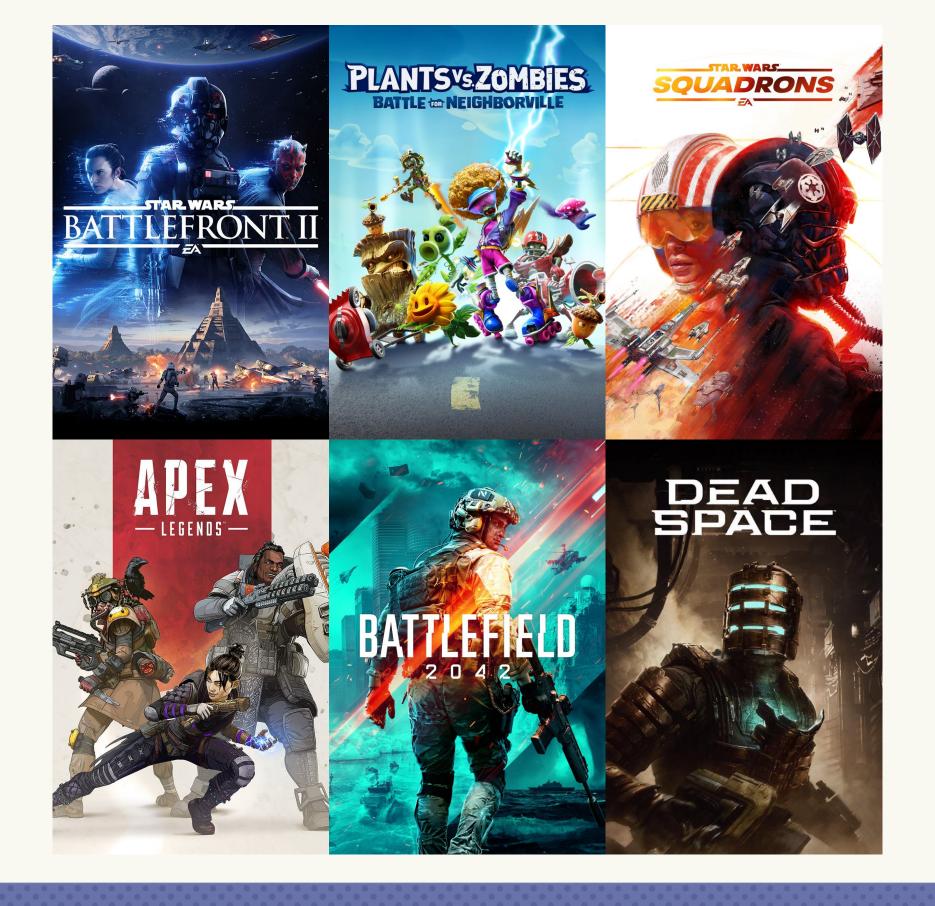
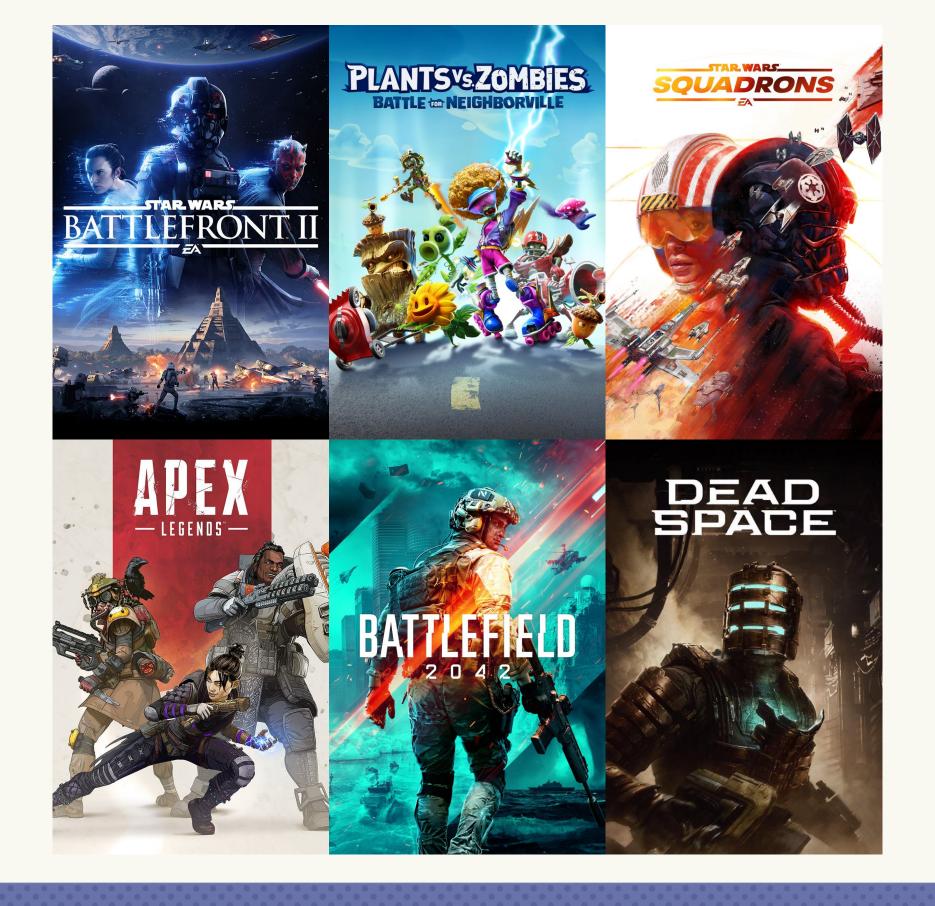
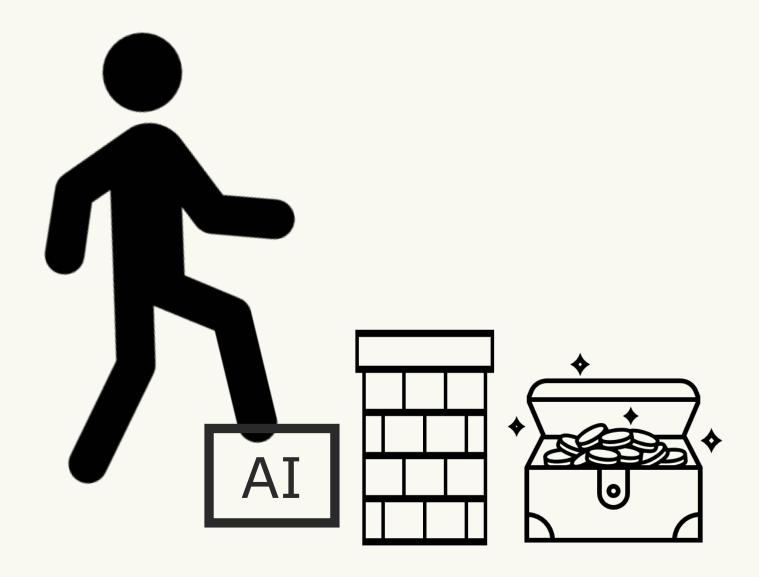


### AutoPlayers

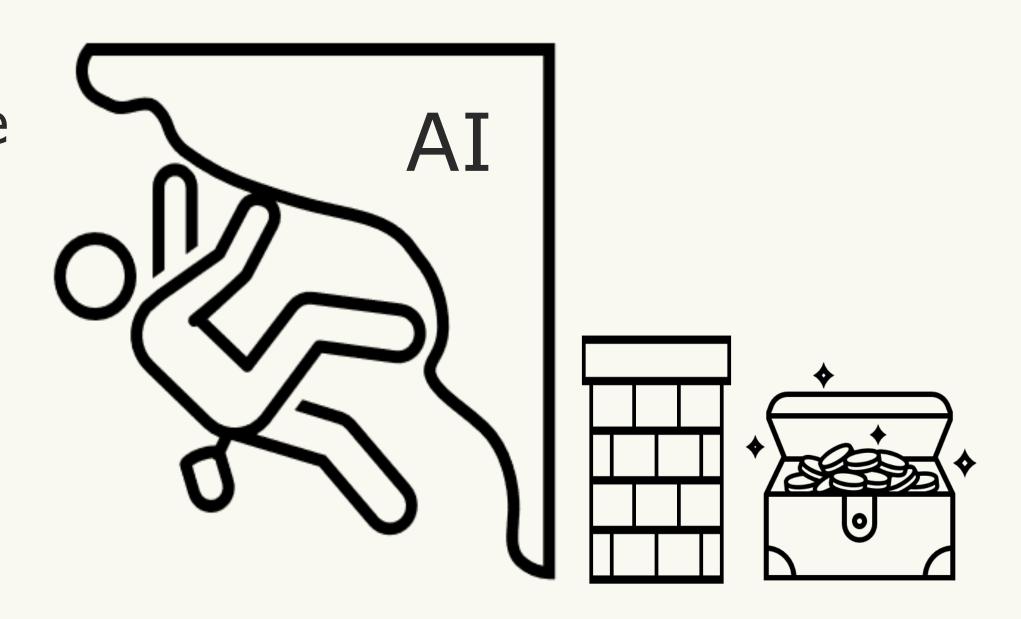




1. Keep it Simple



1. Keep it Simple



- 1. Keep it Simple
- 2. End Use Focus



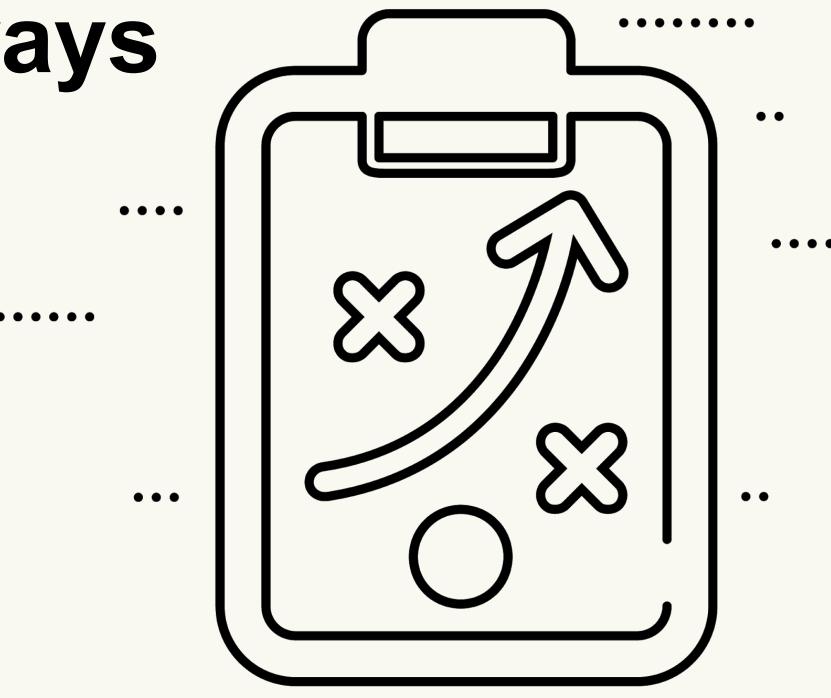
- 1. Keep it Simple
- 2. End Use Focus



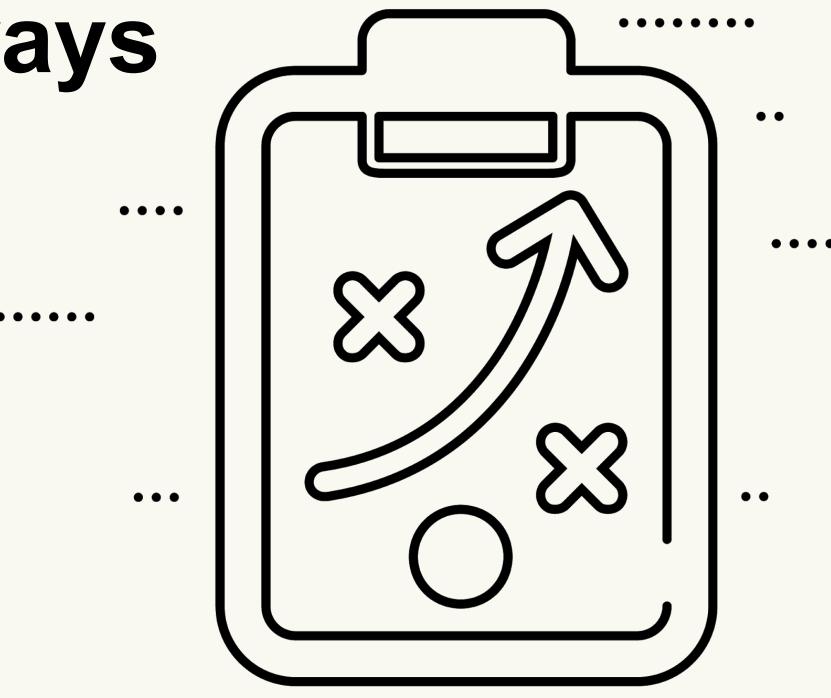
- 1. Keep it Simple
- 2. End Use Focus
- 3. Clear Priority



