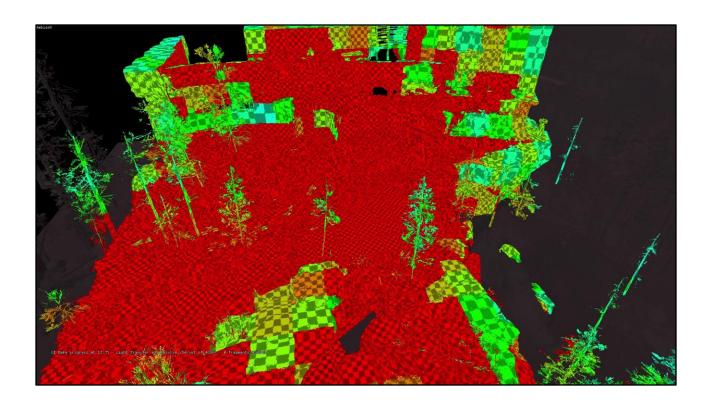
Run over a small number of rays (256-512) at indirection resolution to determine the average-nearest-distance to a surfel from the indirection voxel center in all directions. Then we use a greedy algorithm starting with all voxels as 1x1x1 that promotes the voxel that we estimate reduces error the most based on the average-nearest-distance. We repeat this until we've spent our memory budget. This allows us to know our final resolution before we do any baking.



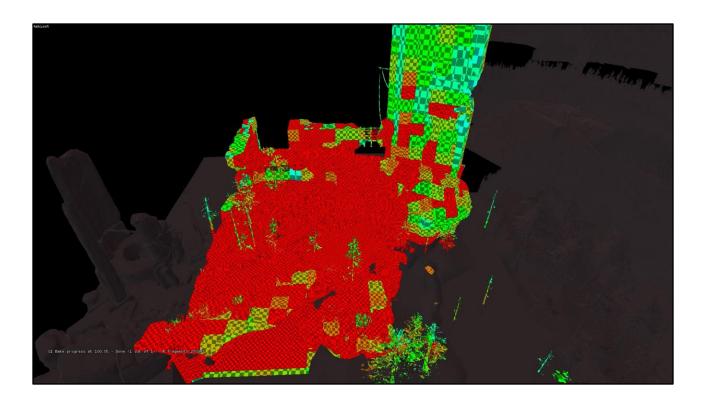
So how do we estimate error? There wasn't a lot of time to derive a perfect mapping so we went with something empirical. The basic idea is we assume all surfaces have high frequency detail. If you move an observer point that is close to the surface perpendicularly the observed error would be large. Whereas an observer far away moving that same distance would have a small error. So we use that parallax angle as our error metric.



Here's a debug visualization showing voxel resolution. This GI volume is uniform.



A variable resolution GI volume using the same memory budget.



Here's a video to hopefully help explain the technique using that same debug view. I'll sweep a plane across the volume so you can see the resolution change in open spaces. Colder colors are lower res, warmer are higher res.

Atlas Packing

We know ideal resolution for every block

List of blocks for each resolution

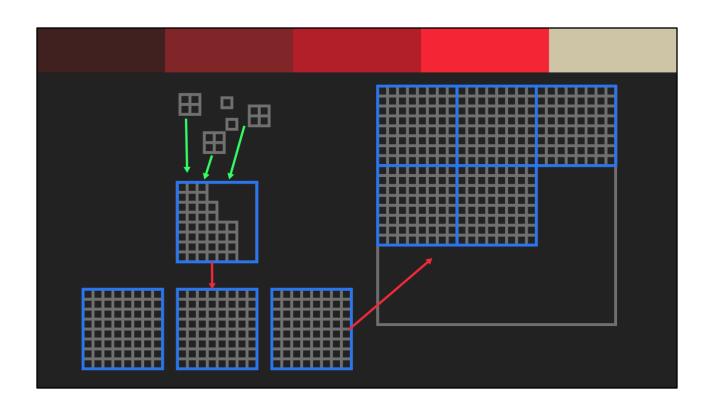
Brute force fill 32x32x32 section with blocks.

Then pick best atlas texture size to minimize waste

• idealDim = $\sqrt[3]{num\ 32x32x32}$ sections

Build indirection texture before lighting

Again, time was limited so there are probably better solutions for packing the atlas texture. This is essentially a 3D pooled allocator for 32x32x32 sections. Each 32x32x32 section is filled as tightly as it can be with the blocks remaining. Then, we simply find the best dimensions for the texture based on the number of sections. In the ideal case the number of sections is a cube, this is never the case so we search the possible width and height options to find one that minimizes waste.



Baking

Resolve - Break blocks in to 4x4x4

Once sample locations are known resolve like normal.

Small blocks are wasteful but bake times aren't drastically slower.

Could pack multiple small blocks into wavefronts

Now that we know the final layout of the atlas texture we can actually bake. Only the resolve stage of the baking changes with variable res. We need some way of mapping atlas voxels to world positions. With uniform volumes we break the voxels into 4x4x4 wavefronts. With variable res we break the individual blocks into 4x4x4 wavefronts too. However, anything that's not a multiple of 4 will have wasted lanes. This didn't end up being a significant performance hit.

Block Borders

Voxel centers are corners. Essentially a voxel border.

Allows hardware filtering.

Seams? Only where under-sampled and neighbors differ in resolution

Better error estimator should help

Ideally closer match in sampling res and signal frequency.

Keeping hardware filtering is even more important now with the indirection texture, it too would unroll to 8 samples + indirection logic for each + 8 atlas taps. So we treat voxel centers as box corners, this means that we transition to the next block before we'd start filtering outside our current block (and from sampling the random neighboring block in the atlas texture).

Seams should only occur where sampling density is lower than lighting frequency and where neighbors have different resolutions

- Under-sampling means error estimate failed or we ran out of memory
- Going forward I'd like to experiment with using real lighting information to drive the resolution. Maybe replacing the average-nearest-depth pass with instead a lighting variance over the voxel. This would also avoid wasting samples close to objects that don't actually have interesting lighting features.

Variable Resolution - Fixup

Use Eigen library linear solver to minimize error in border voxels across neighbors (4)

Solve runs on pairs of neighbors on a single axis at a time to allow precomputing.

Fixup must be run several times to fix corners and edges

Could solve whole volume at once but probably would be very expensive (large matrix)

lwanicki, "Lighting Technology of "The Last of Us"", Siggraph 2013

(4)

Precompute solver for each pair of neighbor options. Then run across each axis separately. Corners and edges have multiple constraints so we have to run multiple iterations.

Can take minutes to compute on the CPU.

There are better options but we ran out of time



Before fixup



After fixup



Here's a video of me sweeping that plane across the volume again, this time with the GI results.

Variable Resolution

Added late in development (rolled out Sept. 2017, gold Mar. 2018)

Optional and opt-in

- Helped trim memory or improve visuals depending on the level.
- Small divergent branch to alter UVs used when applying GI volume



Uniform



Variable res with the same memory budget

Compression

Added Jan.-Feb. 2018 (gold in Mar.2018)

"Low risk" compared to variable res.

Keep band0 as float16

Store
$$\frac{band1}{band0 * \sqrt{3}}$$
 as LDR (8)

Compute band 1 by multiplying by band 0 * $\sqrt{3}$

Hazel, "Converting SH Radiance to Irradiance", 2017

(8)

We prioritized variable res over compression because it seemed higher risk and the window to implement would close sooner than compression. We could do compression really late right?

Total energy of SH is represented in the constant term, can be used to normalize second band. Store only constant (band0) as float, and the second band as ldr.



Before



After. Whoops

Compression

Lerp(a*b, c*d) := Lerp(a, c) * Lerp(b, d)

Works for point sampling

Negligible error when high res.

Worked for Frostbite (9)

(9)

We're relying heavily on interpolation/up-sampling

Normal offset slightly less than 1 voxel diagonal

O'Donnell, "Precomputed Global Illumination in Frostbite", GDC 2018

What happened? Well, technically the interpolation changes with this compression. Normally this wouldn't be an issue, light maps tend to be higher res, in fact Frostbite presented only a month or so after we'd scrapped it and moved on. For them this approach worked great for lightmaps. So I believe the problem is two fold 1) resolution and 2) high contrast lighting changes from inside and outside of the object coupled with that we'd tuned the normal offset distance down to prevent some overdarkening artifacts which I believe left us with a subtle amount of self-occlusion. When the interpolation changed it exaggerated that self-occlusion. We'll do some more investigation into this, but at a month before gold we didn't have time to open back up the normal offset again.

Fortunately perf and memory were ok. Disk space was our main motivator to get compression in.

Compression – Plan B

Band 1 - Range remap, store in LDR

- One min/max for all color channels per GI volume to avoid quantization discoloration
- Worked for most volumes.
- Turned off for a few due to dynamic range.
- · Came in during finaling.
- Defaulted on. Lighters went back through all levels to verify. Sorry!

So we simply min/max compressed the second band instead. We tested lots of levels and found that banding artifacts were not that common. So, it was defaulted on and the lighters were gracious enough to go back through and verify wads. They turned off compression where there were banding artifacts. Savings (and bake times) were worth it.

Stats

Runtime

GI + Cubemaps - 2 ms

- Final AO apply 0.25ms
- GI 0.75ms
- Cubemaps 0.75ms
- Unpack g-buffers + write results 0.25ms

Bake times

Uniform - 30sec - 6 mins

Variable Res - 3 - 15 mins

Runtime numbers are estimates (removing portions of the combined shader), there are interaction effects between cubemaps and GI. The AO number isn't the total AO time, just the portion of the combined shader that applying it cost.