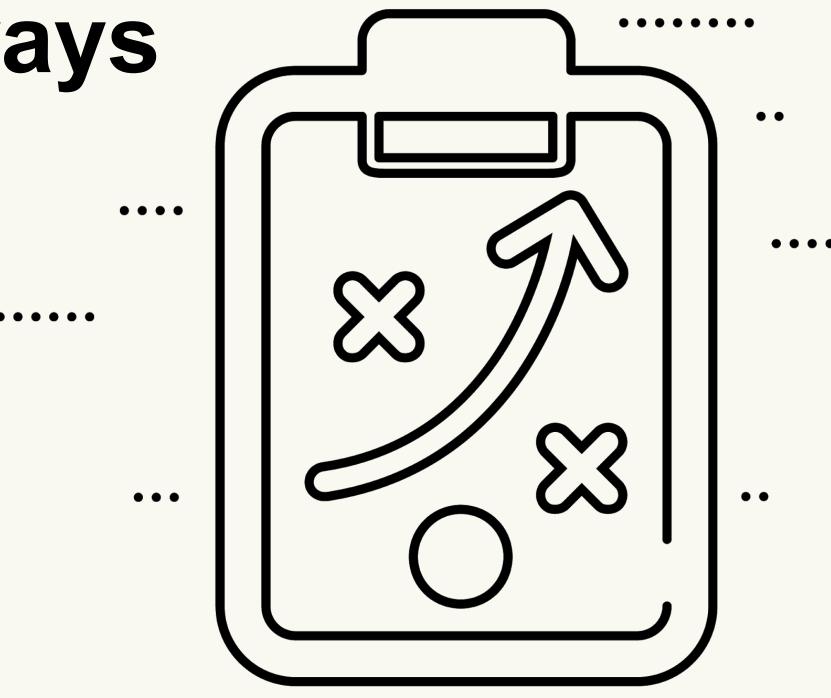
1. Pioneering



1. Pioneering

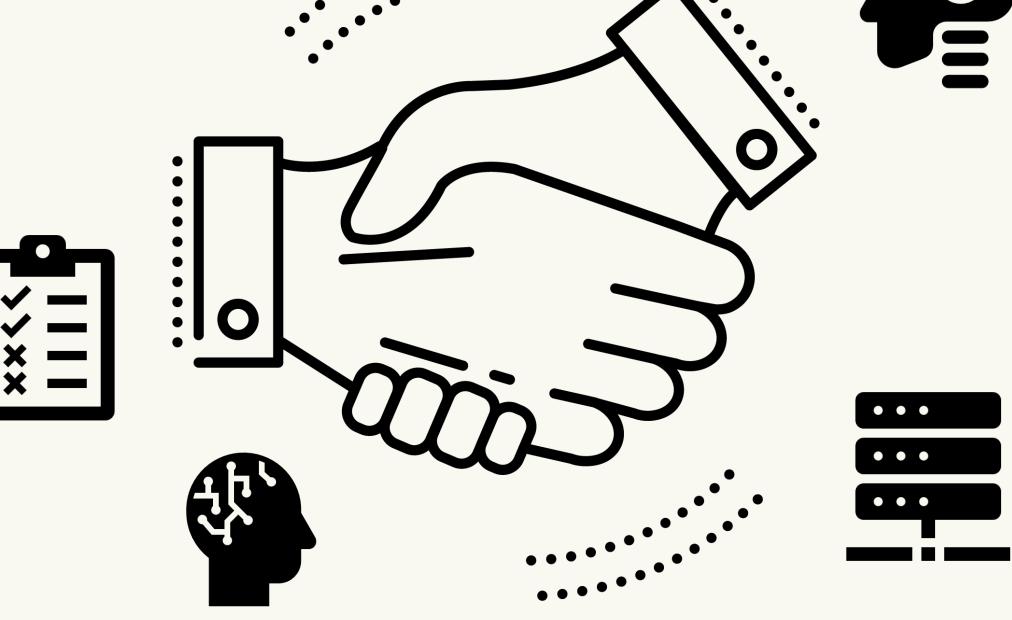


1. Pioneering



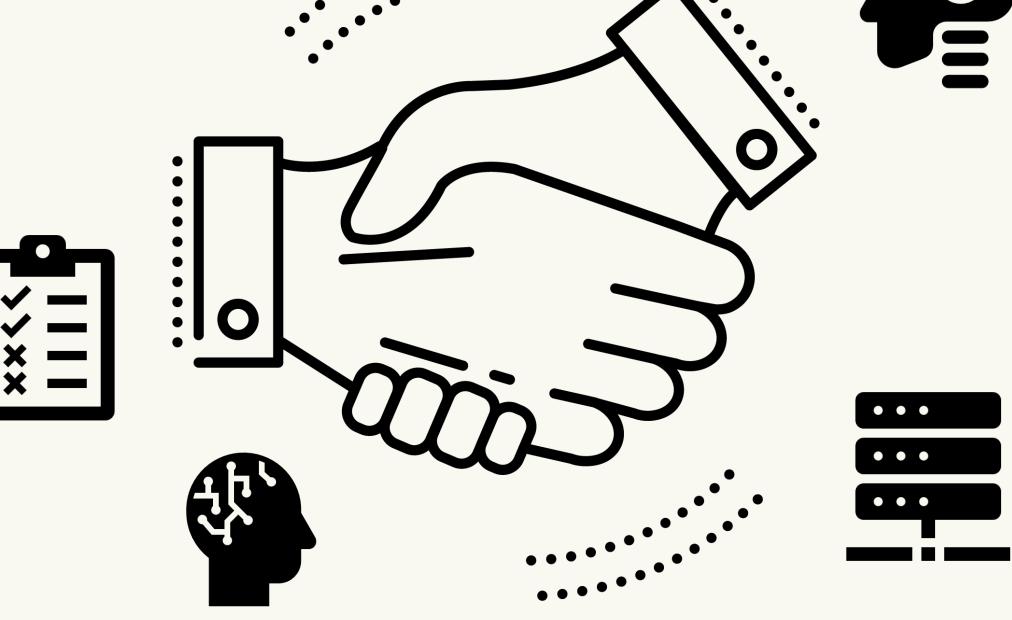
1. Pioneering

2. Teamwork

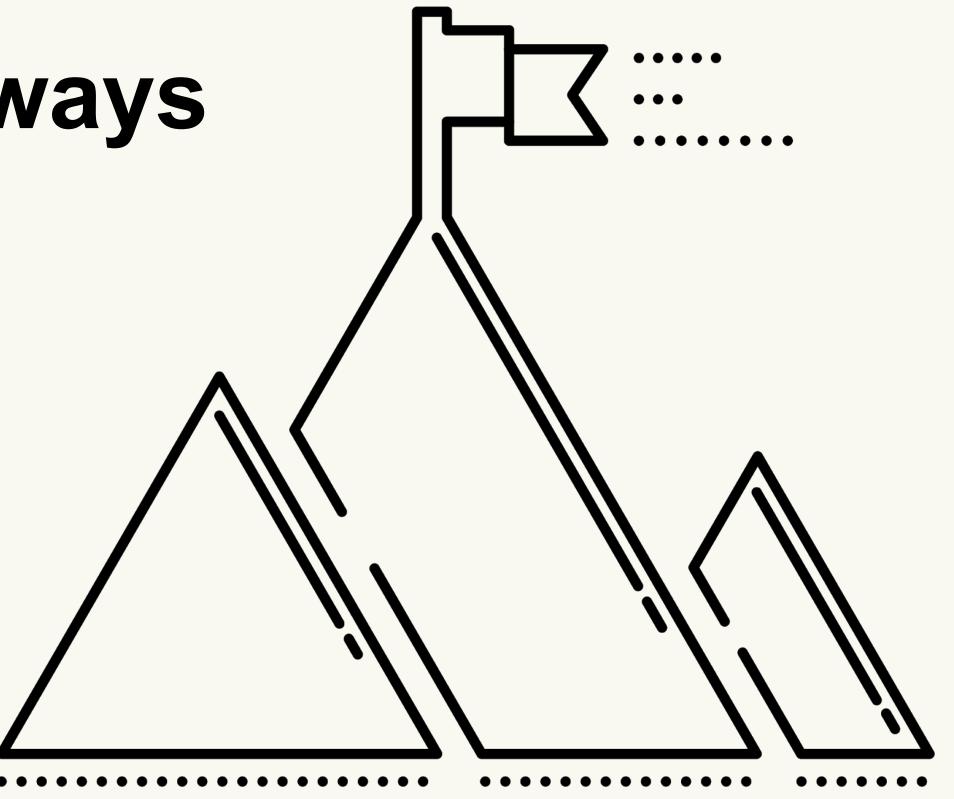


1. Pioneering

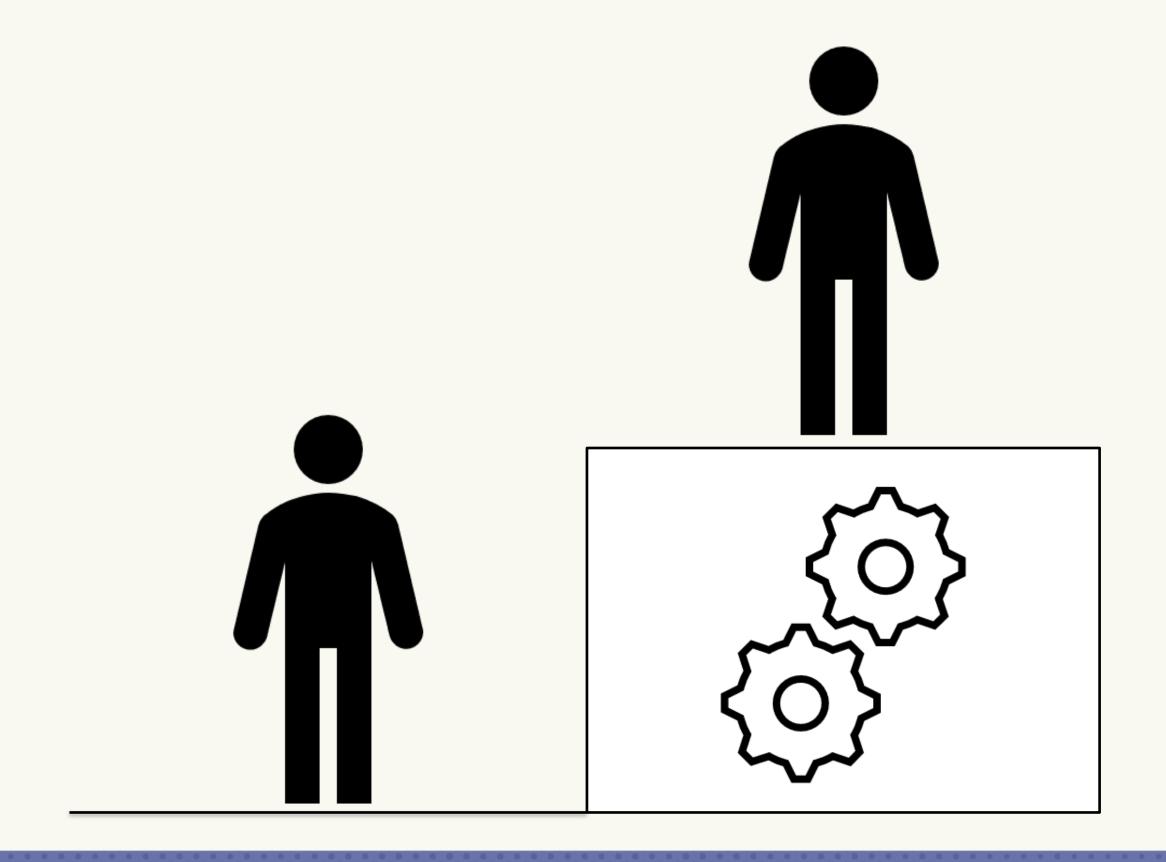
2. Teamwork



- 1. Pioneering
- 2. Teamwork
- 3. Determination



# **Great games, made better**







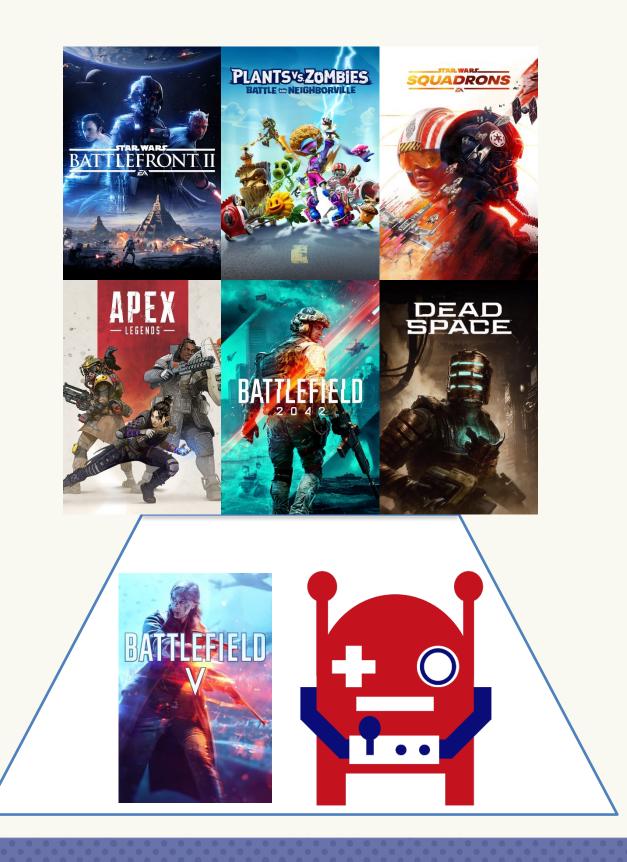








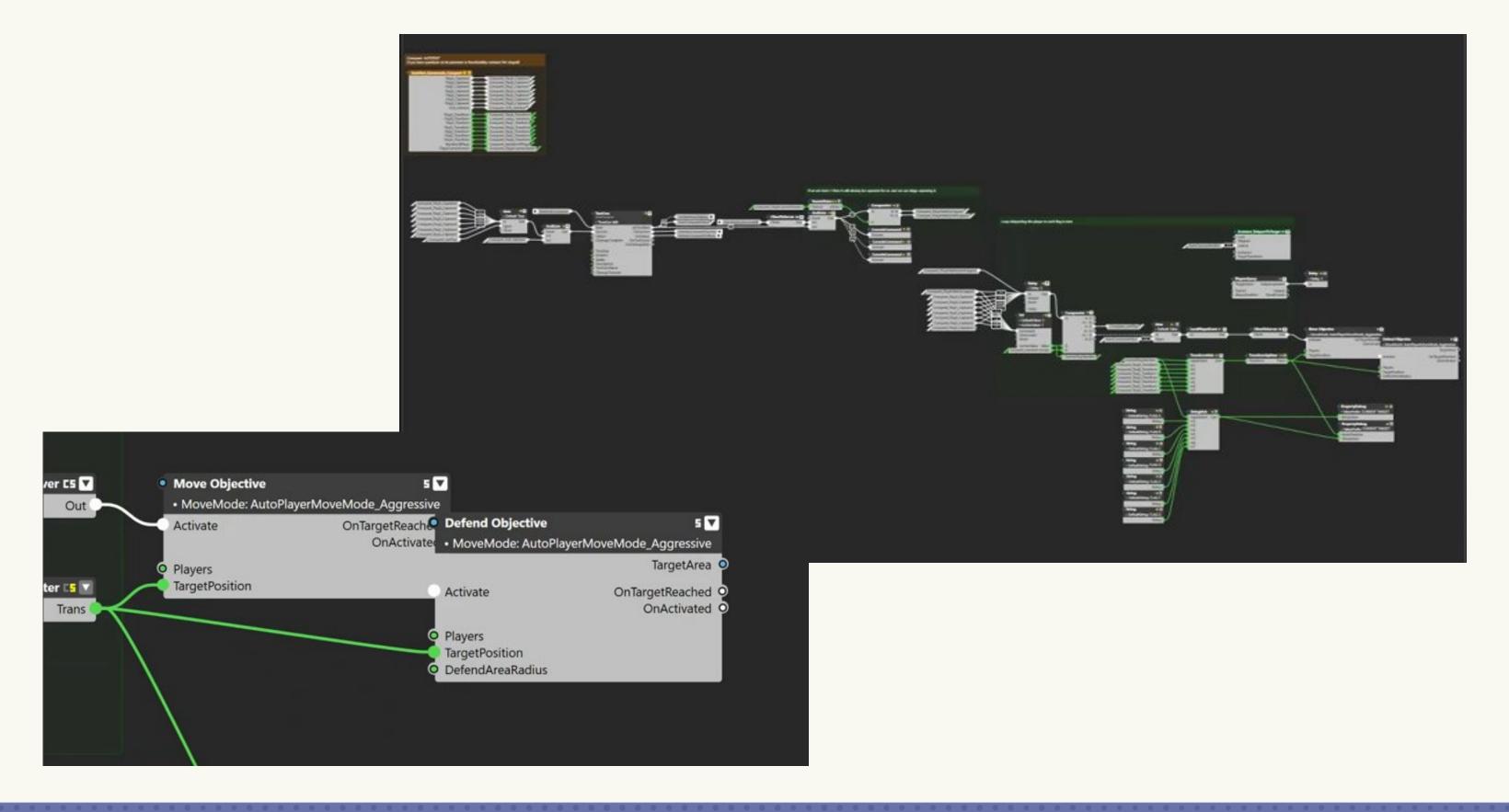


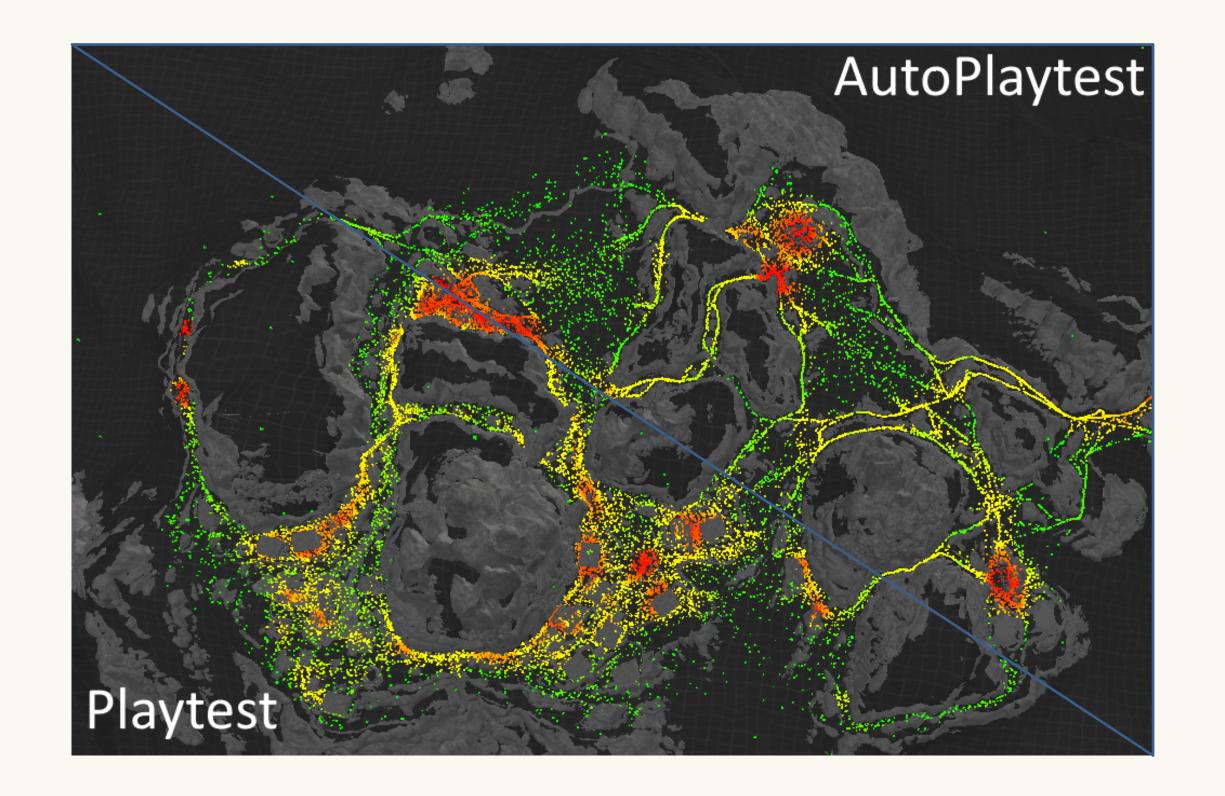




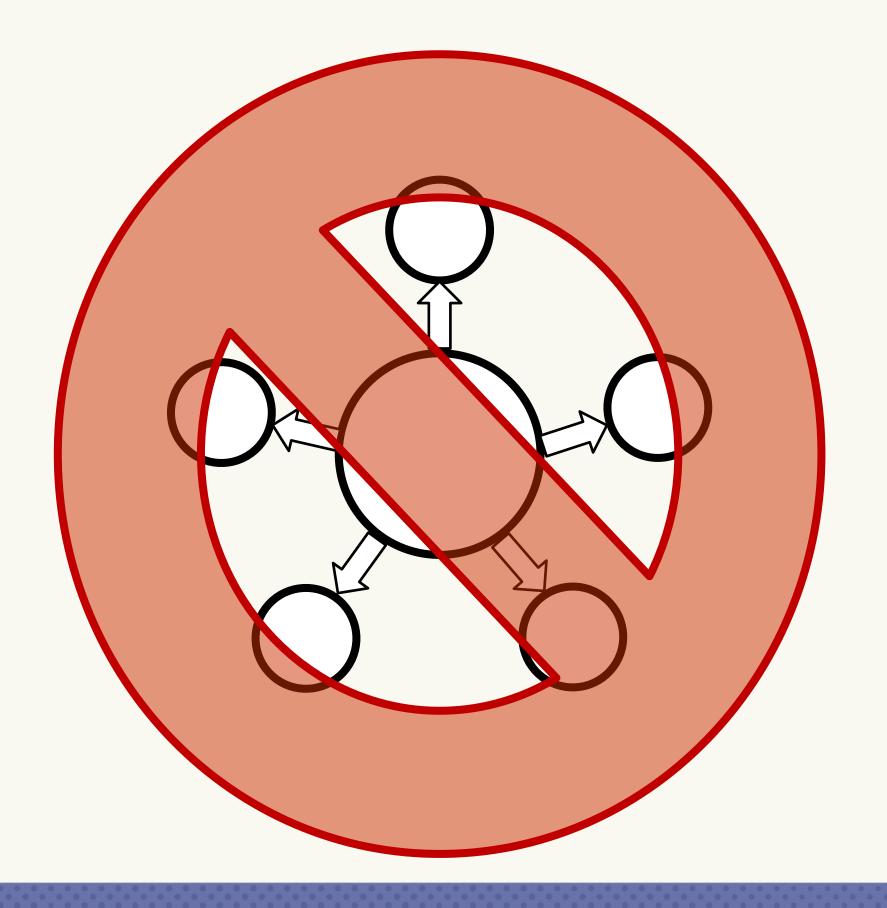


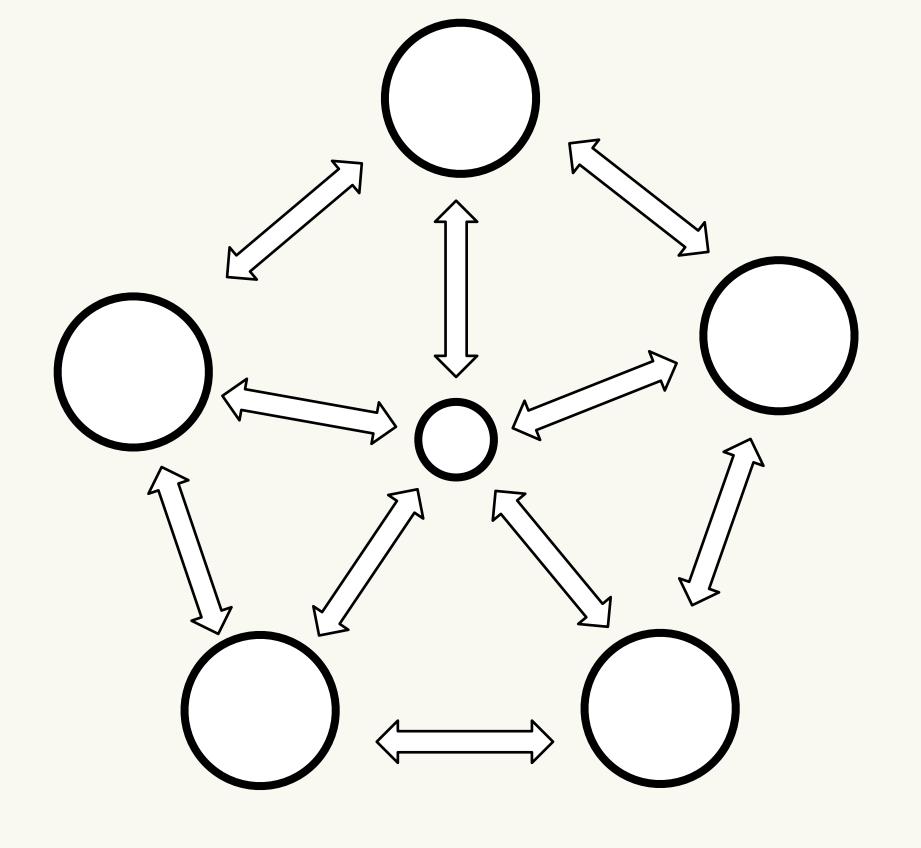


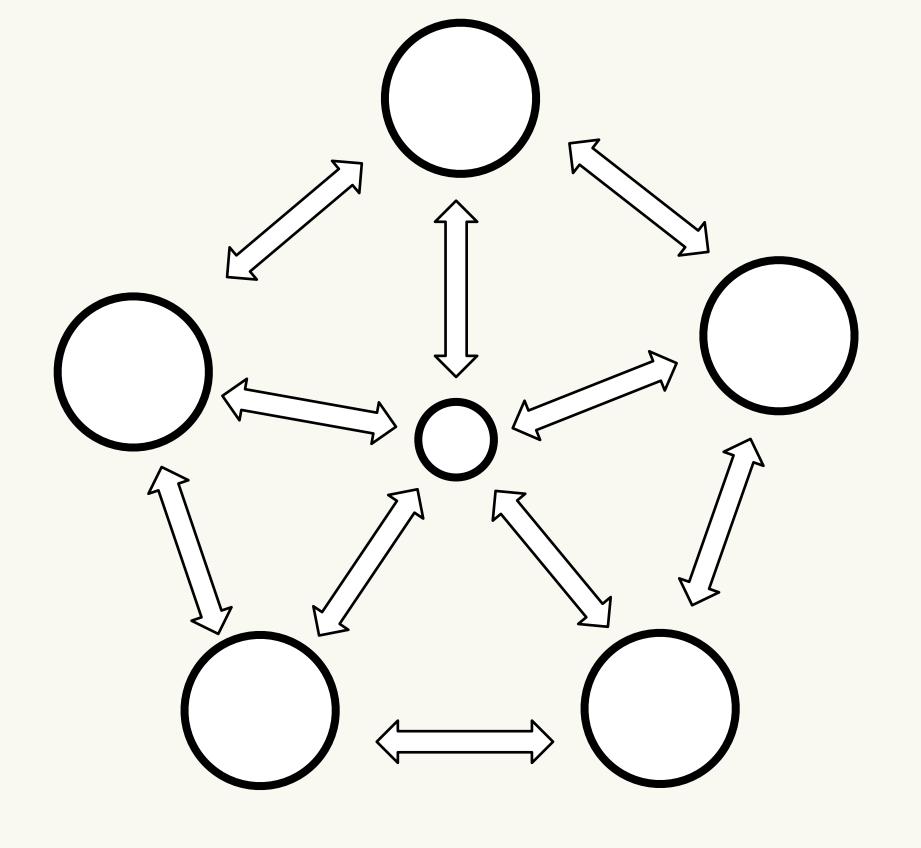


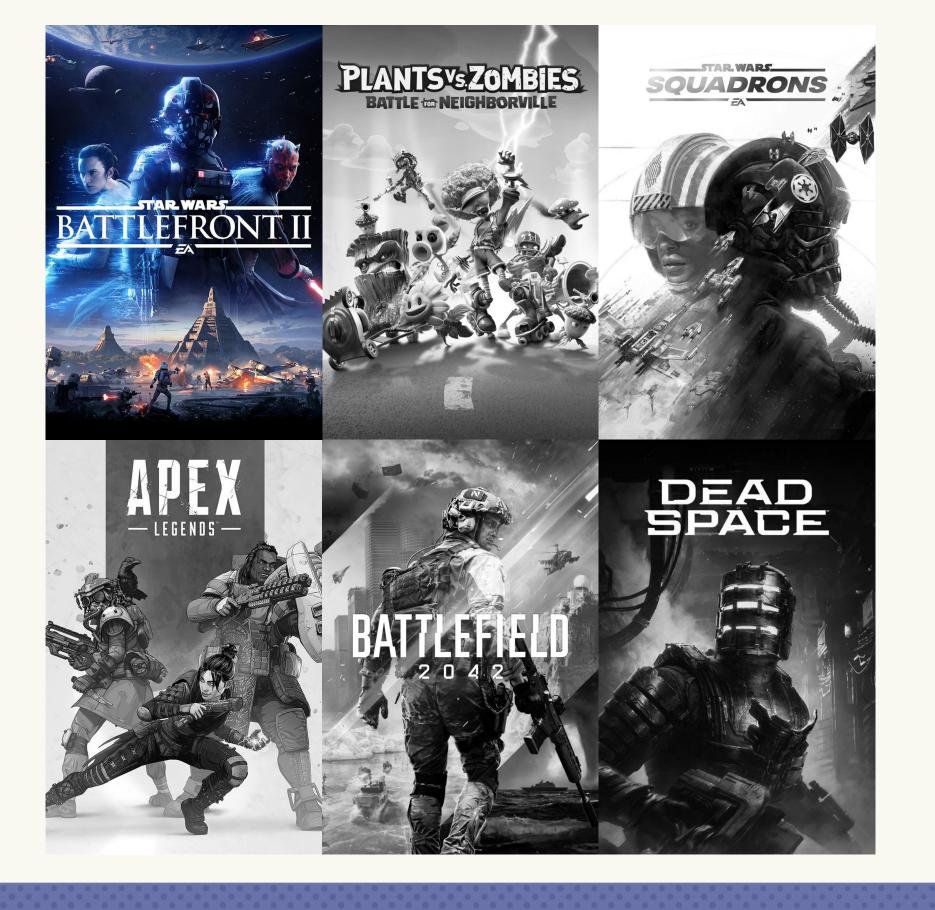










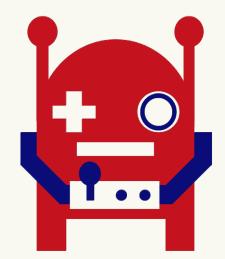


## "How Artificial Intelligence Has Evolved Star Wars Battlefront II"

https://www.ea.com/games/starwars/battlefront/star-wars-battlefront-2/news/ai-article-deep-dive