Bake times: 15mins is the more typical worst case. Lake of nine was the absolute worst case variable res, it took 20 mins.

Stats

GI Volumes

300 total

80 variable res

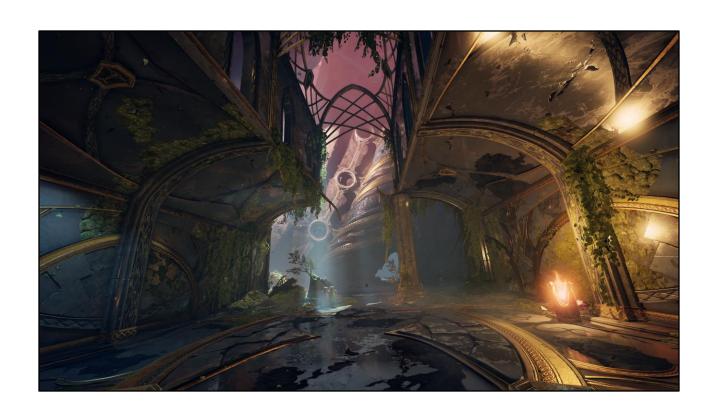
250 compressed

Disc

2.9 GB for GI

30% total savings by compression

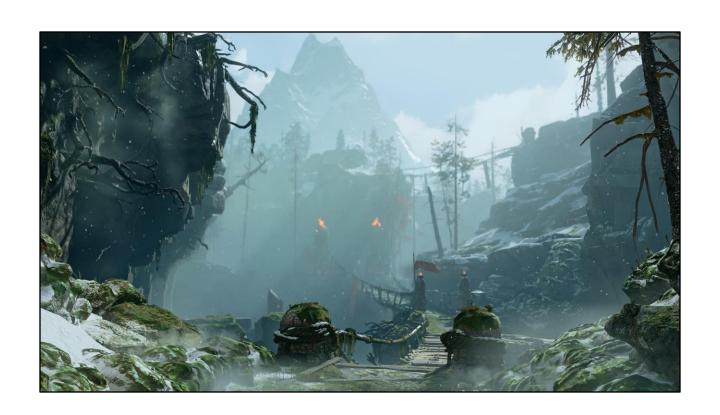




















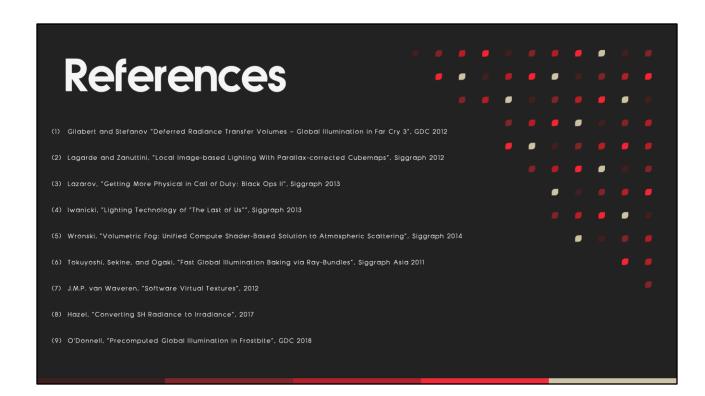
Thanks

Bart Wronski

Stephen Hill

Santa Monica Studio Rendering Team

Santa Monica Studio Lighting Team





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BRUNO VELAZQUEZ - Animation Director
God of War: Breathing New Life into a Hardened Spartan - ANIMATION BOOTCAMP
MONDAY, MARCH 18 - 10:00AM - 11:00AM - ROOM 2010, WEST HALL



MELISSA SHIM - Senior Animator
Animation Bootcamp: Animation Tricks of The Trade - ANIMATION BOOTCAMP
MONDAY, MARCH 18 - 4:40PM - 5:10PM - ROOM 2010, WEST HALL



ROB DAVIS - Lead Level Designer Level Design Workshop: The Level Design of God of War - LD SUMMIT TUESDAY, MARCH 19 - 11:20AM - 12:20PM - ROOM 301, SOUTH HALL



ERICA PINTO - Lead Narrative Aniwator
What They Don't Teach You in Art School: Lessons for First Time Leads - ART DIRECTION BOOTCAMP
TUESDAY, MARCH 19 - 1:20PM - 2:20PM - ROOM 2001, WEST HALL



AXEL STANLEY-GROSSMAN - Lead Technical Character Artist Santa Monica Studio Presents: God of War (Presented by Autodesk) - VISUAL ARTS TUESDAY, MARCH 19 - 2:40PM - 3:40PM - ROOM 3020, WEST HALL



RUPERT RENARD Senior Programmer
Wind Simulation in God of War - PROGRAMMING
WEDNESDAY, MARCH 20 - 10:30AM - 11:00AM - ROOM 303, SOUTH HALL



RUPERT RENARS - Senior Programmer
Disintegrating Meshes with particles in God of War - PROGRAMMING
WEDNESDAY, MARCH 20 - 11:30AM - 12:00PM - ROOM 303, SOUTH HALL



ED DEARIEN & JEET SHROFF Assistant Producer & Gameplay Director

Playtesting God of War + PRODUCTION VEDNESDAY, MARCH 20 + 2:00PM - 3:00PM + ROOM 2001, WEST HALL





BORI ARAZI - Birector of Photography
Creating a Deeper Emotional Connection: The cinematography of God of War - VISUAL ARTS
WEDNESDAY, MARCH 20 - 339PM - 4309PM - ROOM 2005, WEST HALL



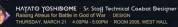
JASON MCDONALD - Design Director Taking an Axe to God of War Gameplay - DESIGN THURSDAY, MARCH 21 - 10:00AM - 11:00AM - ROOM 303, SOUTH HALL



ERICA PINTO - Lead Narrative Aniactor
Keyframes and Cardboard Props: The Cinematic Process Behind God of War - VISUAL ARTS
THURSDAY, MARCH 21 - 11:30AM - 12:30PM - ROOM 2001, WEST HALL









JOSH HOBSON - Lead Rendering Programmer The Indirect Lighting Pipeline of God of War - PROGRAMMING THURSDAY, MARCH 21 - 4:00PM - 5:00PM - ROOM 2010, WEST HALL



SEAN FEELEY * Sr Stoff Technical Artist Interactive Wind and Vegetation in God of War * DESIGN THURSDAY, MARCH 21 * 5:30PM - 6:30PM * ROOM 2005, WEST HALL



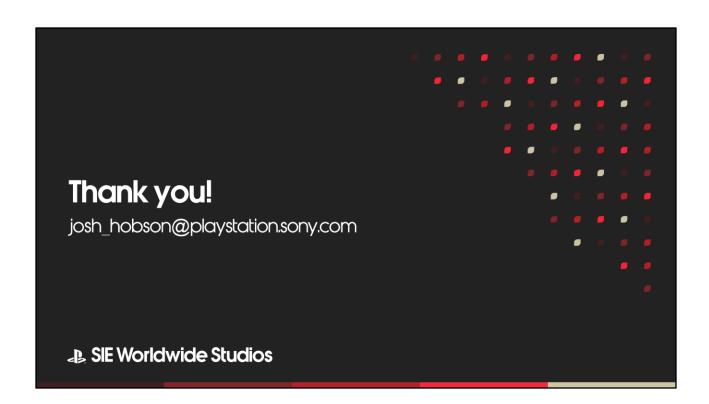
CORY BARLOG - Creative Director Reinventing God of War FRIDAY, MARCH 22 - 10:00AM - 11:00AM - ROOM 303, SOUTH HALL

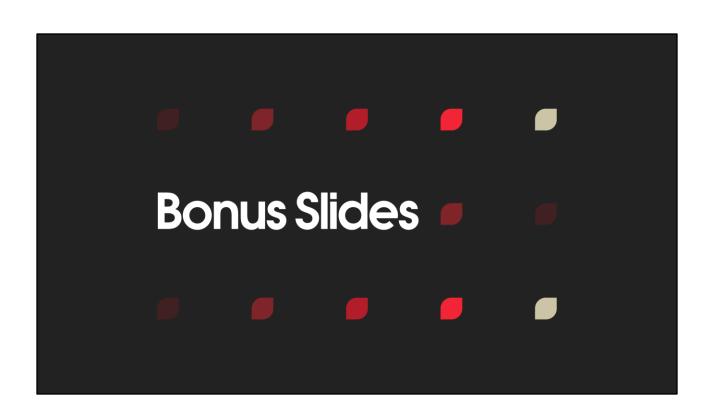


MINIR SHETH & JEET SHROFF - Lead Combat Designer & Gameplay Director Evolving Combat in God of War for a New Perspective - DESIGN FRIDAY, MARCH 22 - 1:30PM - 2:30PM - ROOM 2005, WEST HALL









Blending Between GI Volumes

GI Volume bakes were sometimes manual

- Some setups involved manually altering the setup before baking
- For that reason we could not automatically re-bake the whole game.
- Having all special setups saved as data going forward is a goal so we can automate.

No blending between volumes at run time.

Offline tool identifies overlaps

- Resamples lower priority volume from higher priority.
- Bilinear smooths edges around borders.

Offline blending only

- Where there's overlap, lower priority GI volumes sample higher priority and replace contents