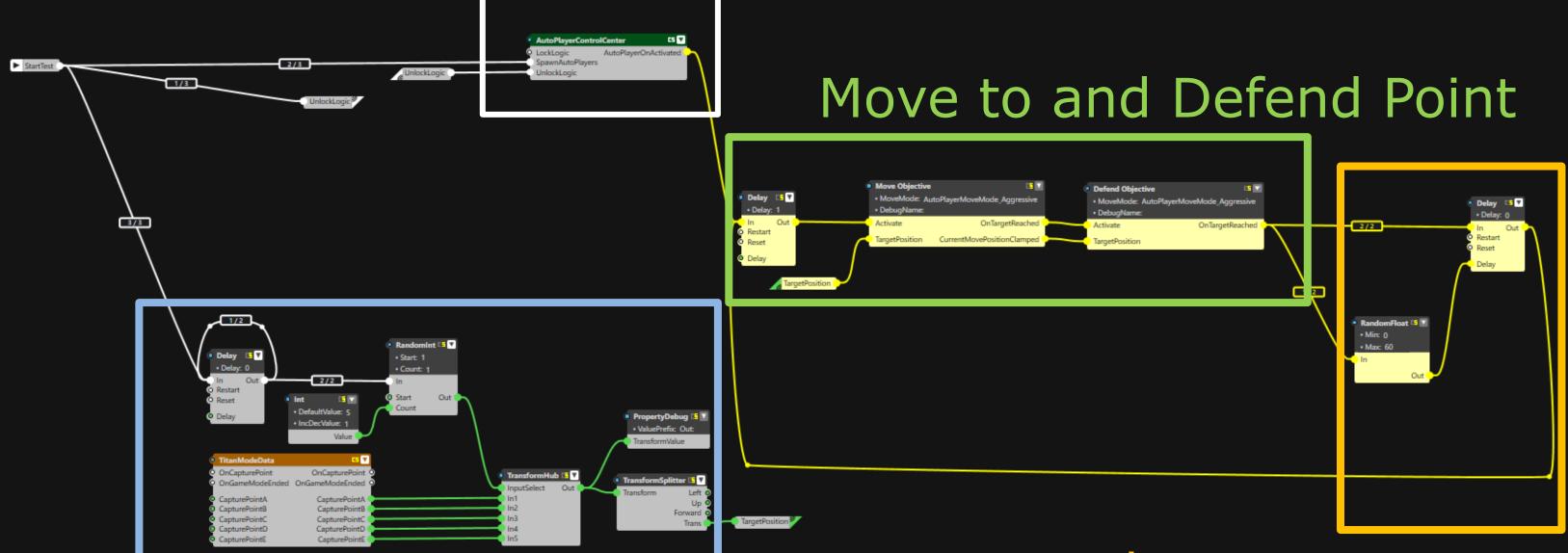






AutoPlayers Fork

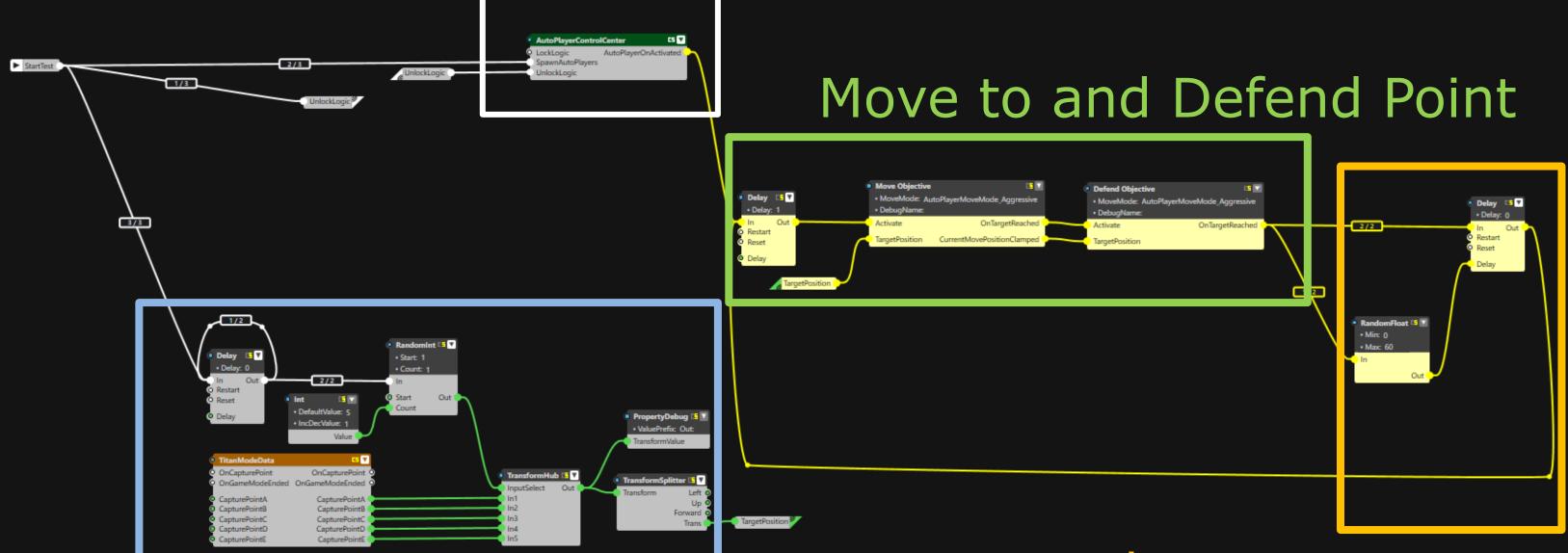
#### Trigger Per Player



Pick Control Point at random

Pick new point after random interval

#### Trigger Per Player

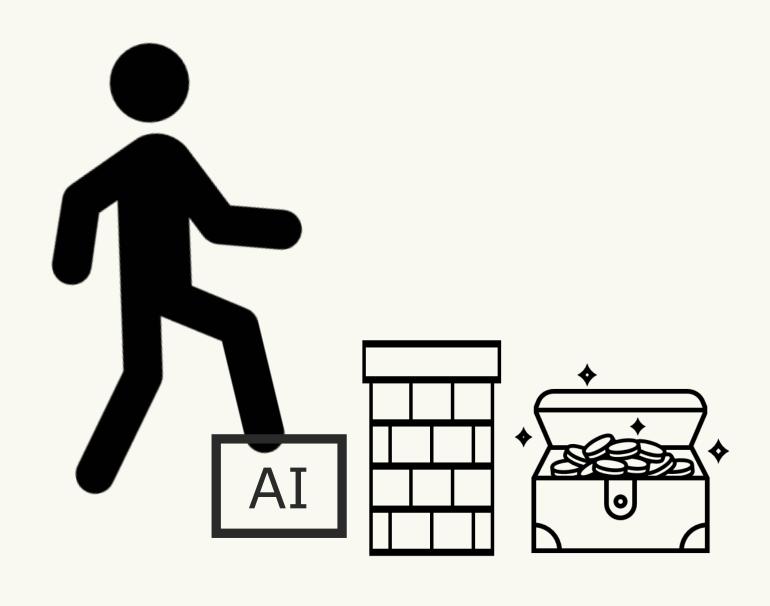


Pick Control Point at random

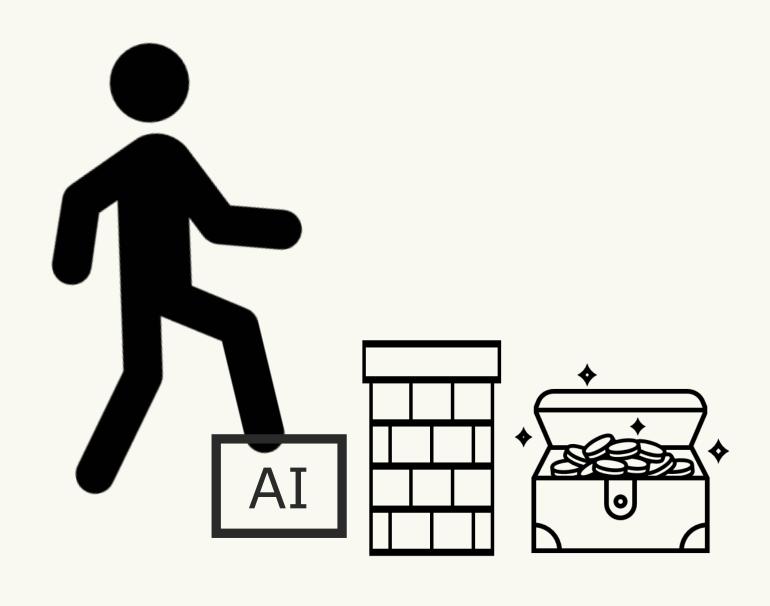
Pick new point after random interval



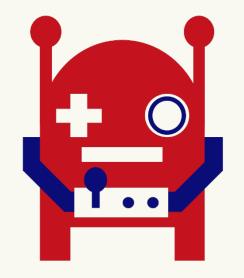












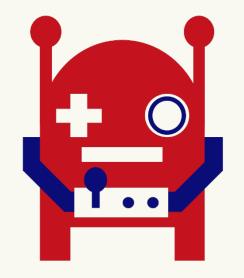




GAME CLIENT



GAME SERVER







GAME CLIENT



GAME SERVER



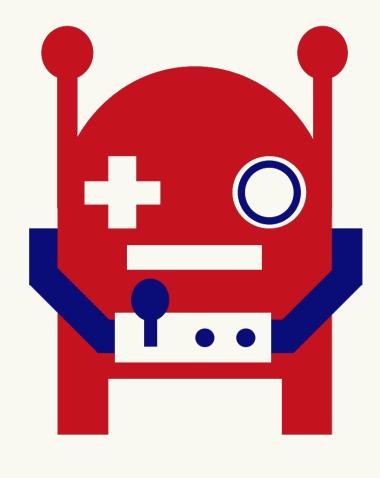
## Fan art & Positive Memes! "AutoBois"



Play The Objective

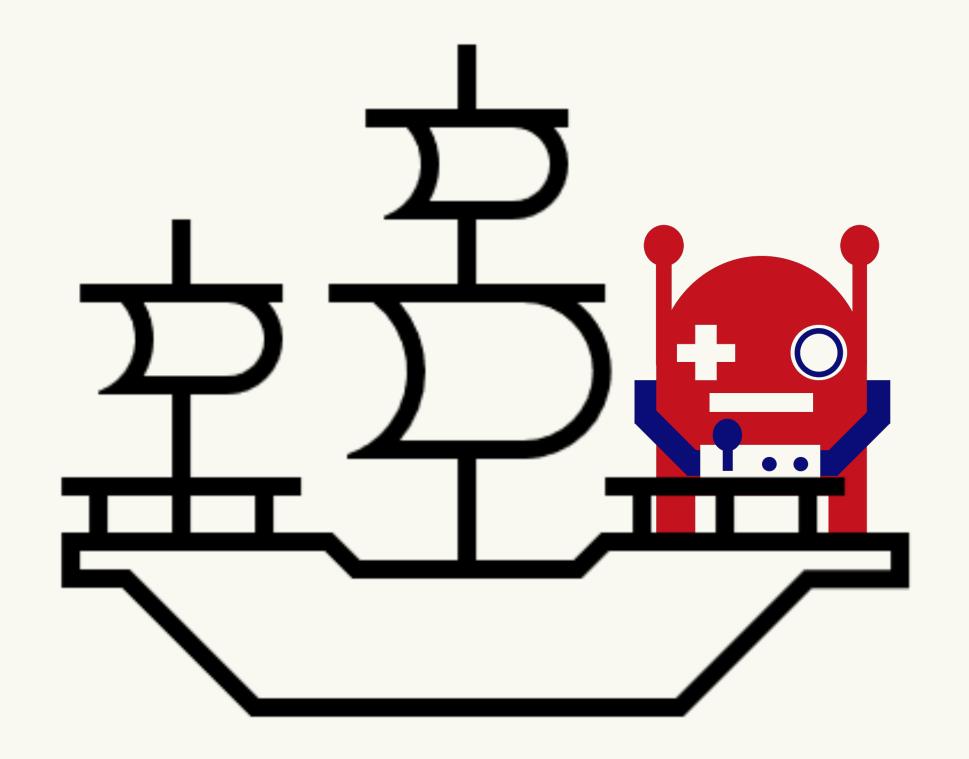


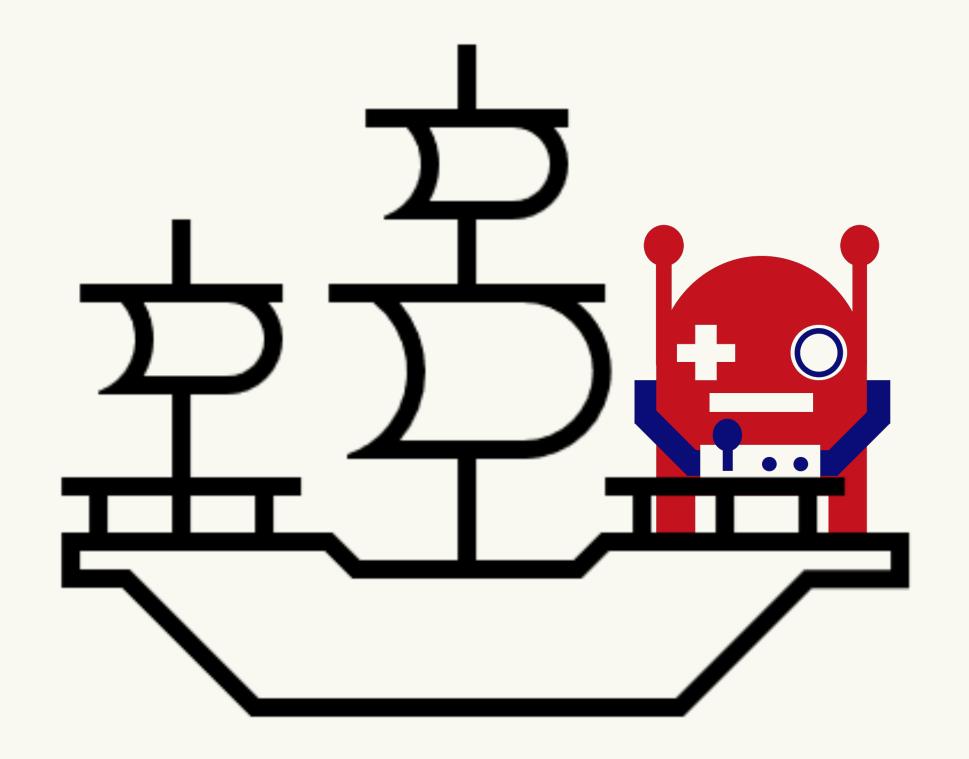




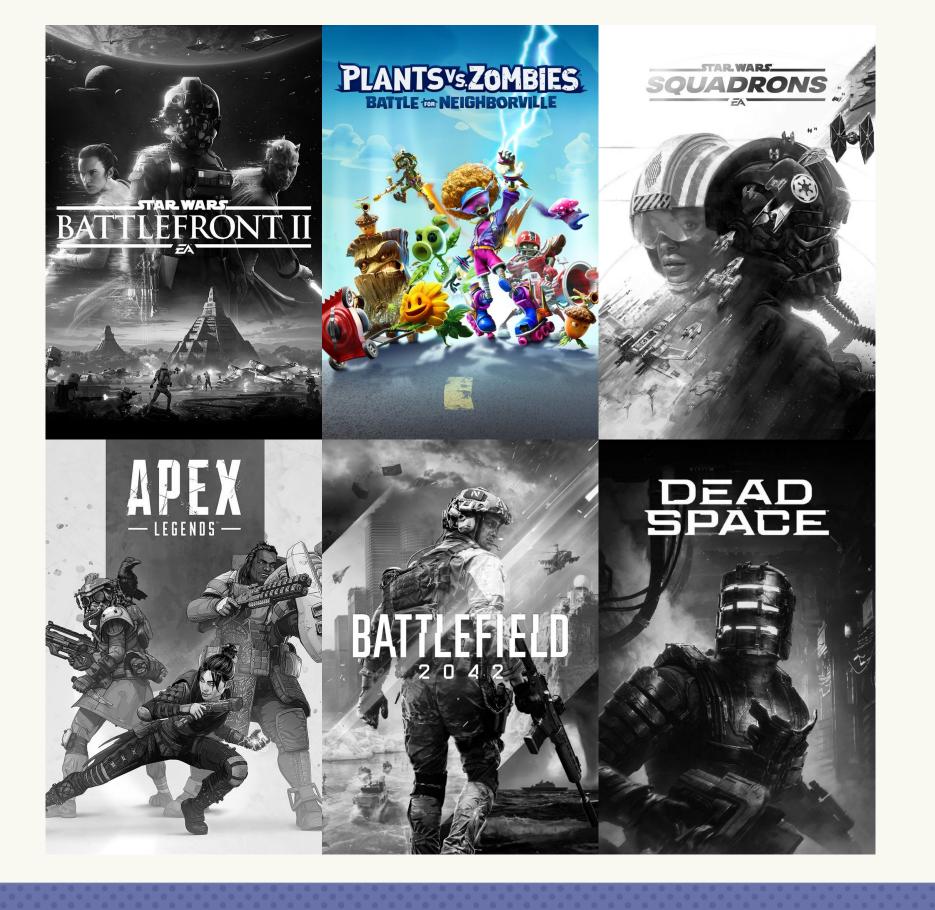




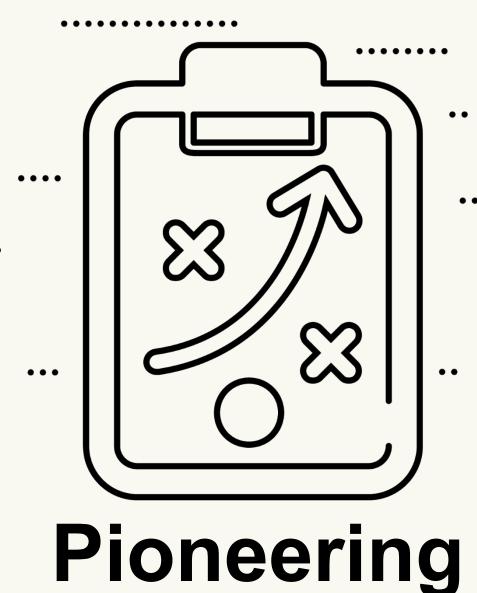








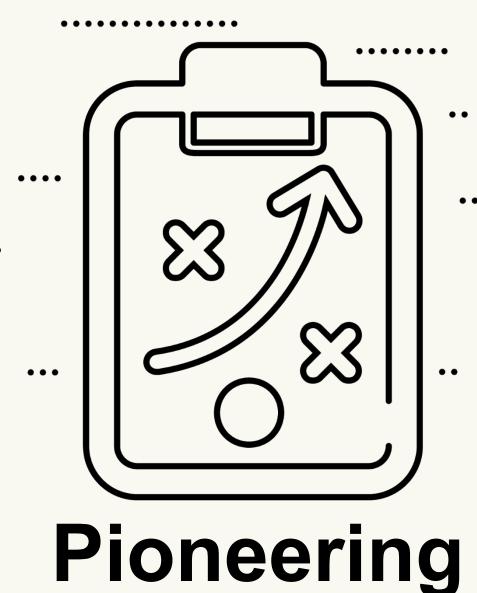






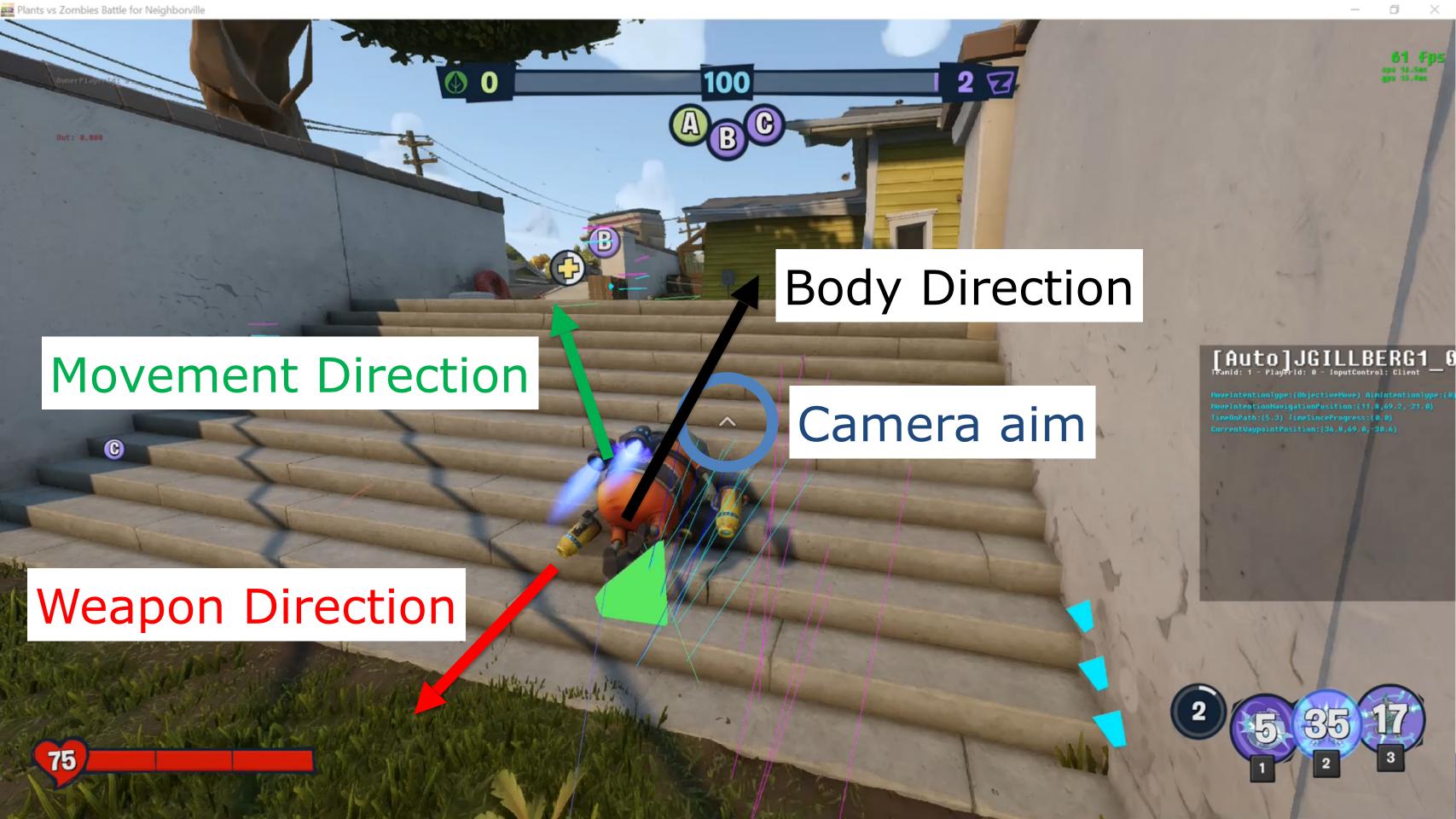




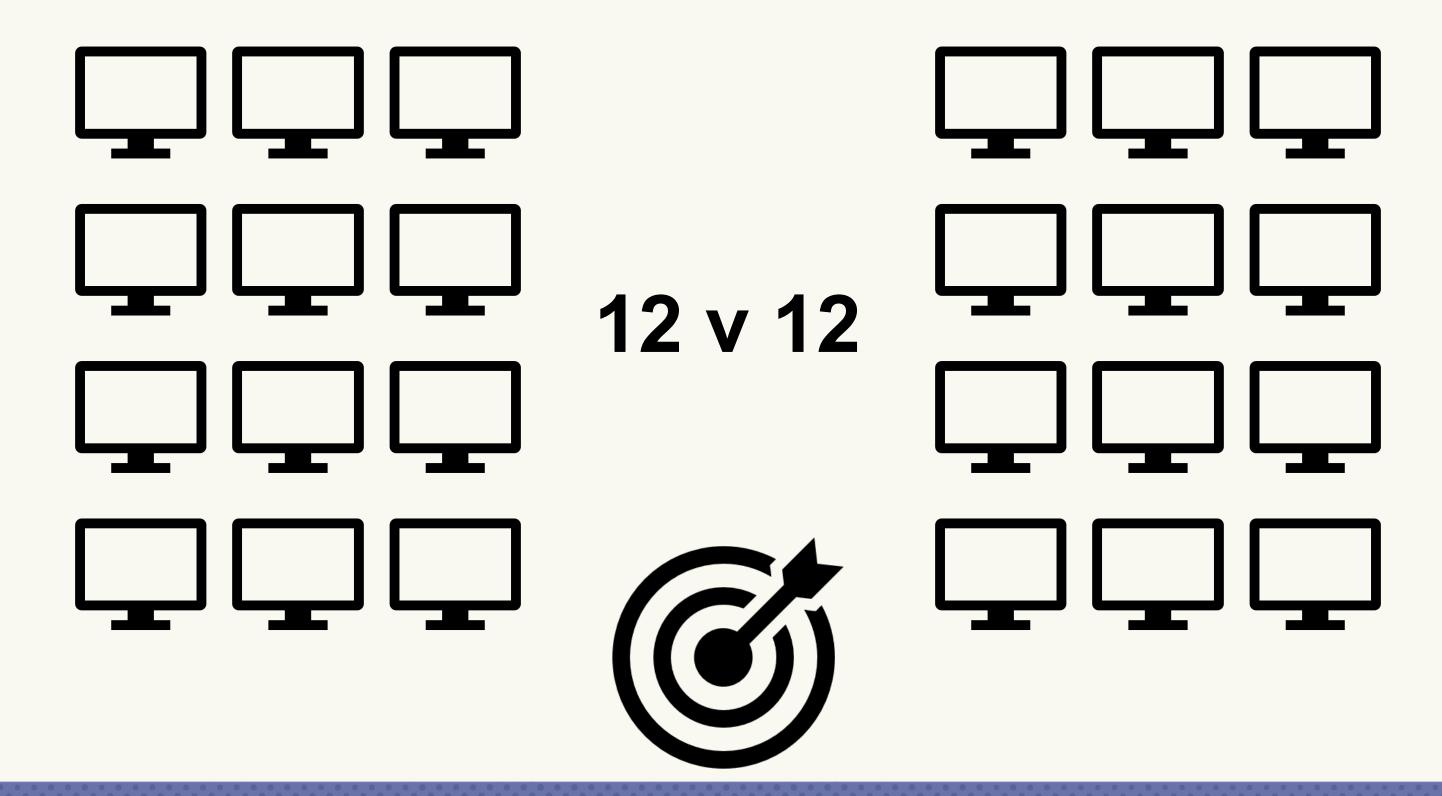


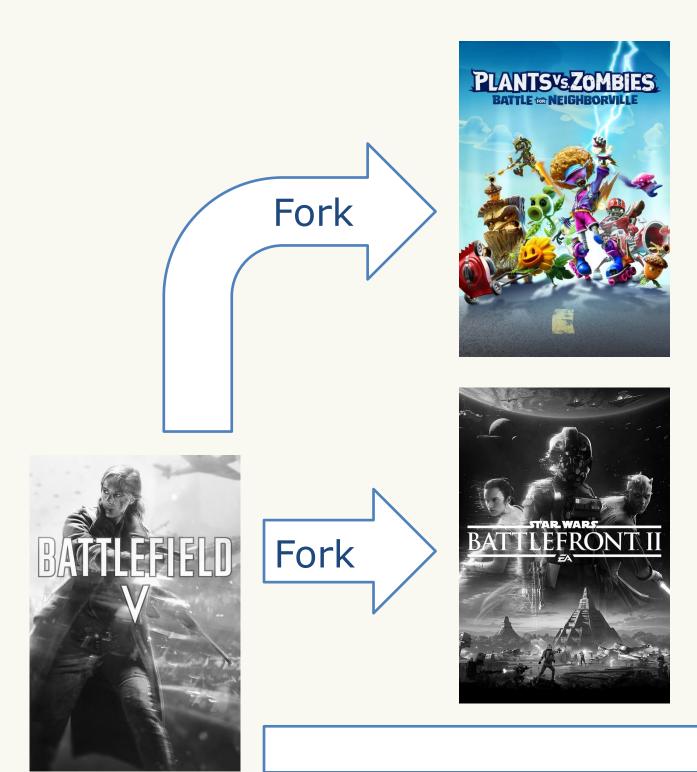








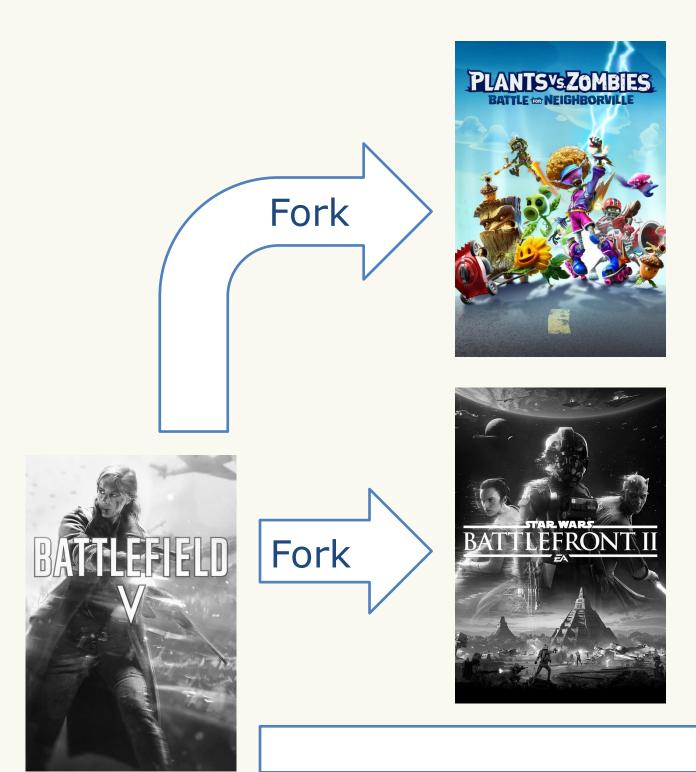




Big effort

Lessons learned

API takes shape

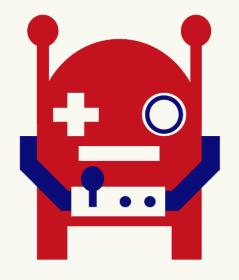


Big effort

Lessons learned

API takes shape







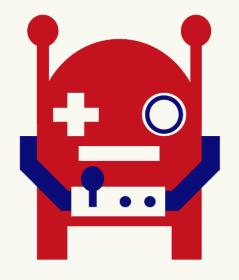


GAME CLIENT



GAME SERVER

Iteration Speed!







GAME CLIENT



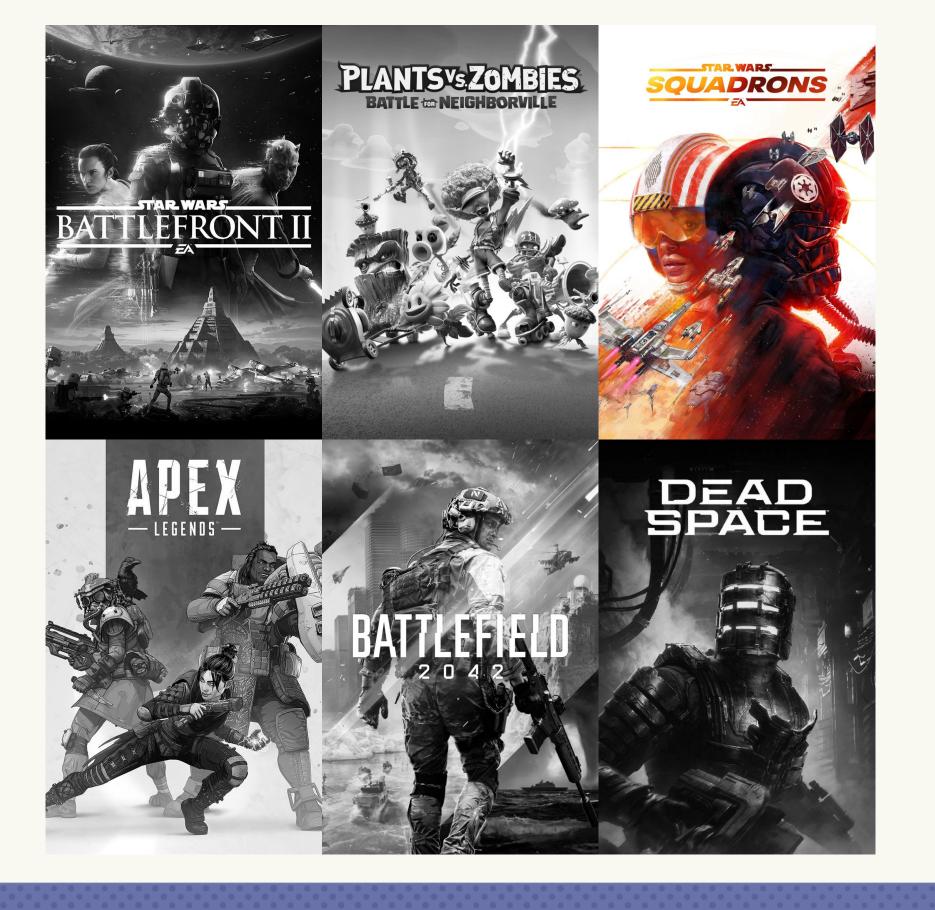
GAME SERVER

Iteration Speed!



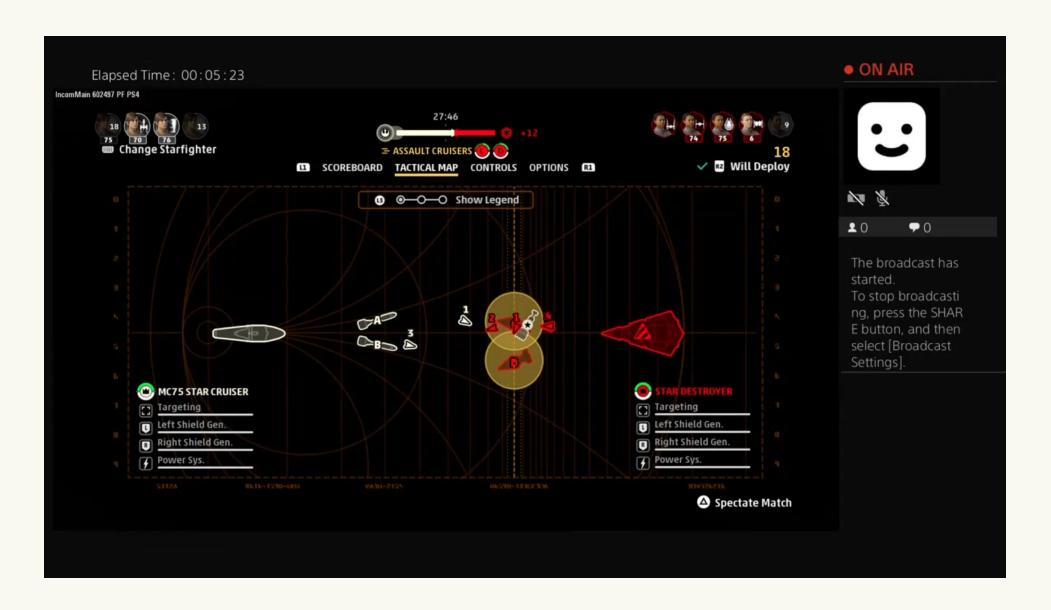






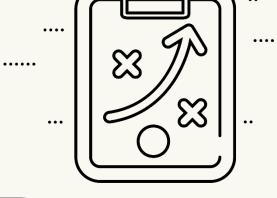


### Goals



Performance

- 5 v 5



......

PS4 VR

## Challenges

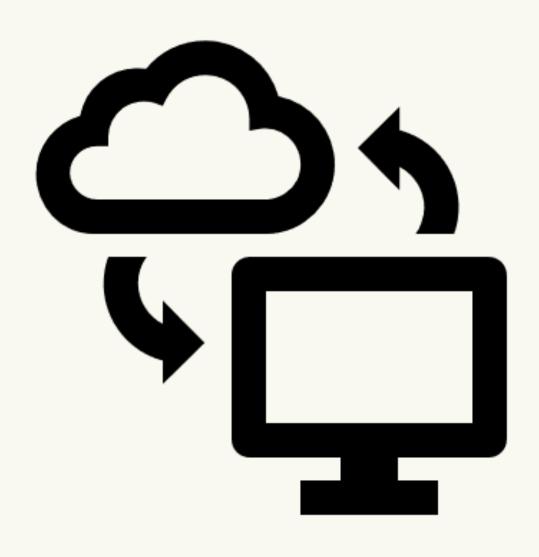
Space flight

Player Flow

Game mode



## Farm Setup, 10 kits









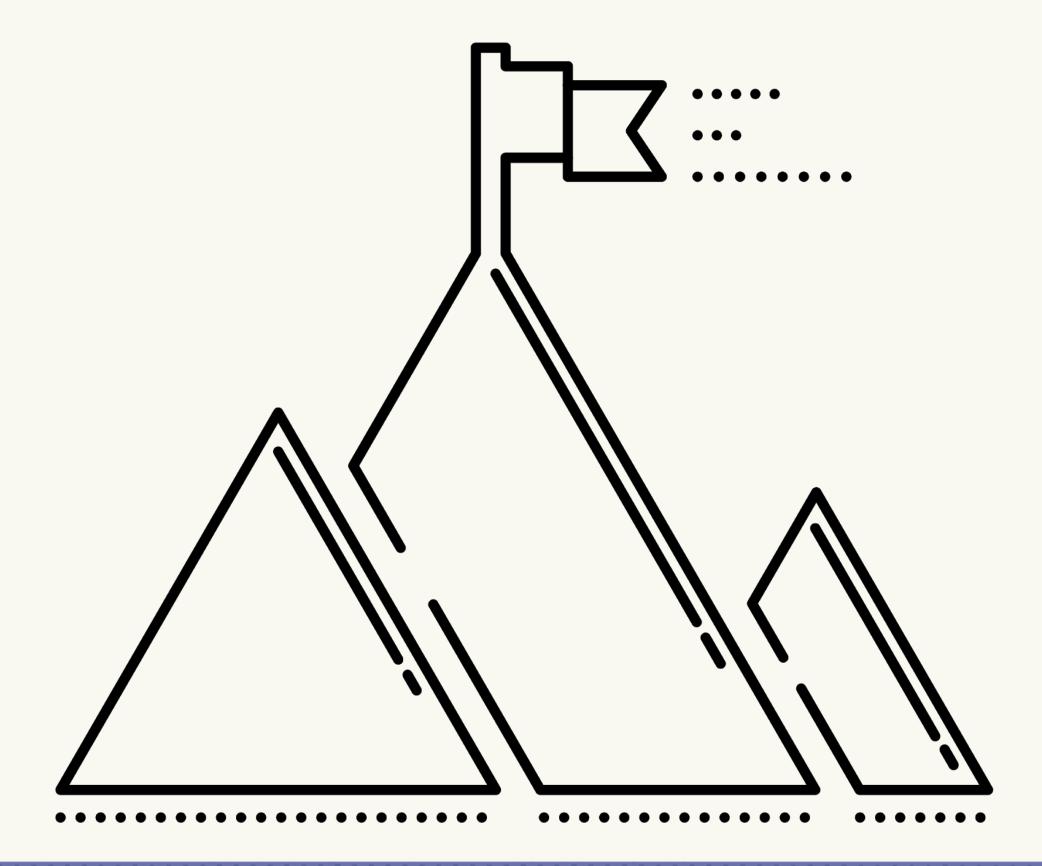
# VR Regular

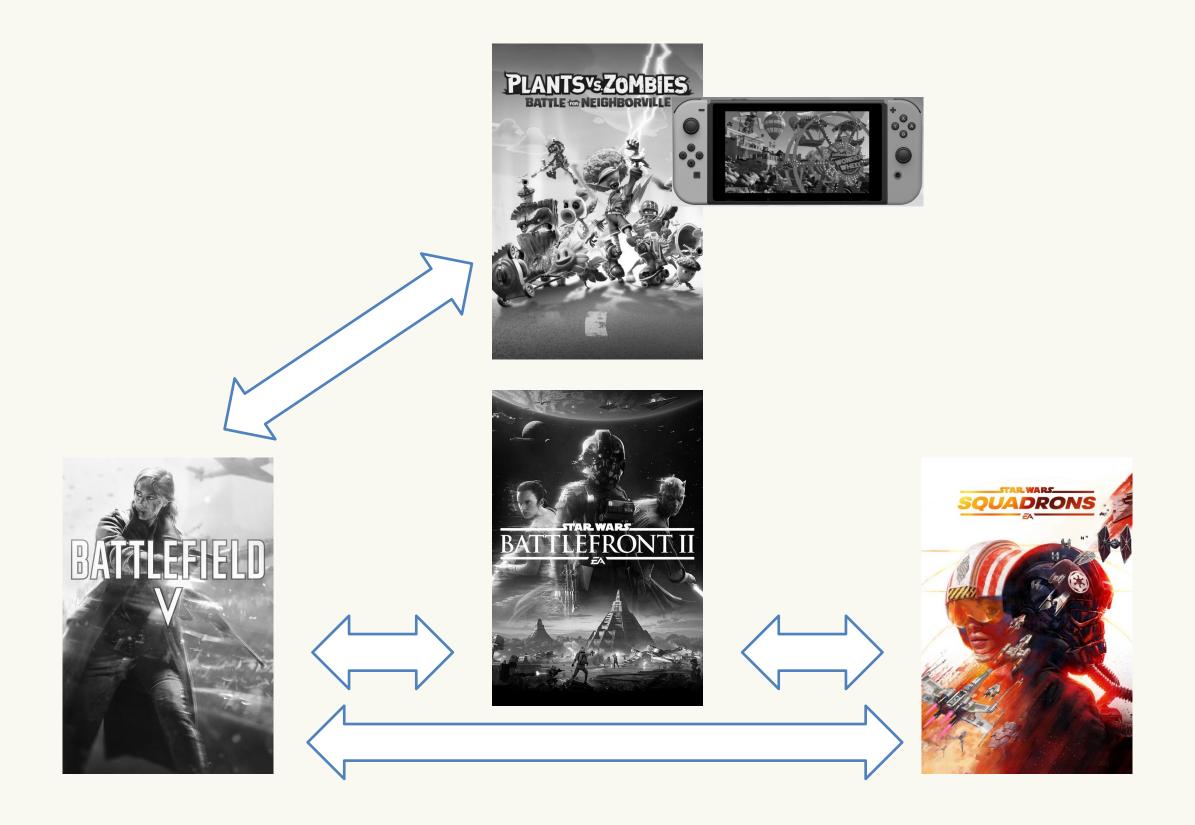












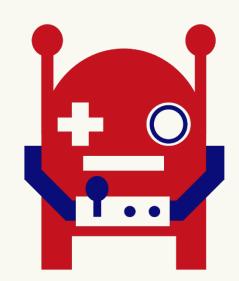








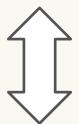




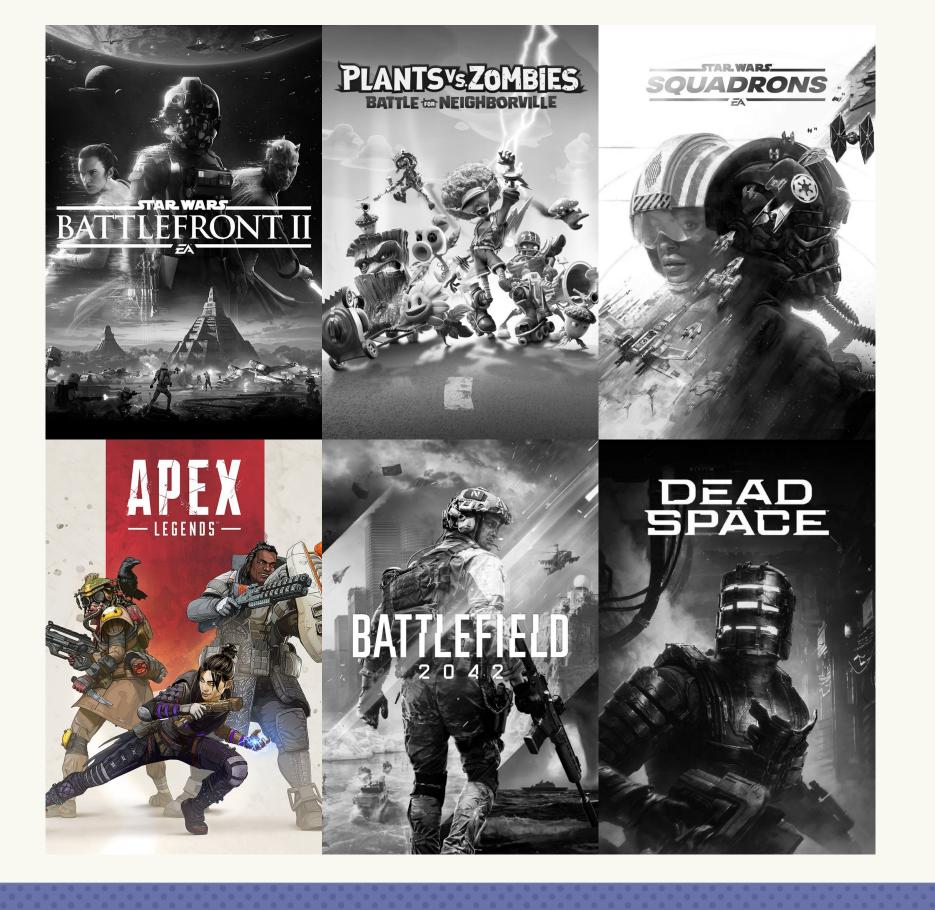


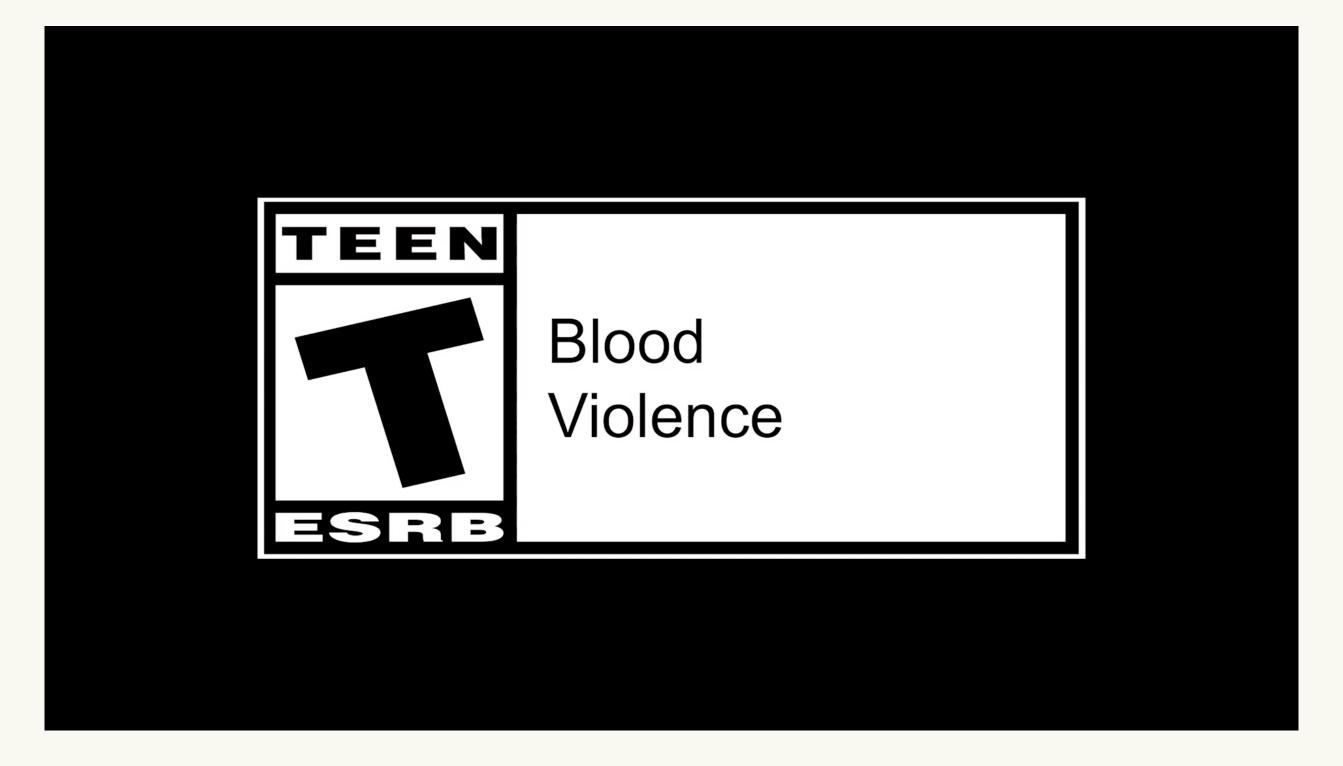


GAME CLIENT



GAME SERVER





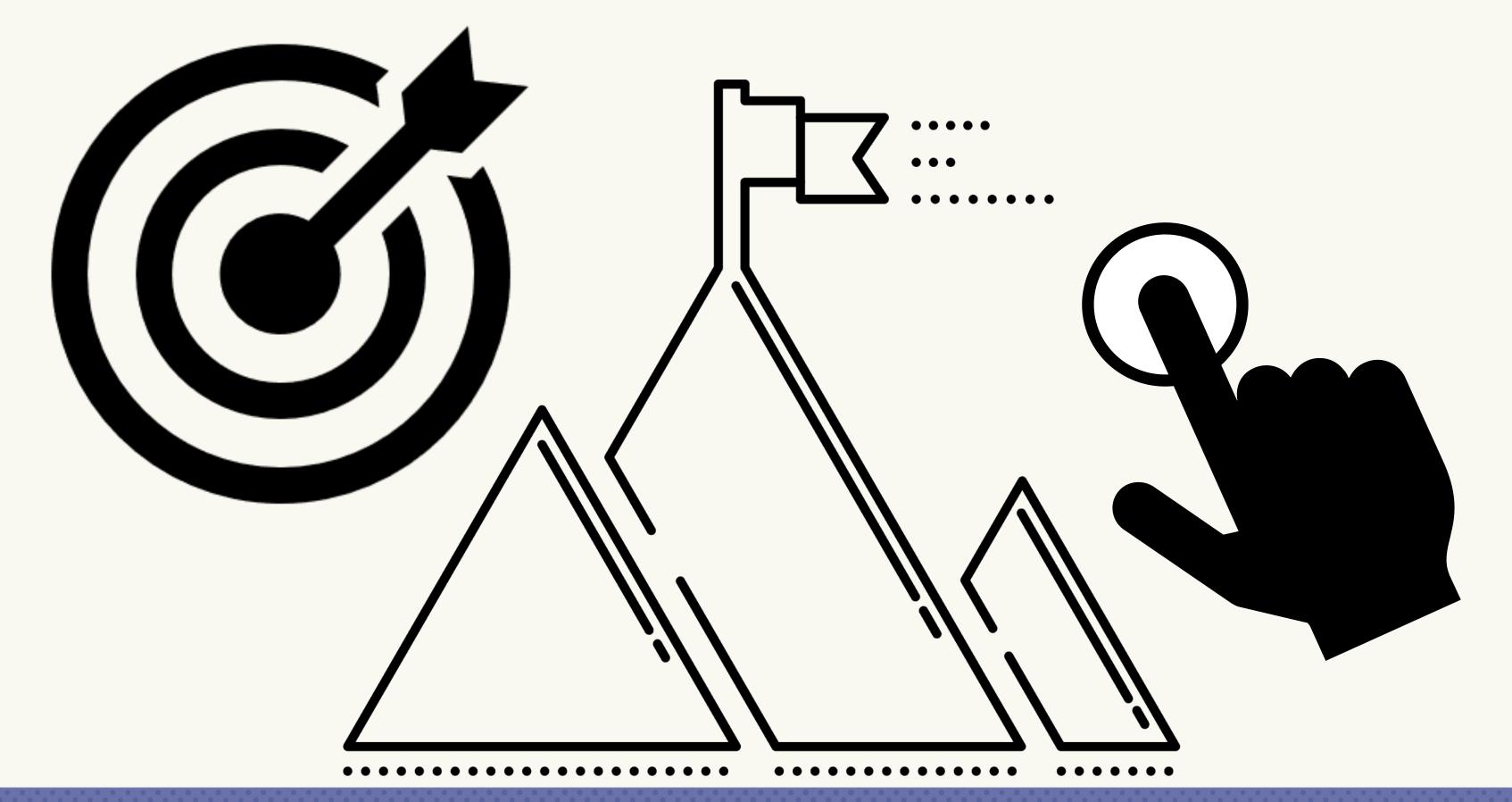
Goal: Faster QV Matchmaking

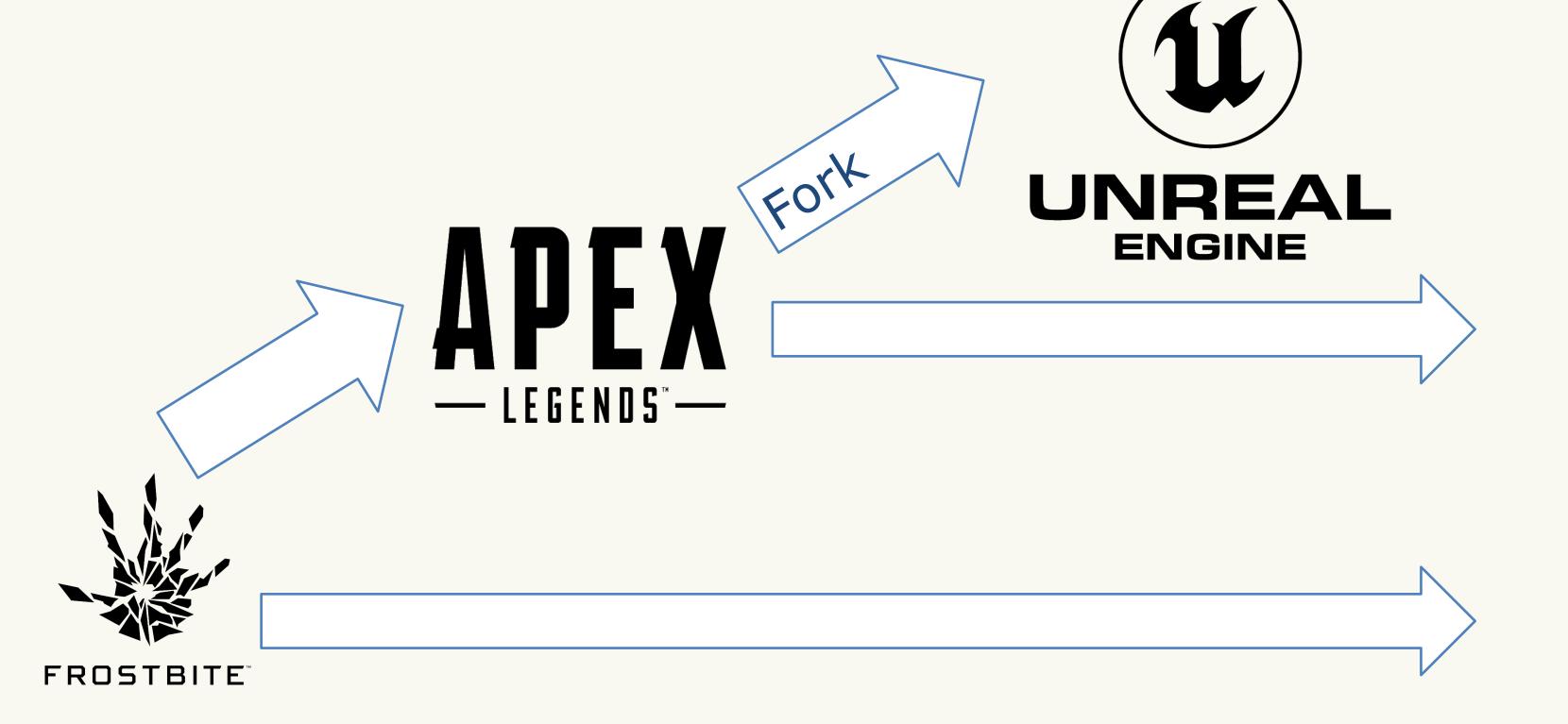


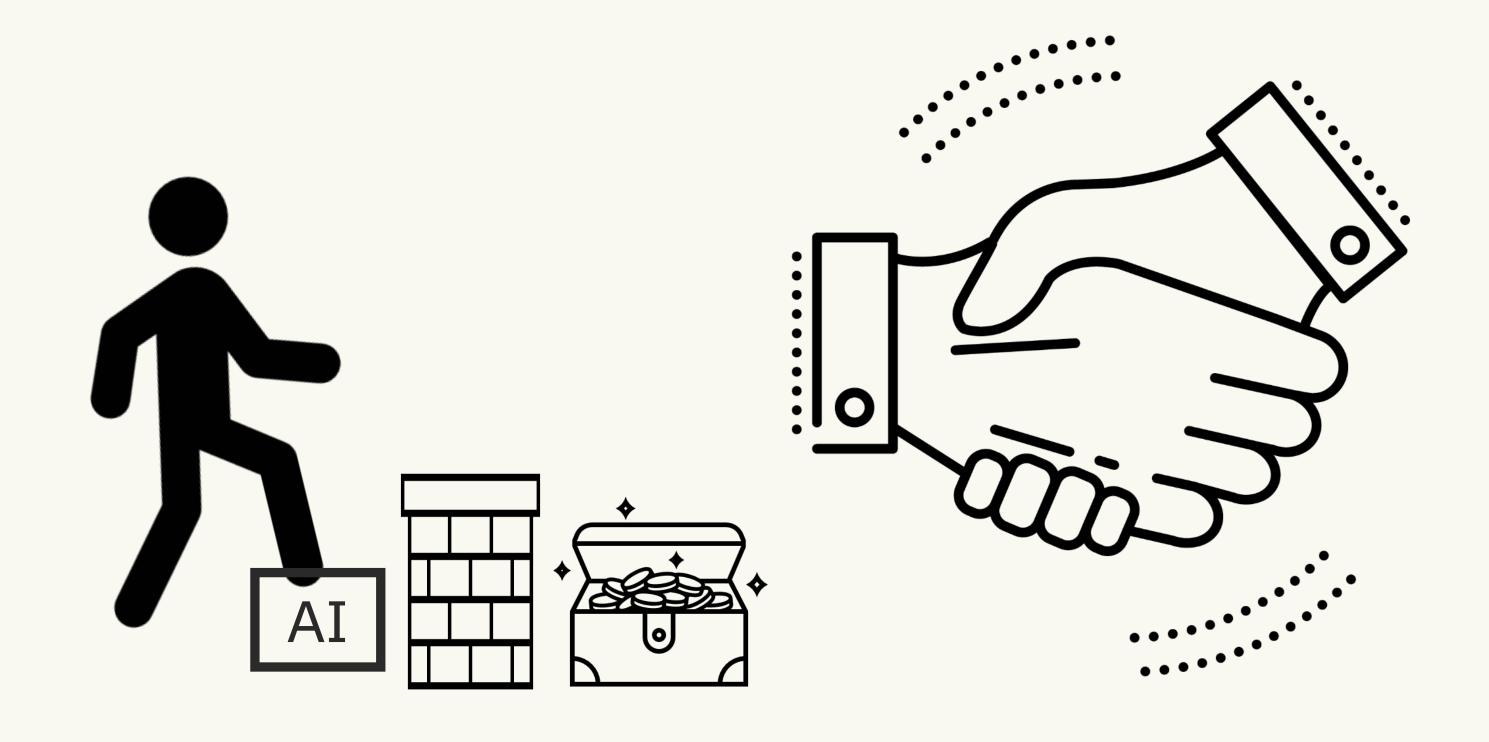












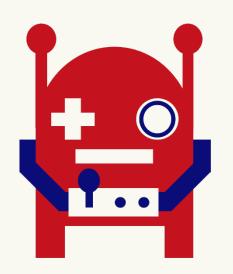




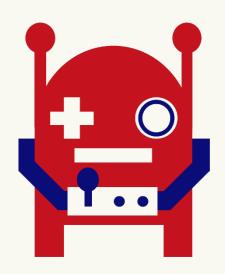








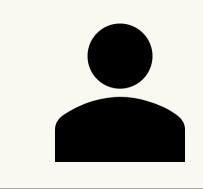












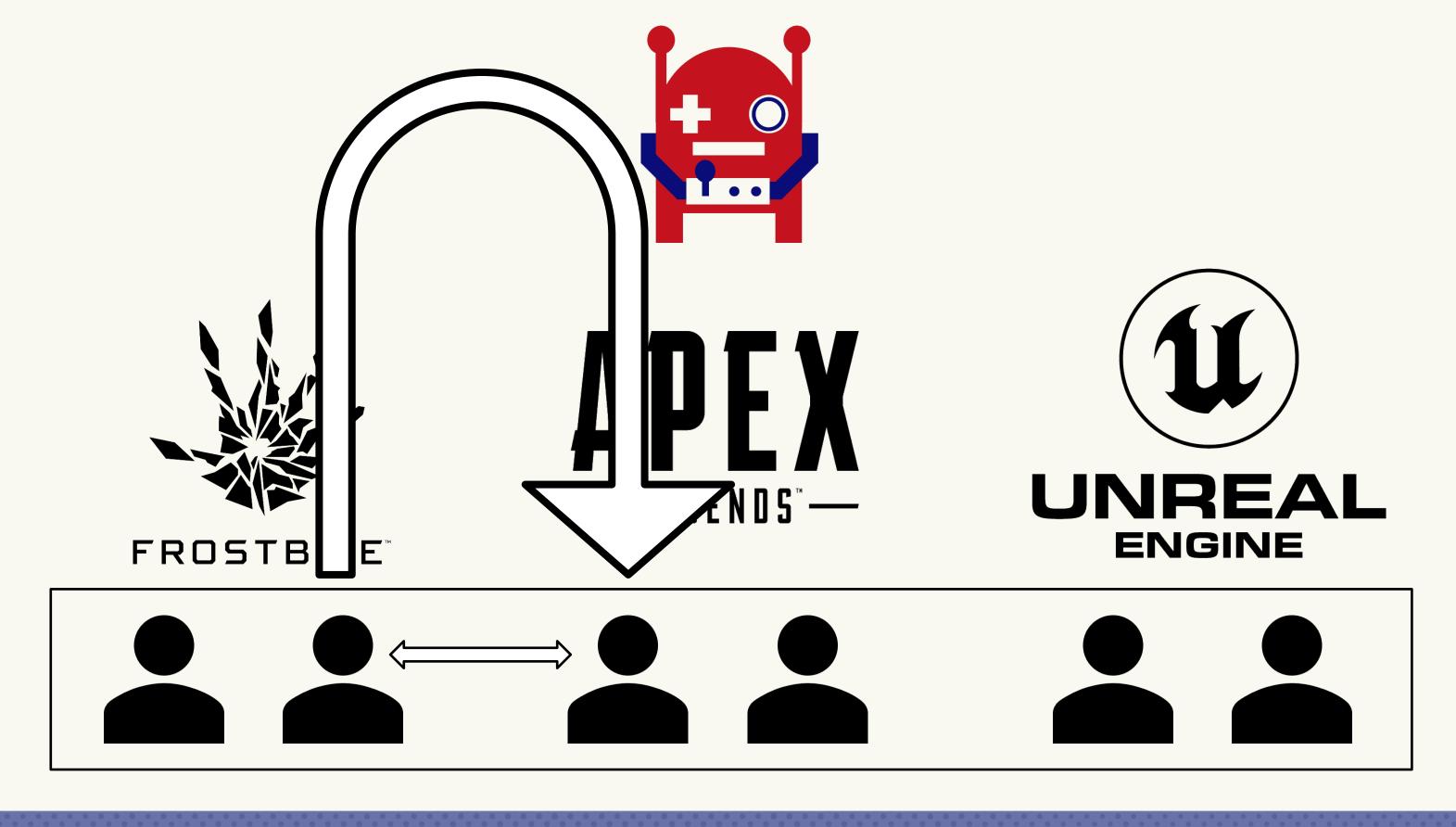


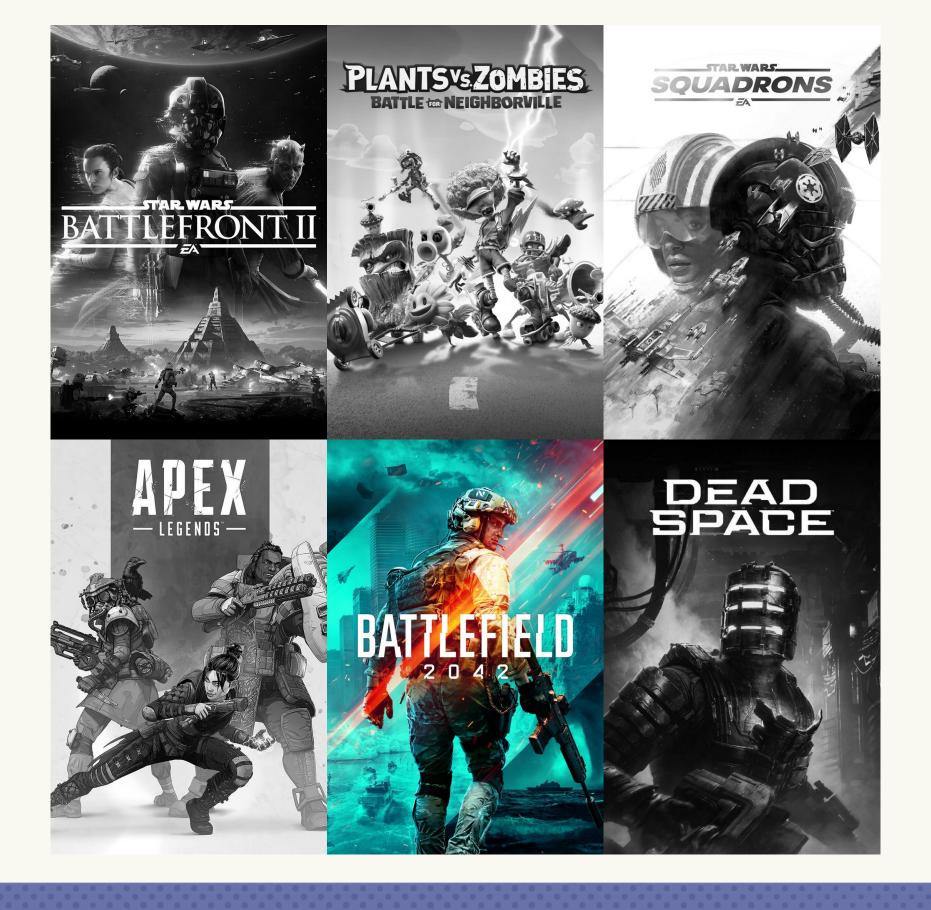














Reinforcement Learning

Trial n Error

Rewards

Millions of iterations



## Explore RL





## Explore RL

Real Problem

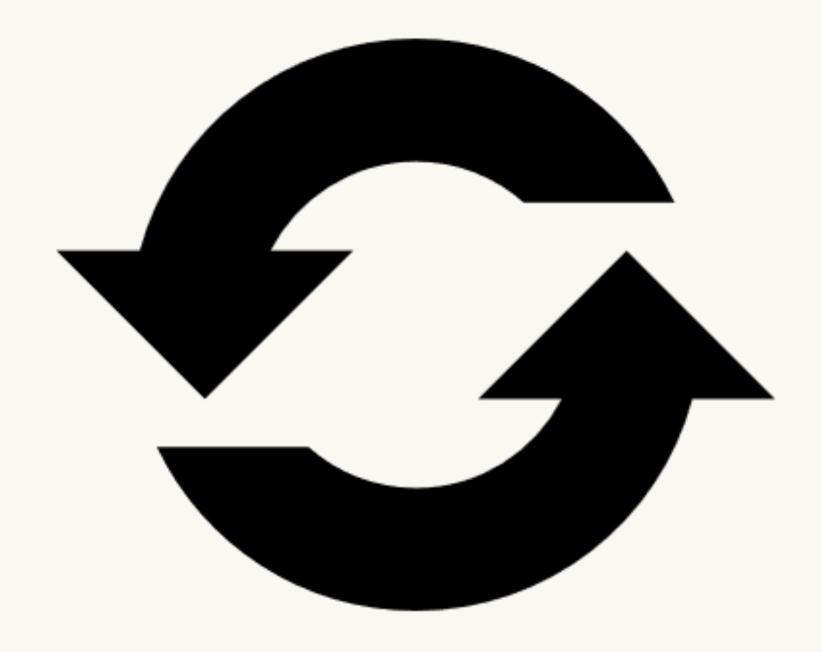


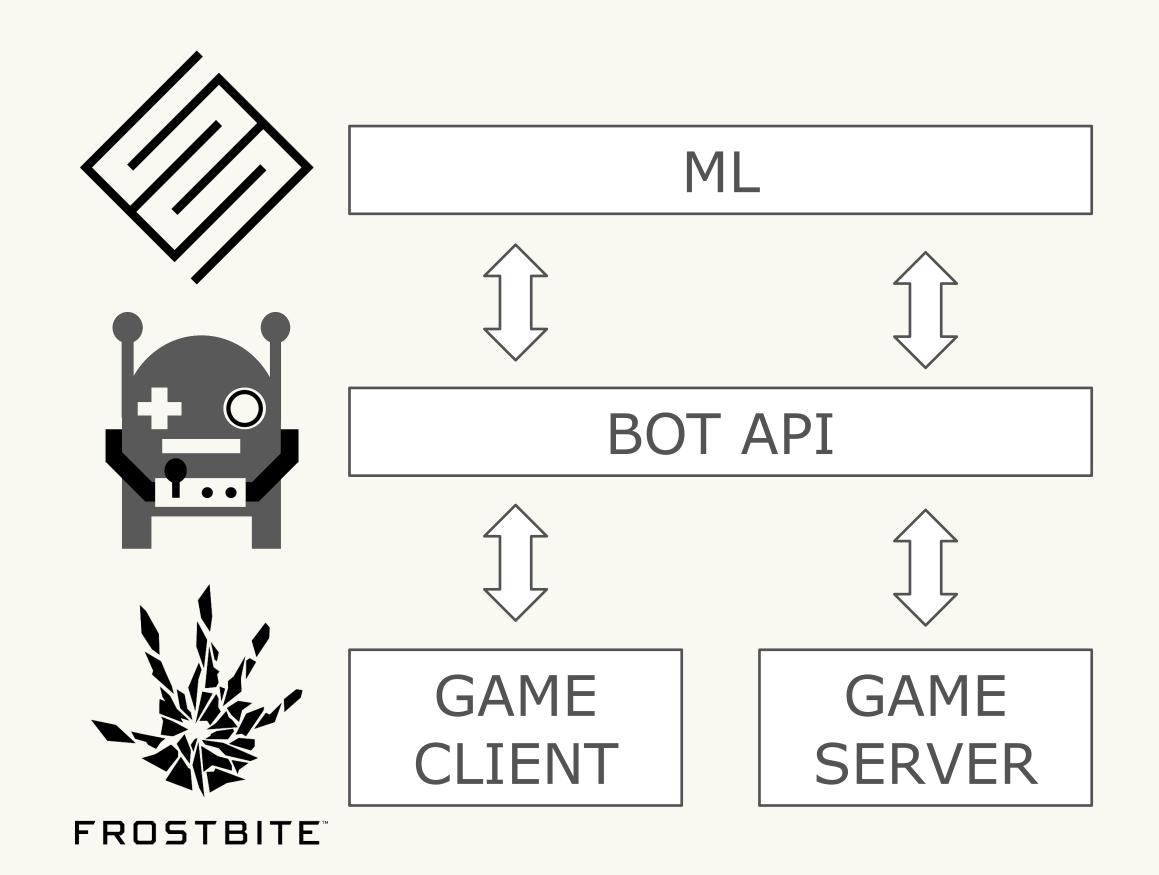


Explore RL

Real Problem

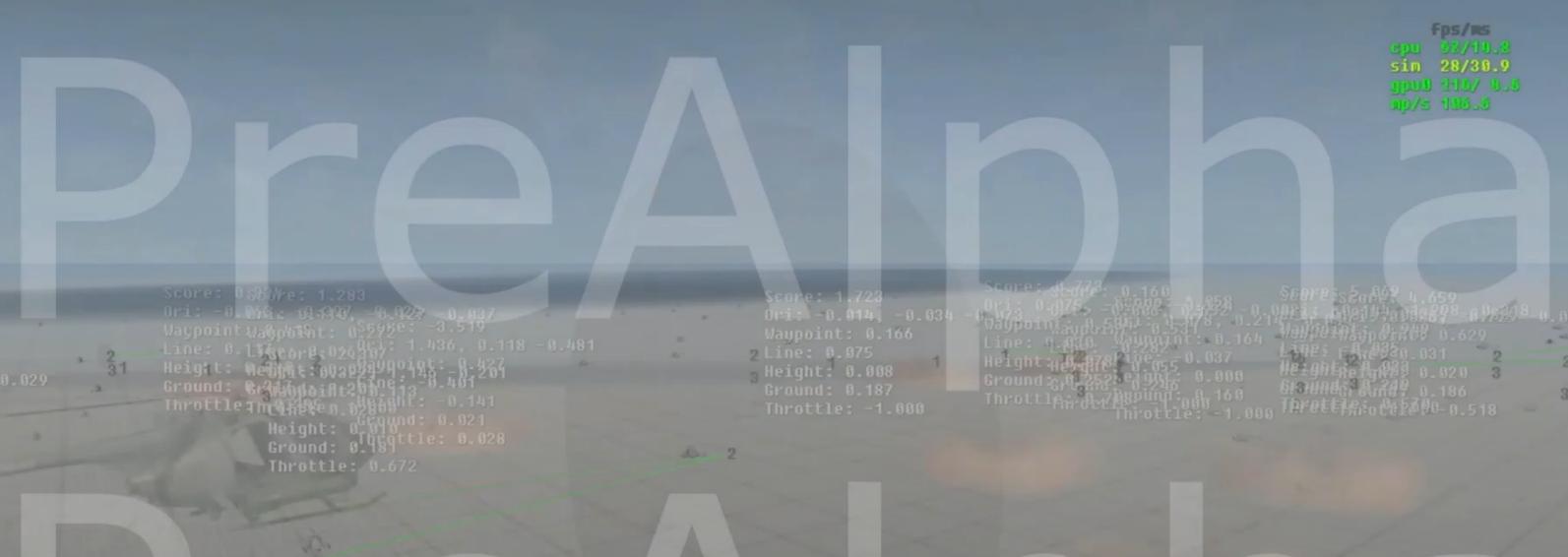
Major Changes





- Single Machine
- 250 Helicopters
- 5 Game Servers
- 10M Steps/Hour
- ~5 Hours training





## PreAlpha















TeamId: 1 - PlayerId: 0 - GameTime: 45.6% ObjectiveControl(Remote) - PathfindingControl(Remote) isAllowedToUseNavmesh(True) ObjectiveType:(Himic) Priority:(Primary) ObjectiveDebugName:() ObjectiveNoveNode:(Defensive) TimeInObjective: (44.9) ObjectiveDoneTimer: (8.8) ObjectiveState: [11](-19.06,109.85,370.66) d:4.44 t:7.18 ObjectivePosition: (0.0,0.0,0.0) CurrentPosition:(-28.3,118.4,366.4) HoveIntentionType:(ObjectiveHove) AimIntentionType:(0) MoveIntentionNavigationPosition:(-19.1,189.9,378.7) ObstacleAvoidanceSensorLenght:(2.0) TimeOnPath:(1.5) TimeSinceProgress:(0.0) TimeOutCorr(0.0) CurrentWaypointPosition:(-19.2,118.4,370.8) isInfantryStuckProcedureActive:(0)

## [Auto]CBINDEA1 TeamId: 1 - PlayerId: 0 - GameTime: 45.88 ObjectiveControl(Remote) - PathfindingControl(Remote) isAllowedToUseNavmesh(True) ObjectiveType:(Mimic) Priority:(Primary) ObjectiveDebugName:() ObjectiveMoveMode:(Defensive) TimeInObjective: (45.8) ObjectiveDoneTimer: (0.0) ObjectiveState: [11](-19.06,109.85,370.66) d:1.85 t:6.0 ObjectivePosition:(0.0,0.0,0.0) CurrentPosition:(-19.6,110.8,368.9) MoveIntentionType:(ObjectiveMove) AimIntentionType:(0) MoveIntentionNavigationPosition:(-19.1,109.9,370.7) ObstacleAvoidanceSensorLenght:(2.0) TimeOnPath:(1.9) TimeSinceProgress:(0.0) TimeOutCorr(0.0) CurrentWaypointPosition:(-19.1,109.9,370.7) isInfantryStuckProcedureActive:(0) | Nuclear Nucl



ObjectiveControl(Remote) - PathFindingControl(Remote) isAllowedToUseNavmesh(True) ObjectiveType:(Mimic) Priority:(Primary) ObjectiveDebugHame:() ObjectiveHoveHode:(Defensive) TimeInObjective:(44.8) ObjectiveDoneTimer:(0.8)

ObjectiveState: [11](-19.06,109.85,370.66) d:2.32 t:7.09 ObjectivePosition: (0.0,0.8,0.0)

CurrentPosition:(-19.8,118.1,368.5)

MoveIntentionType:(ObjectiveMove) AimIntentionType:(0)

HoveIntentionNavigationPosition:(-19.1,109.9,370.7)

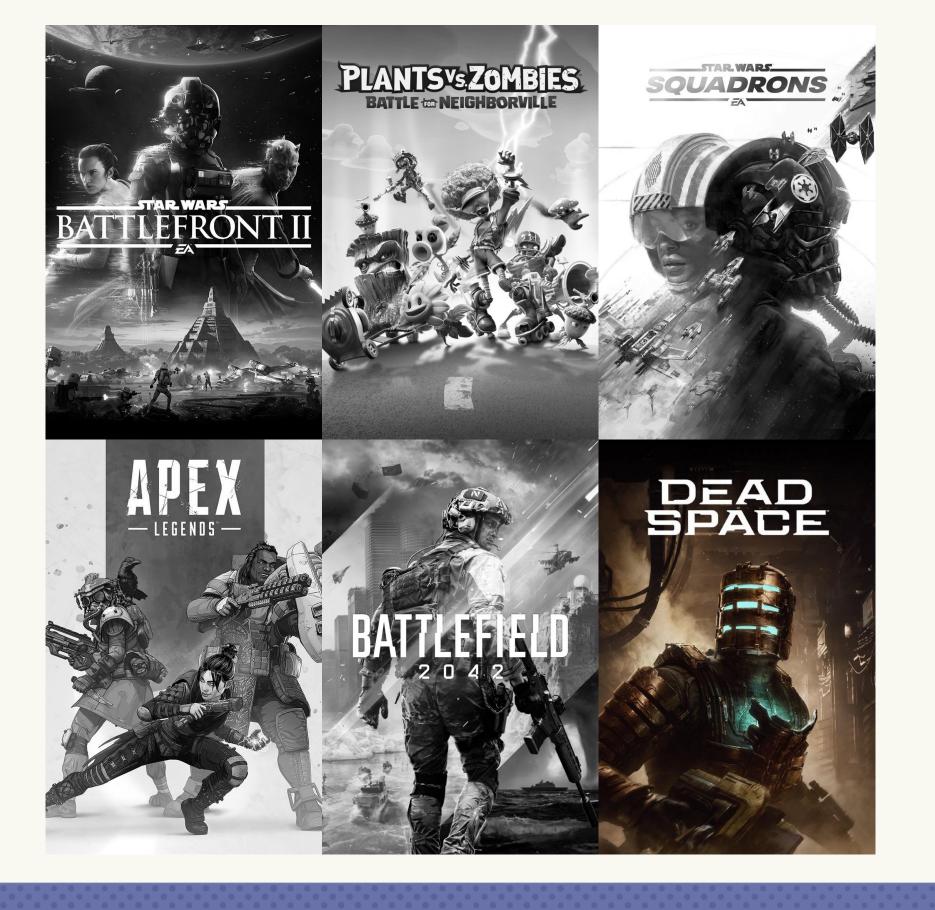
ObstacleAvoidanceSensorLenght:(2.0)

TimeOnPath:(1.8) TimeSinceProgress:(0.0) TimeOutCorr(0.0)

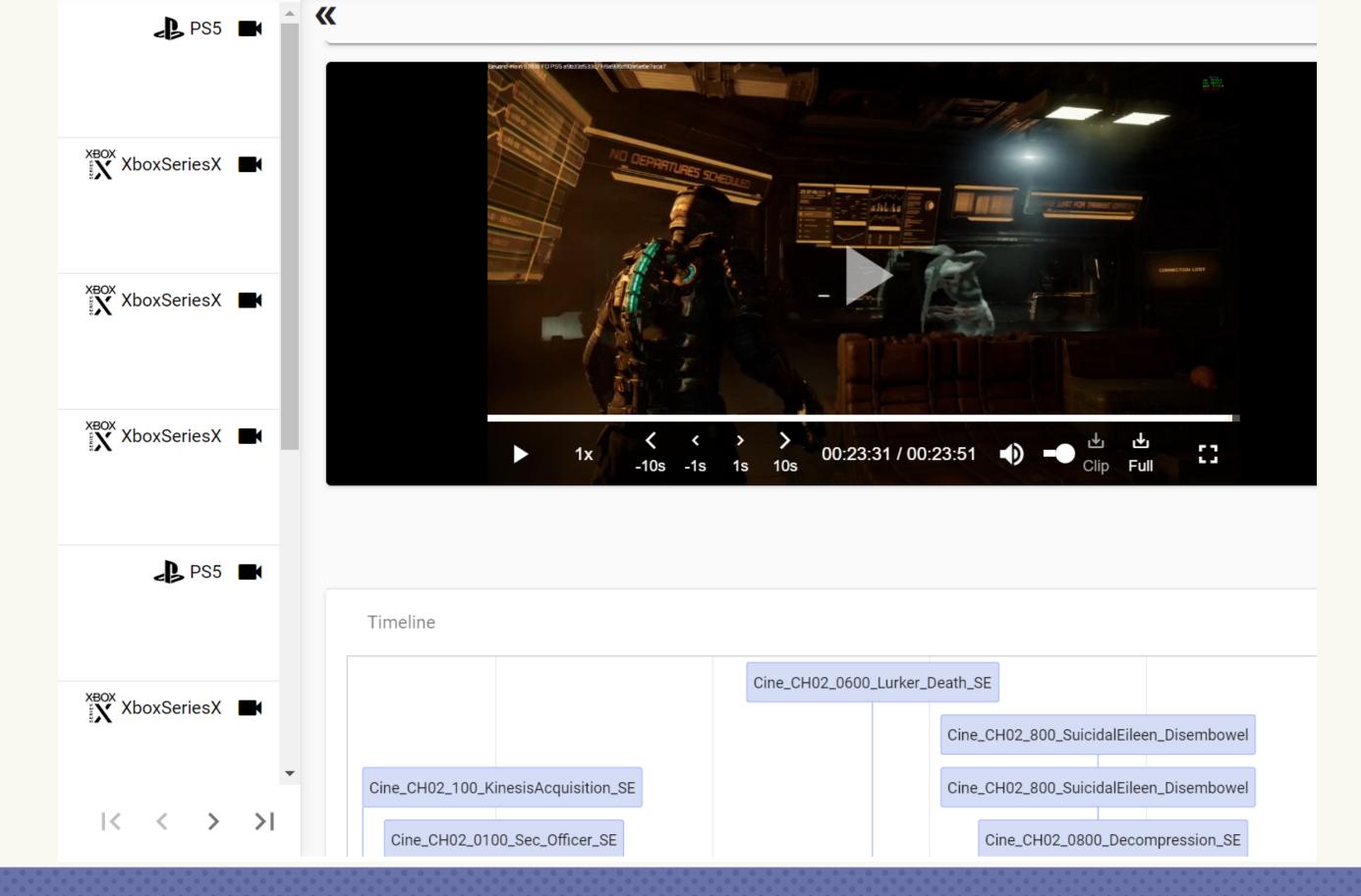
CurrentWaypointPosition:(-19.1,109.9,370.6)

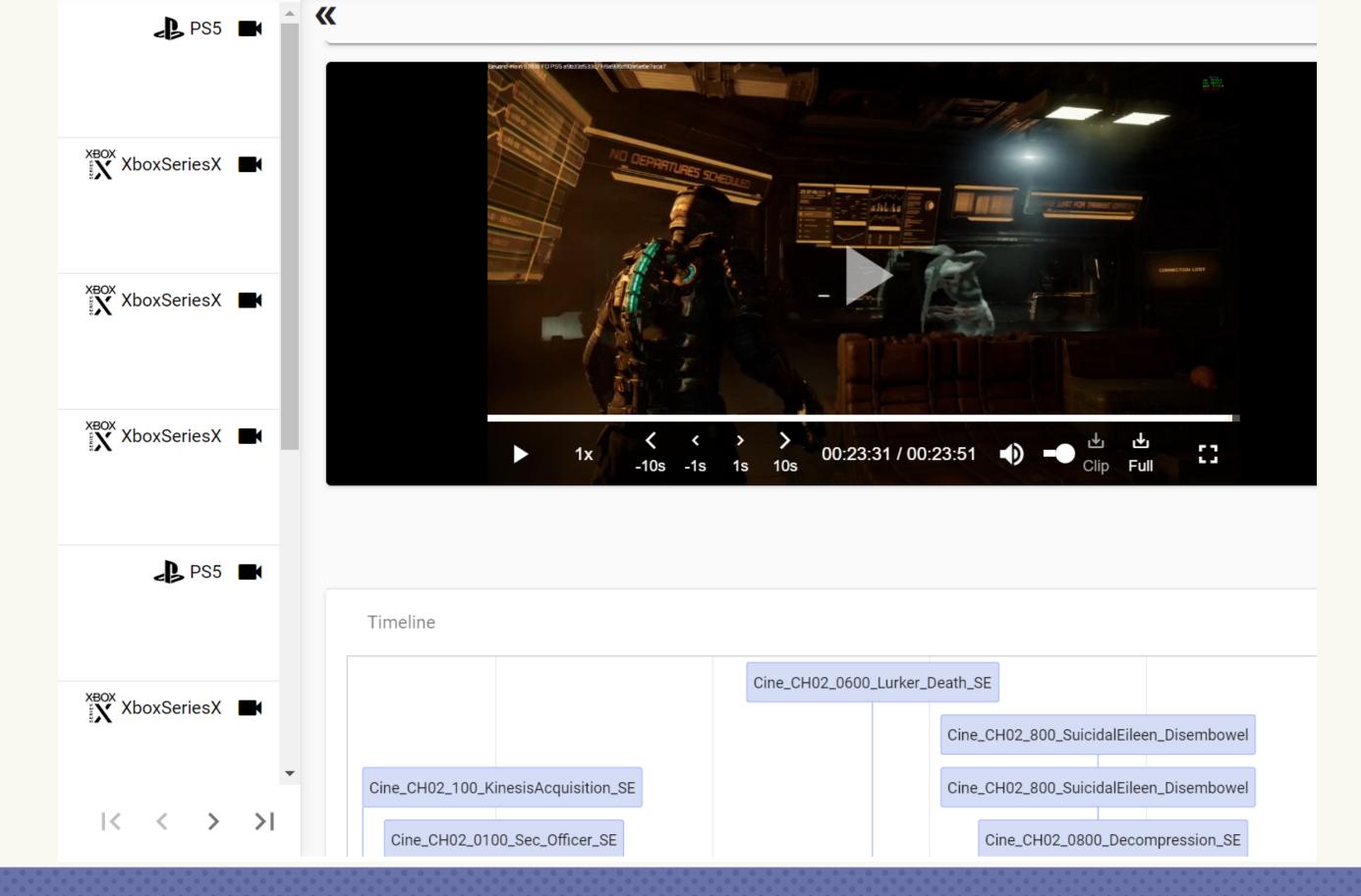
isInFantryStuckProcedureActive:(0)

Mimic3









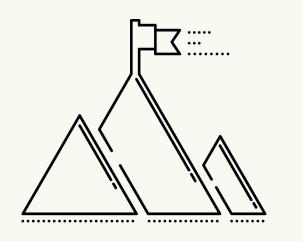






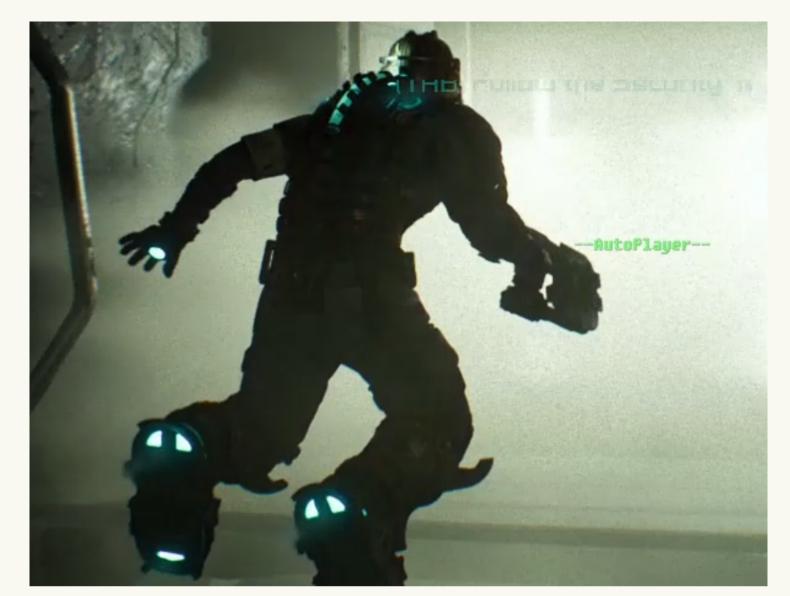


# Single Player Worth it?



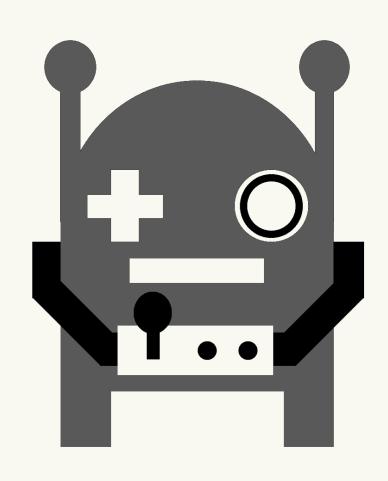


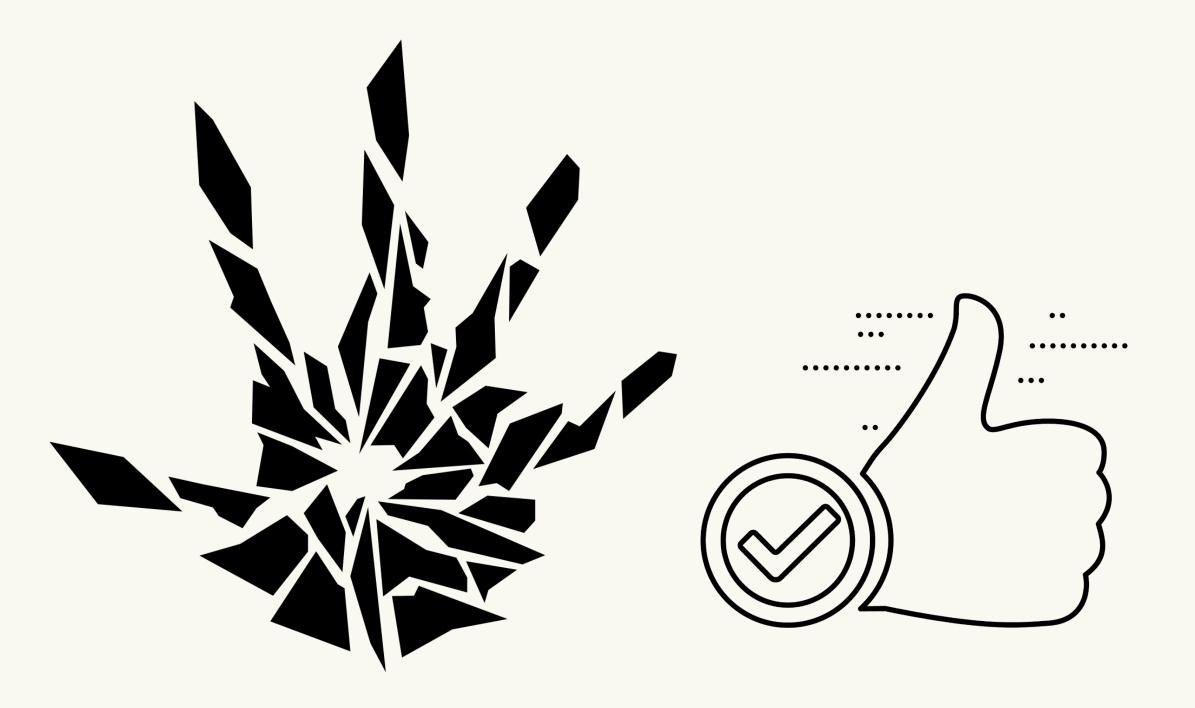








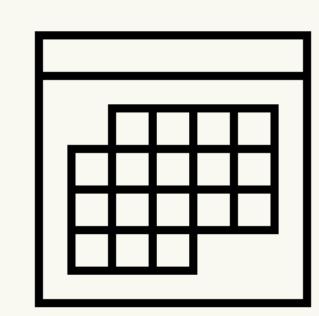




## FROSTBITE





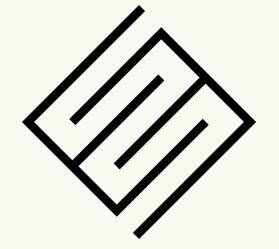


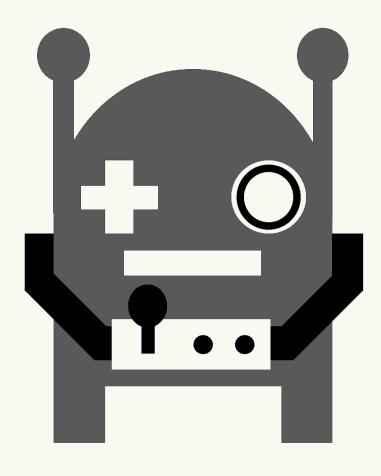










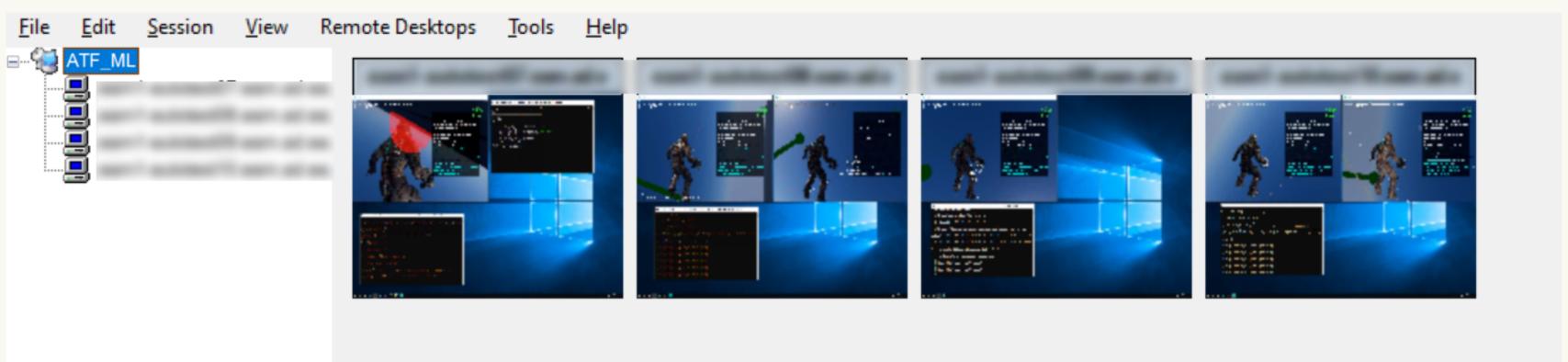


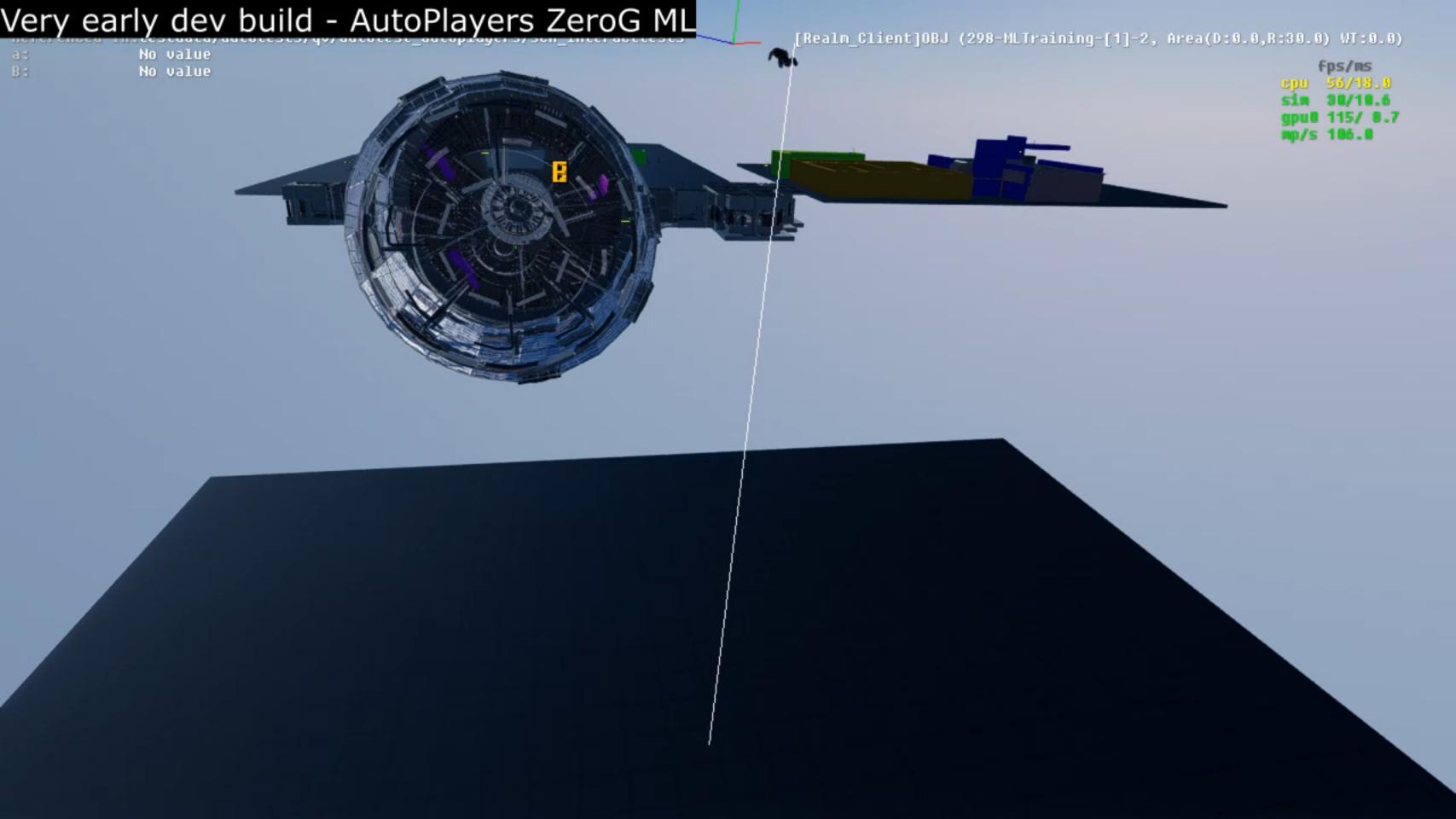


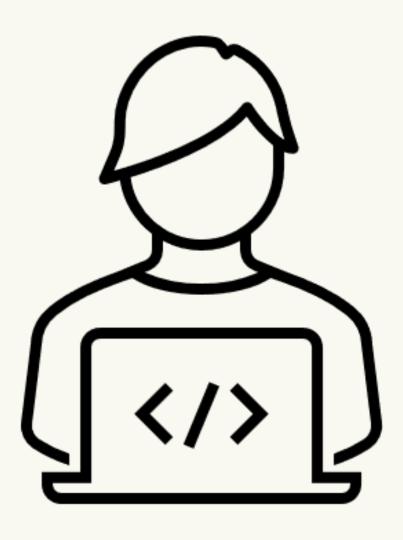


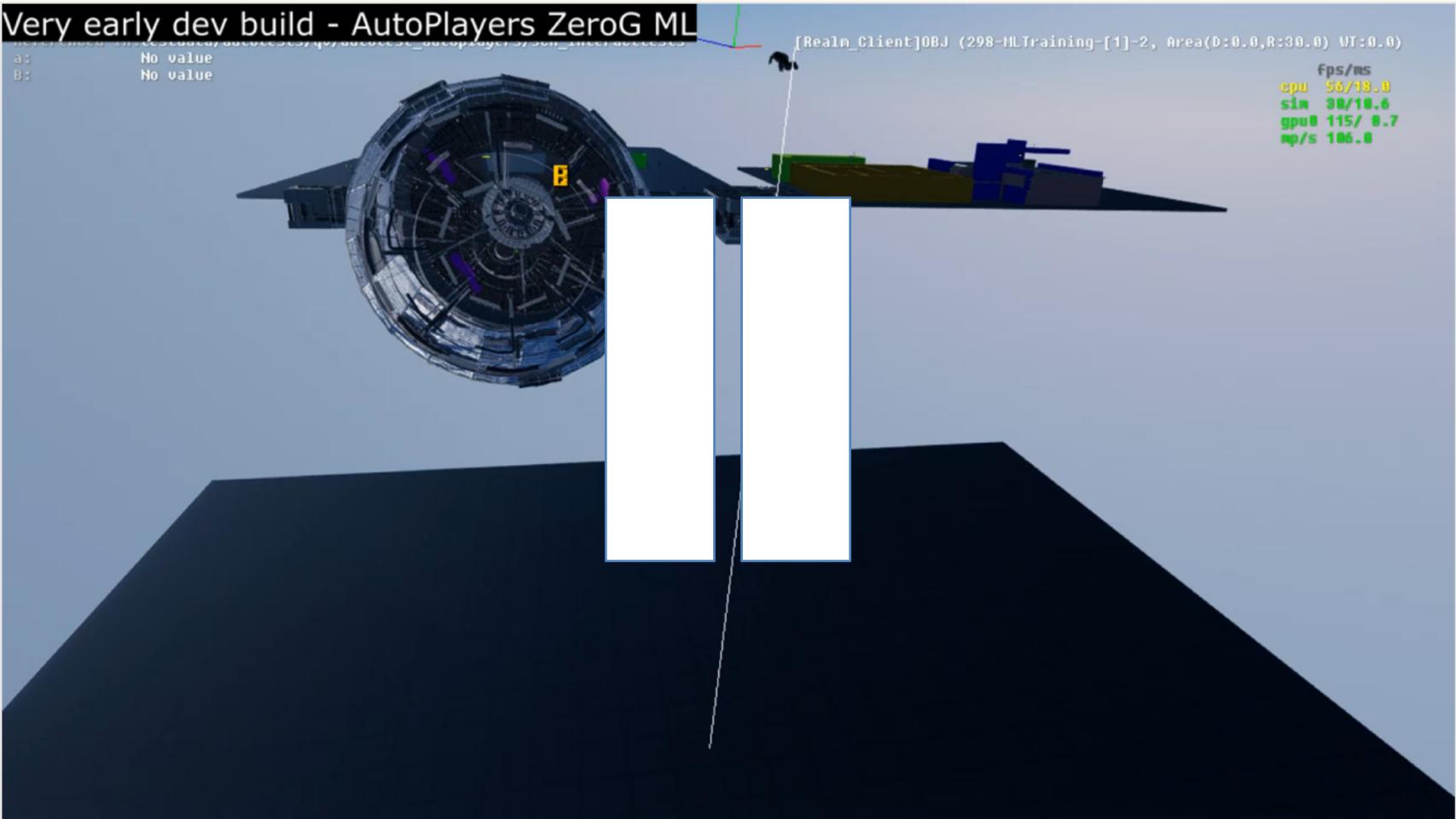
# Yes, but











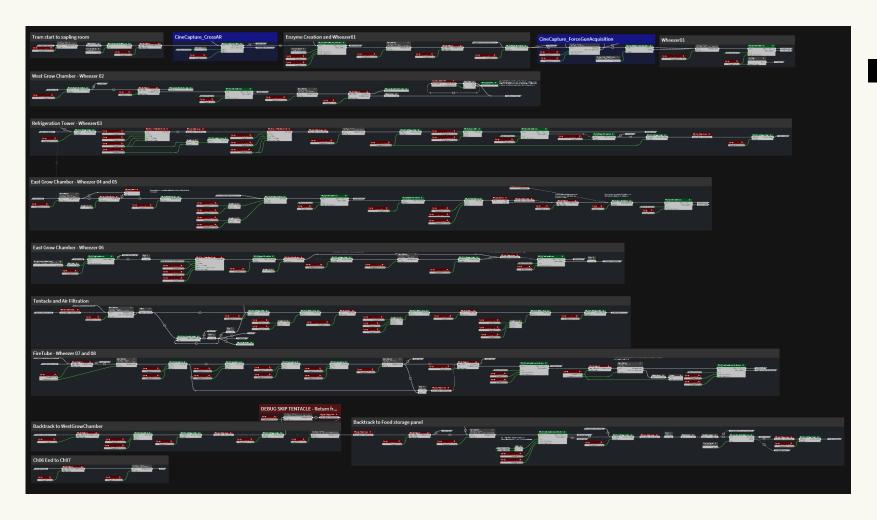
#### Results

Portable ML

ML Guidelines

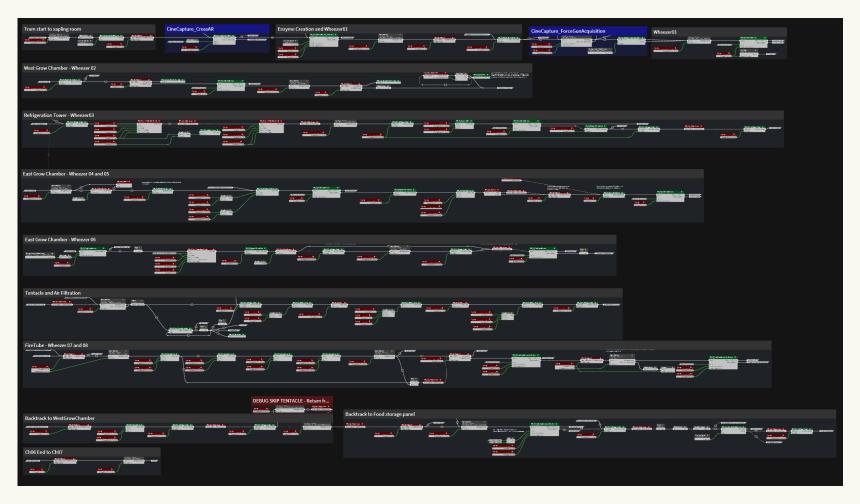
ML Training

## Playthrough Scripting



Unique Events

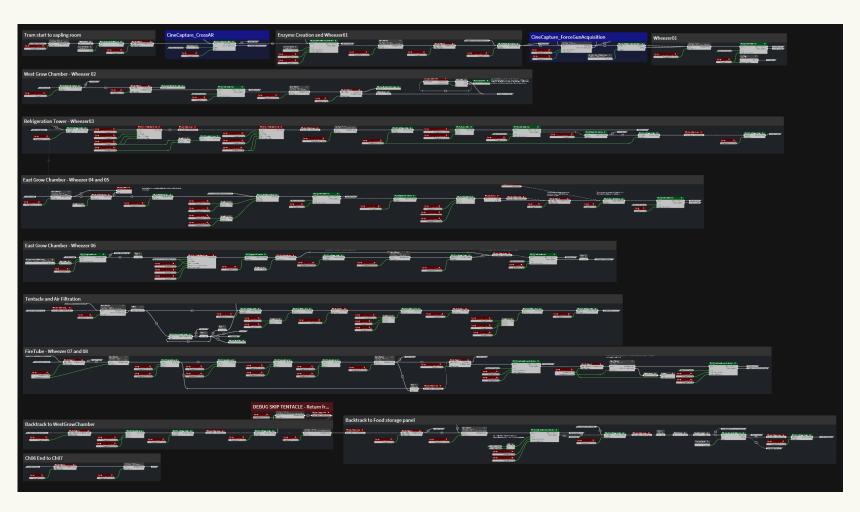
## Playthrough Scripting



Unique Events

Repeatability

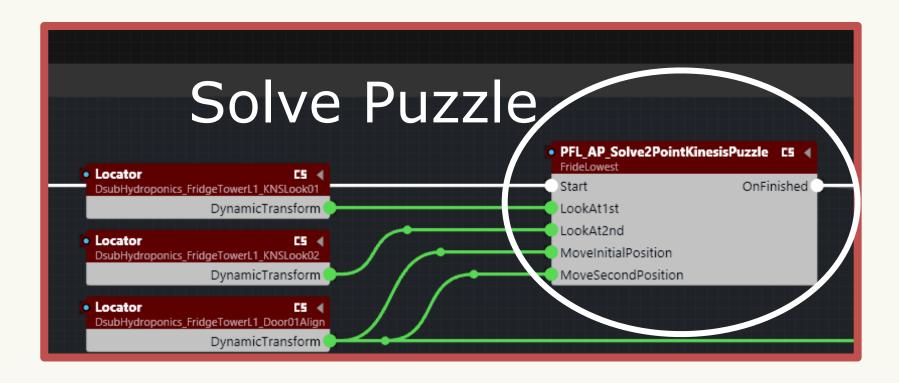
## Playthrough Scripting

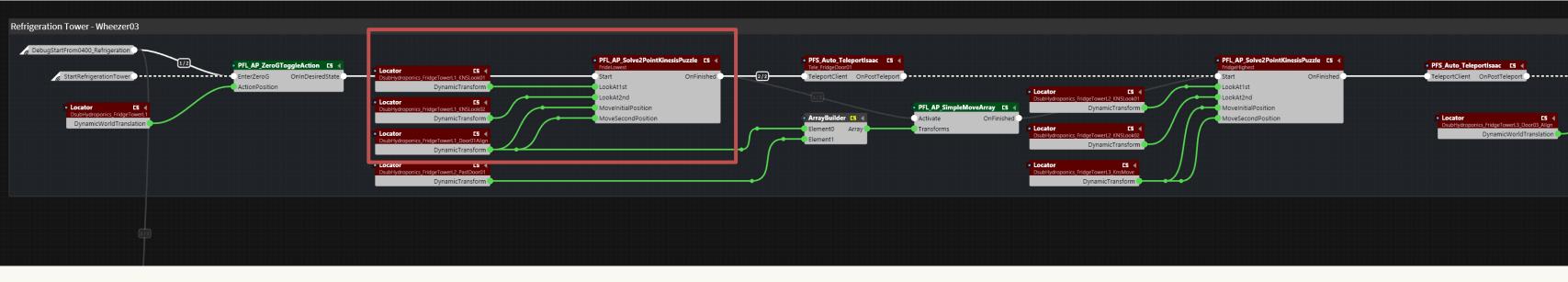


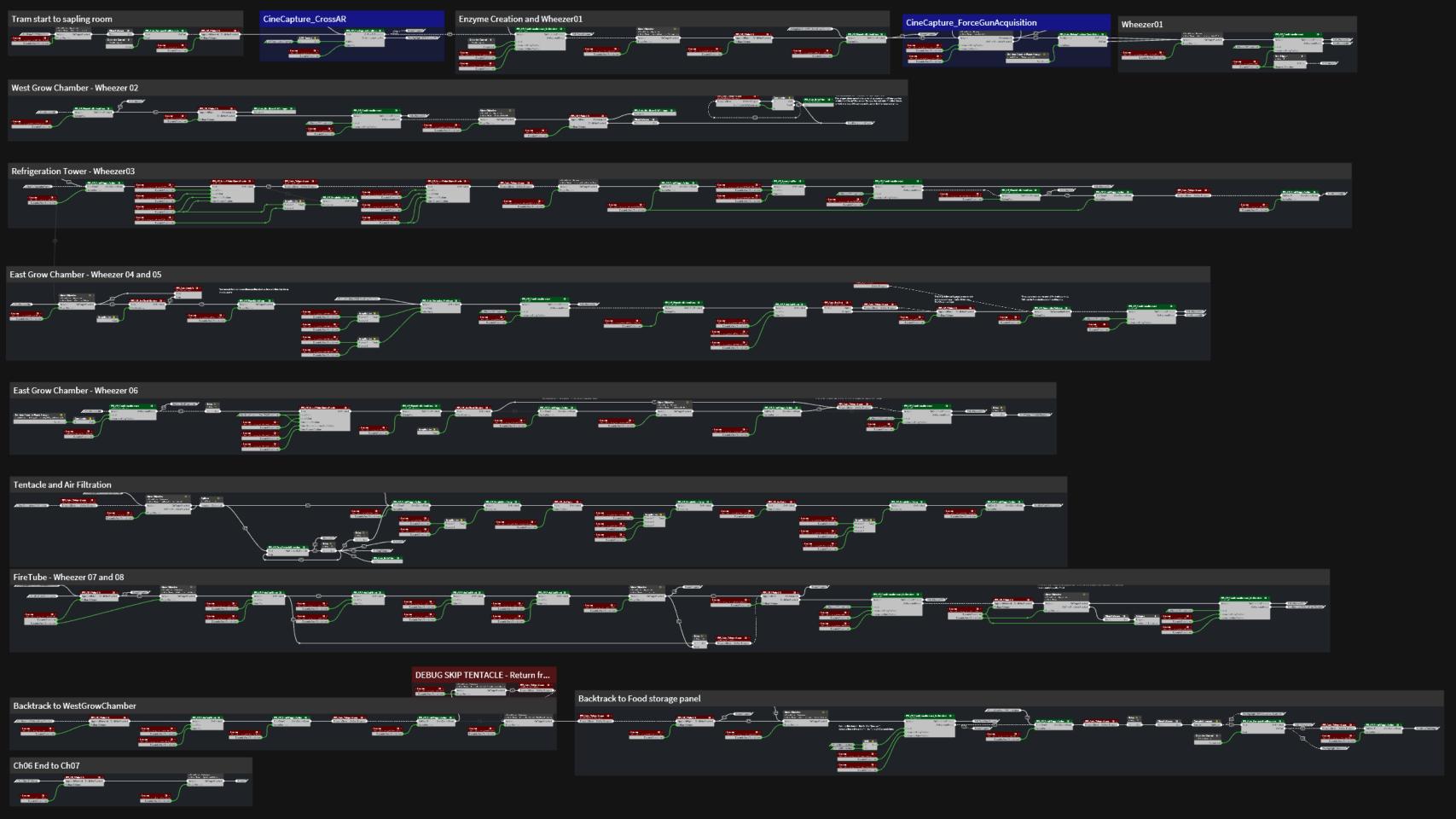
Unique Events

Repeatability

No Exploration







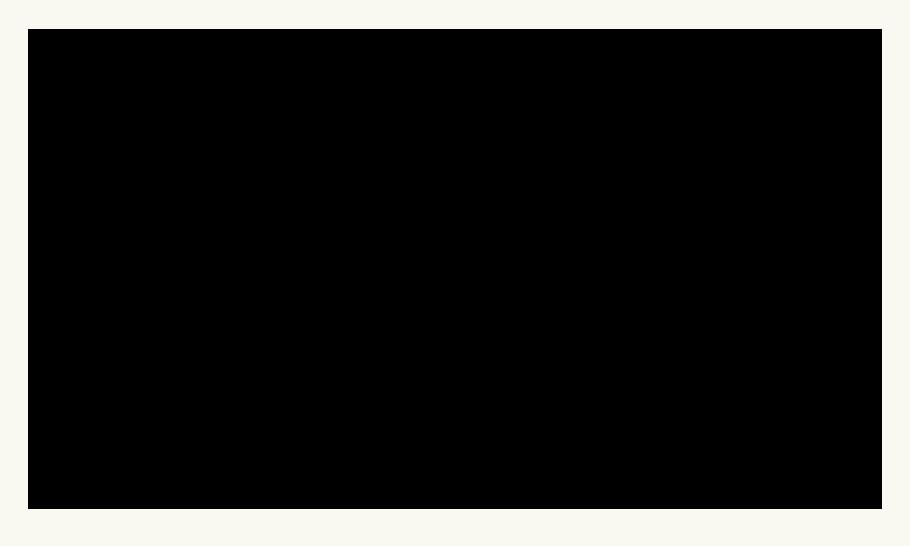
## Panel Scripting



UI

Stateful

## Script + Objective



Script Where

Al Carry

#### Combat



Defend Area

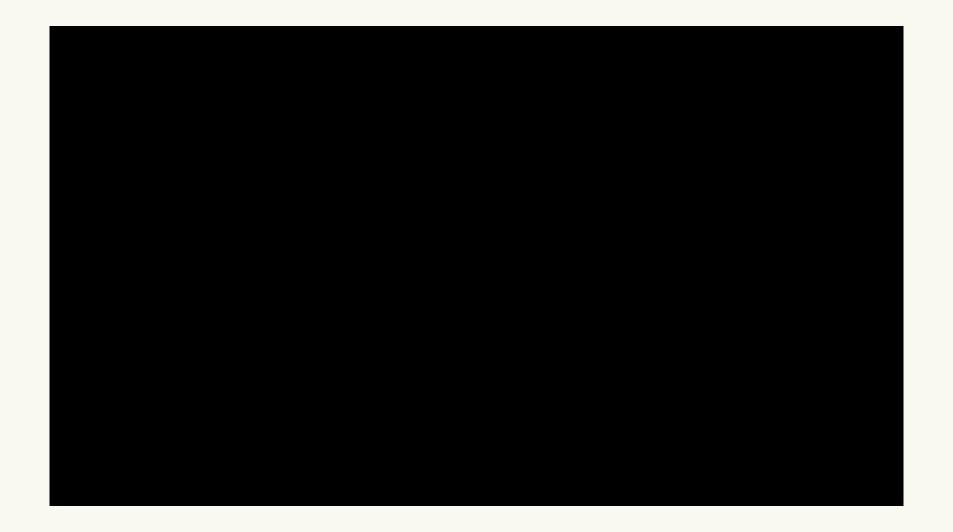
Godmode

#### Stuck

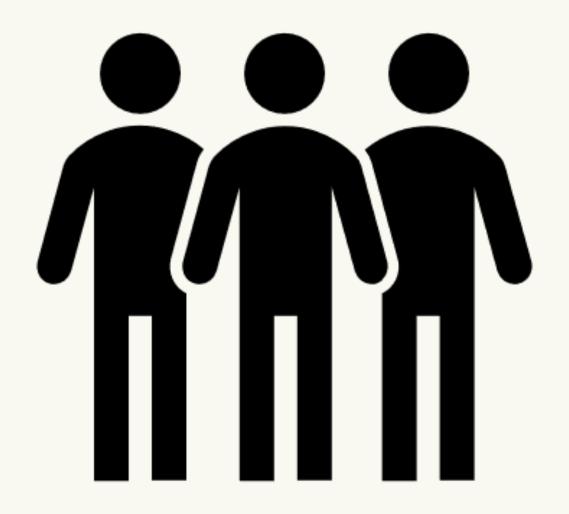


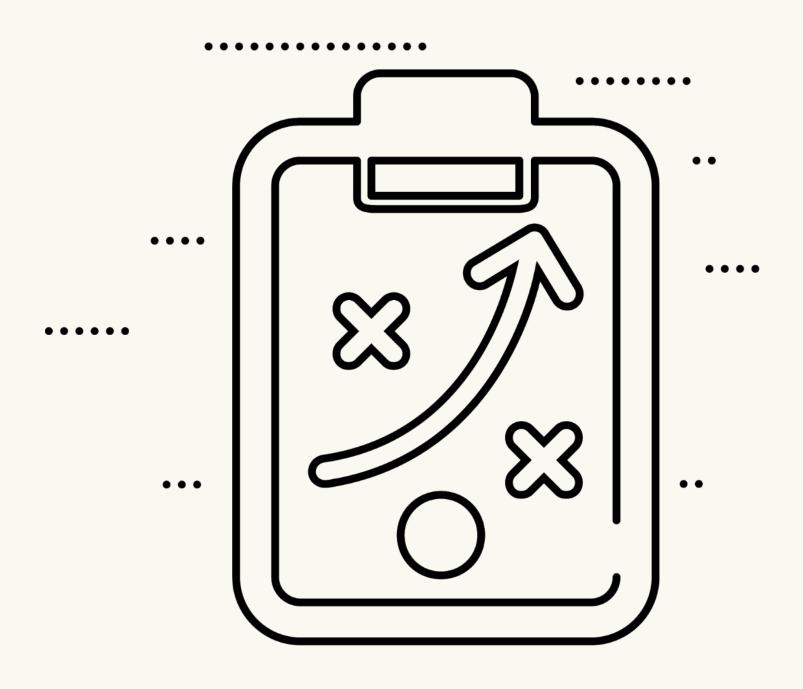
Input spam

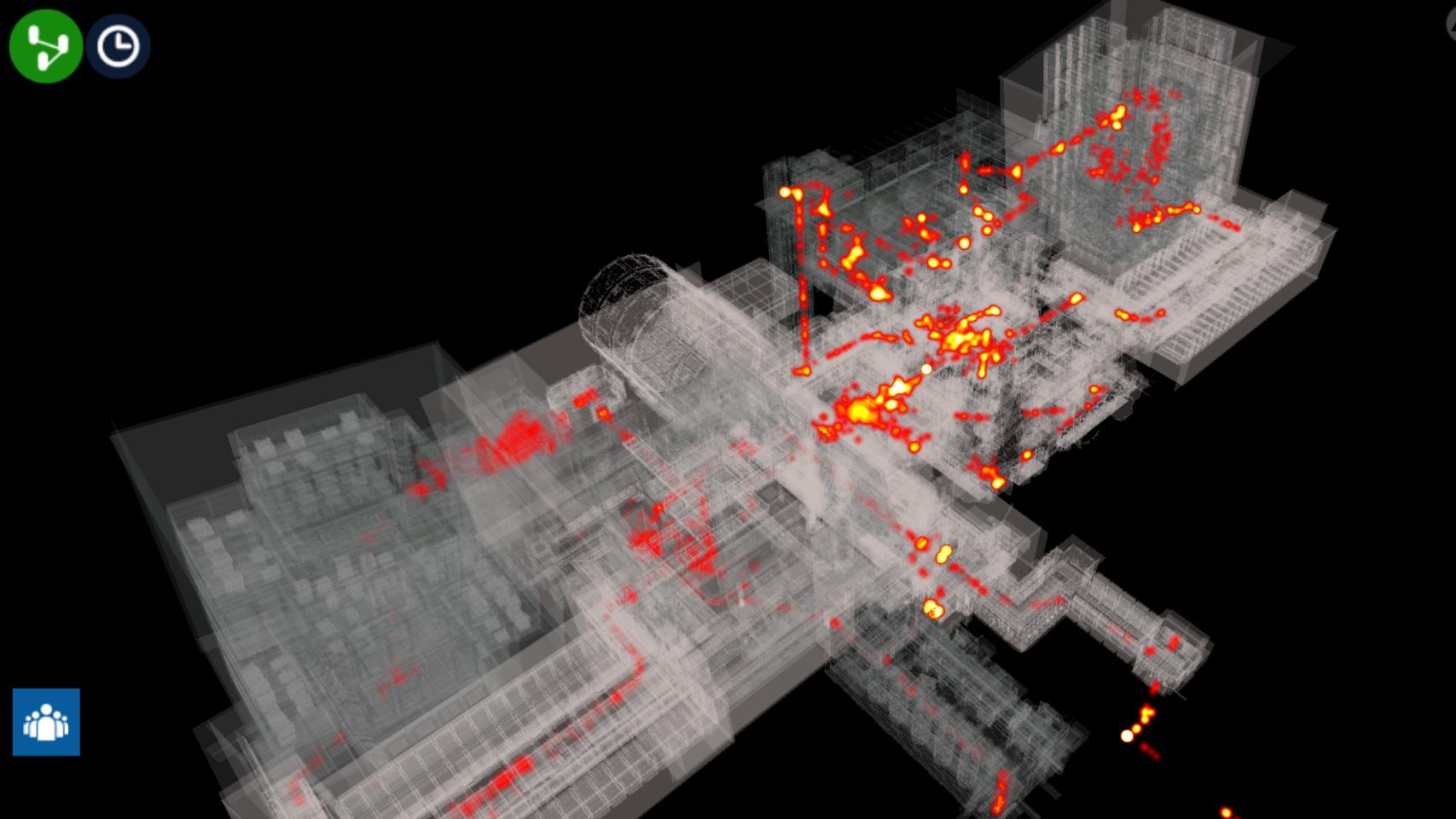
### Aimbot...











### Human

## AutoPlayer



#### Before





After



4x Work

#### Before





After



4x Work

Very early dev version - AutoPlayers integration spike

Trained RL model, loaded and running with FB ML

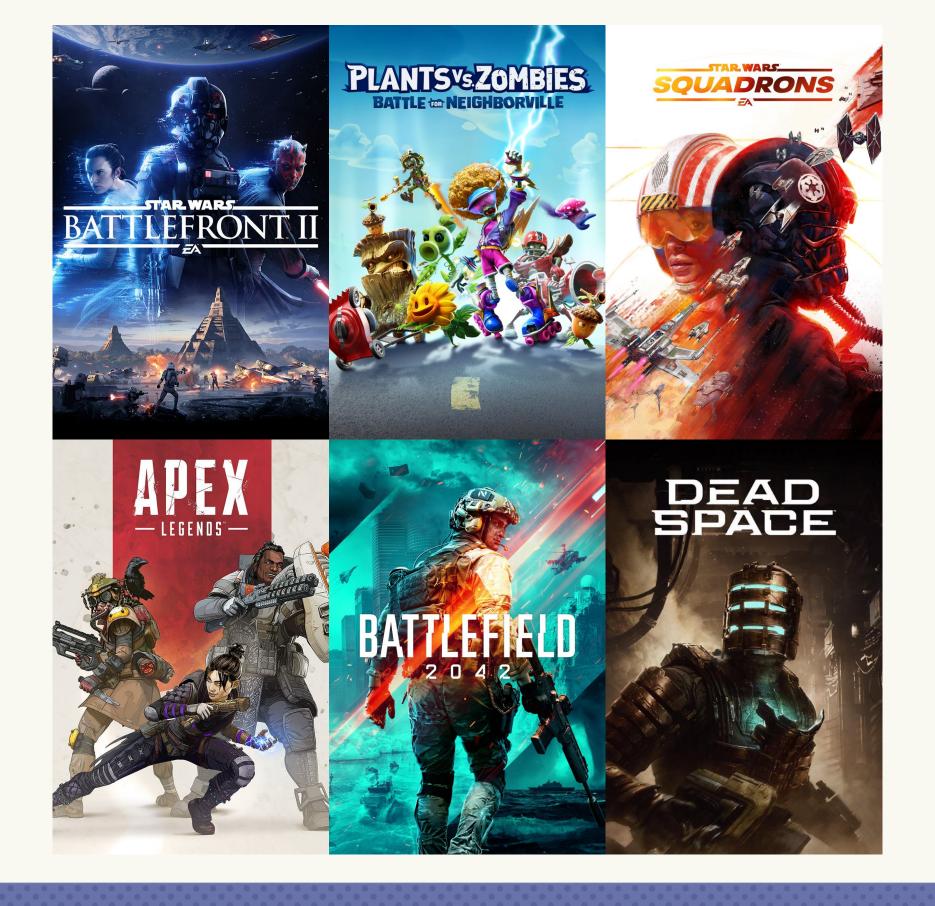
Traveltime ~14s

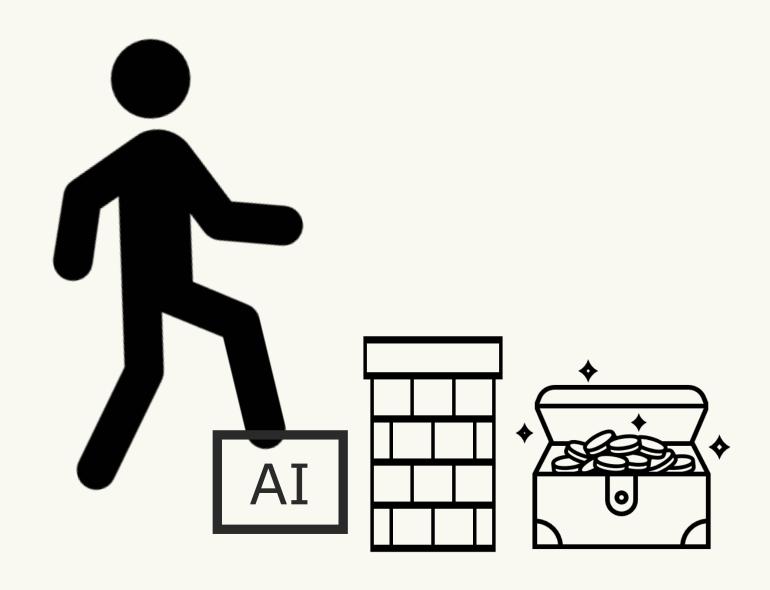
(very few iterations on training setup/rewards)

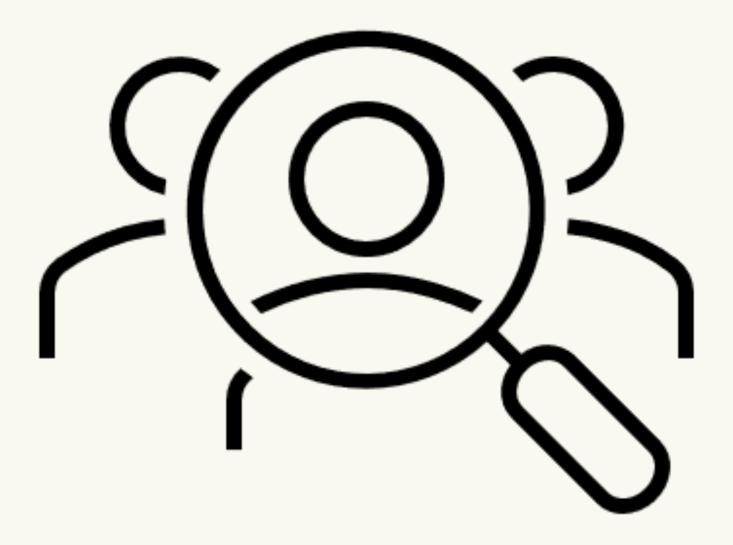


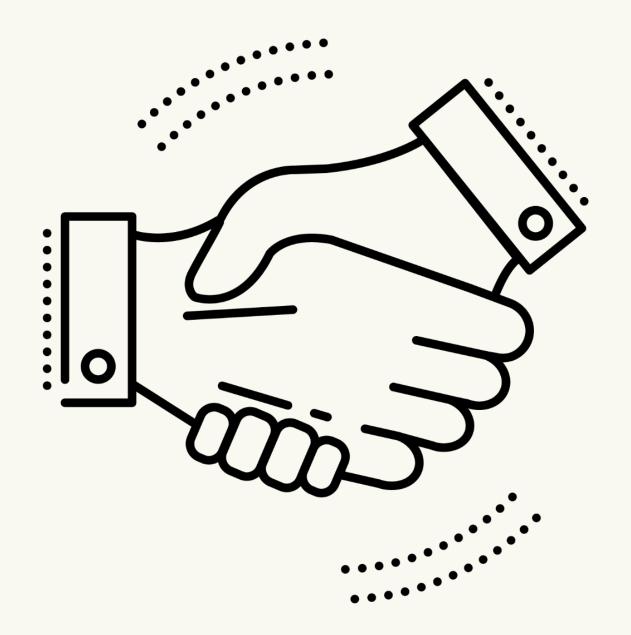




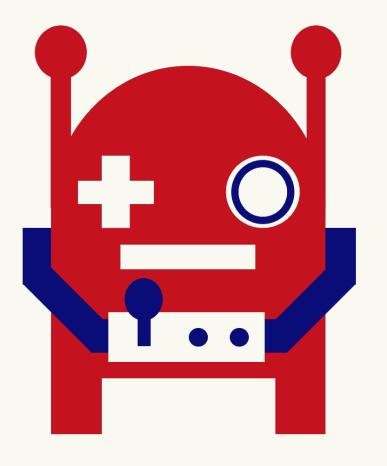








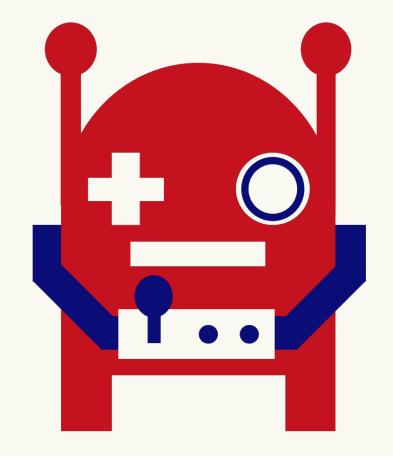




## jonas.gillberg@dice.se



#### 5/5 – "want to see more"



jonas.gillberg@dice.se